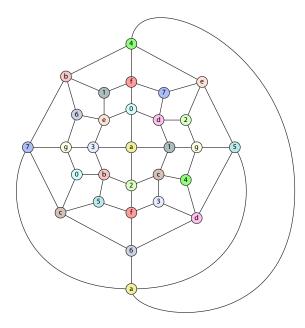
On the Planar Split Thickness of Graphs

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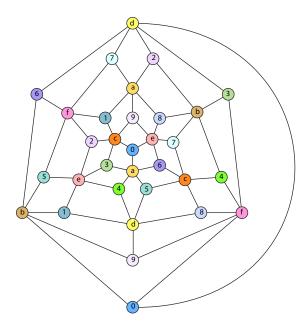
Definition by example, I



Draw a graph (here, $K_{7,8}$) with:

- ► Each vertex ⇒ O(1) points (here, 2 points/vertex)
- ► Each edge ⇒ curve between representatives of its endpoints
- No crossings

Definition by example, II

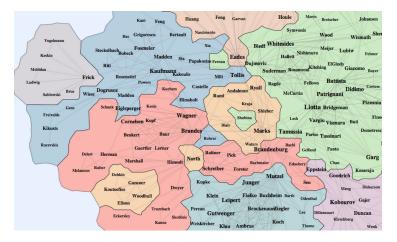


Split thickness: max points/vertex (here, 2)

G is k-splittable: it has a drawing with split thickness $\leq k$

E.g. this drawing shows that $K_{6,10}$ is 2-splittable

Motivation: Maps of clustered social networks



Network itself drawn conventionally (no split vertices) Clusters drawn as regions with $\leq k$ connected components To construct drawing, need to show cluster graph is k-splittable

Related research

Rephrased into our terminology:

Heawood 1890: K_{12} is 2-splittable

Ringel and Jackson 1984: Optimal k-splittability for K_n (n > 6) is $k = \lceil n/6 \rceil$

Hartsfield et al 1985 and later researchers:

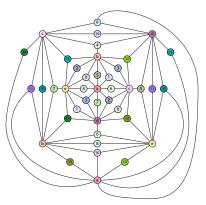
Split to planar minimizing total # splits rather than splits/vertex

Knauer and Ueckerdt 2012:

Split vertices to transform graph into several types of trees

Complete bipartite graphs

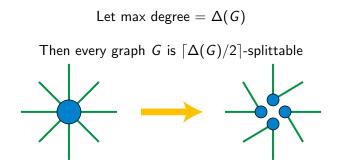
Theorem: $K_{a,b}$ is 2-splittable if and only if $ab \le 4(a+b)-4$



Proof:

 $ab \le 4(a+b) - 4 \Rightarrow G \subset K_{4,b}$, $K_{5,16}$ (above), $K_{6,10}$, or $K_{7,8}$ $ab > 4(a+b) - 4 \Rightarrow$ too many edges for bipartite planar drawing

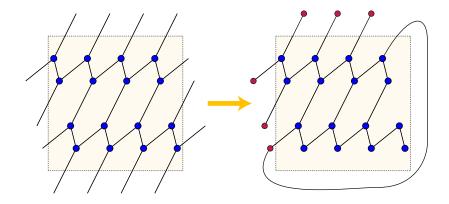
Splittability by maximum degree



Regular graphs with odd Δ , high girth are not $\lfloor \Delta/2 \rfloor$ -splittable: high-girth planar graphs have edges/vertices $\leq 1 + o(1)$ but any $\lfloor \Delta/2 \rfloor$ -split would have edges/vertices $= 1 + \frac{1}{\Delta - 1}$.

Splittability by genus

Theorem: Toroidal and projective-planar graphs are 2-splittable



Computational complexity

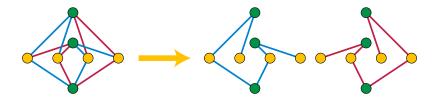
Theorem: 2-splittability is NP-complete

 C_{2} c_1 \overline{v}_{\prime} \overline{v}_{1} \overline{v}_{g} 11

Reduction from planar 3-SAT with a cycle through clause vertices (shown NPC by Kratochvíl, Lubiw, & Nešetřil 1991)

Approximation

Part of a family of graph parameters (arboricity, thickness, degeneracy, etc) all within constant factors of each other Arboricity a(G): minimum # trees whose union is the given graph Every graph is a(G)-splittable: draw the trees disjointly



Every *n*-vertex *k*-splittable graph has $\leq (3k + 1)(n - 1)$ edges \Rightarrow (Nash-Williams 1964) $a(G) \leq 3k + 1$

So arboricity is a $(3 + \frac{1}{k})$ -approximation to splittability (can improve to 3-approximation using pseudoarboricity)

Fixed-parameter tractability

Theorem: can test k-splittability of graphs of treewidth $\leq w$ in time $O(f(k, w) \cdot n)$

Main ideas:



Use monadic second-order logic (MSO) to represent graph properties as quantified formulae over vertex and edge sets

 $\forall S \subset E(G) : \exists T \subset G(V) : \ldots$

- A standard DFS-tree trick distinguishes endpoints of each edge
- Use edge-set variables to partition the edges according to the vertex-copies that each endpoint connects to
- Simulate any MSO formula on the split graph by a more complex formula on the original graph
- Planarity = absence of K_5 and $K_{3,3}$ minors
- Use Courcelle's theorem to construct an automaton that tests whether tree-decompositions obey the formula

Conclusions

Defined a new concept of *k*-splittability, used it to draw nonplanar graphs in a planar way

Tight bounds for complete graphs, complete bipartite graphs, and graphs of bounded maximum degree

NP-complete but O(1)-approximable, FPT for bounded treewidth

Future work: splitting vertices to produce near-planar graphs (e.g. low genus or bounded local crossing number)