

User Interface Software Projects: Intro to Depth- Sensing Interfaces

Assoc. Professor Donald J. Patterson
INF 134 Winter 2013



Intro to Kinect and Depth-Sensing Interfaces



<http://www.nintendo.com/wii/what-is-wii/#/wii-for-the-whole-family>

<http://us.playstation.com/ps3/accessories/playstation-eye-camera-ps3.html>

Intro to Kinect and Depth-Sensing Interfaces

- What is Kinect?
 - Hardware package for sensors
 - Built for the Microsoft Xbox 360 game console



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Intro to Kinect and Depth-Sensing Interfaces

- What is Kinect?
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- Supports a new interaction mode
 - **Natural User Interface**
 - Gestures
 - Speech
 - No explicit controller



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 - **Natural User Interface**
 - Gestures
 - Speech
 - No explicit controller
- Competitors
 - Wii Remote
 - PlayStation Move
 - LEAP



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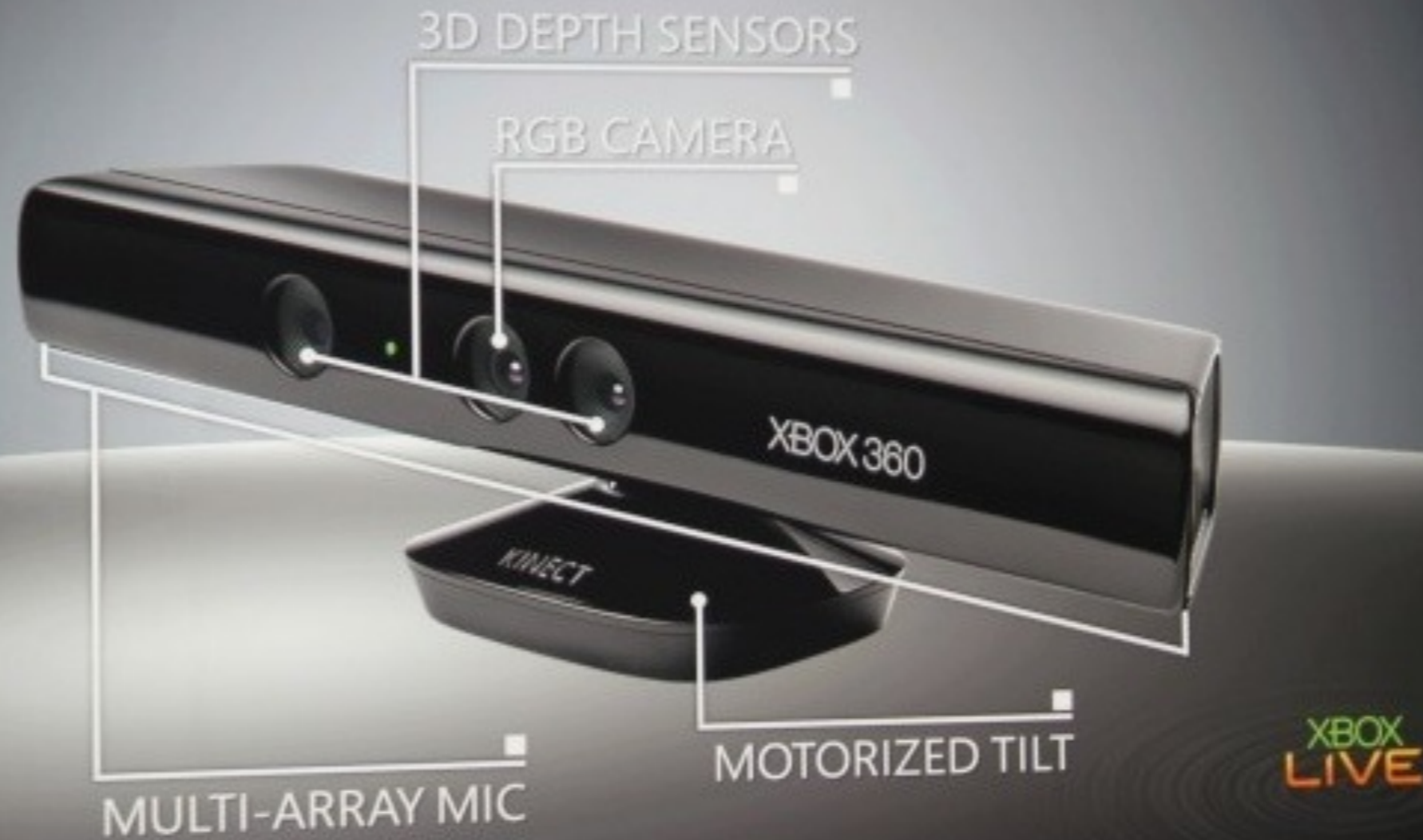
Intro to Kinect

<http://en.wikipedia.org/wiki/Kinect>

- A Horizontal bar
 - motorized base
 - RGB camera
 - depth sensor
 - multi-array microphone
- Supports
 - full-body 3D motion capture
 - skeletal tracking
 - facial recognition
 - voice recognition
 - acoustic source localization
 - ambient noise suppression

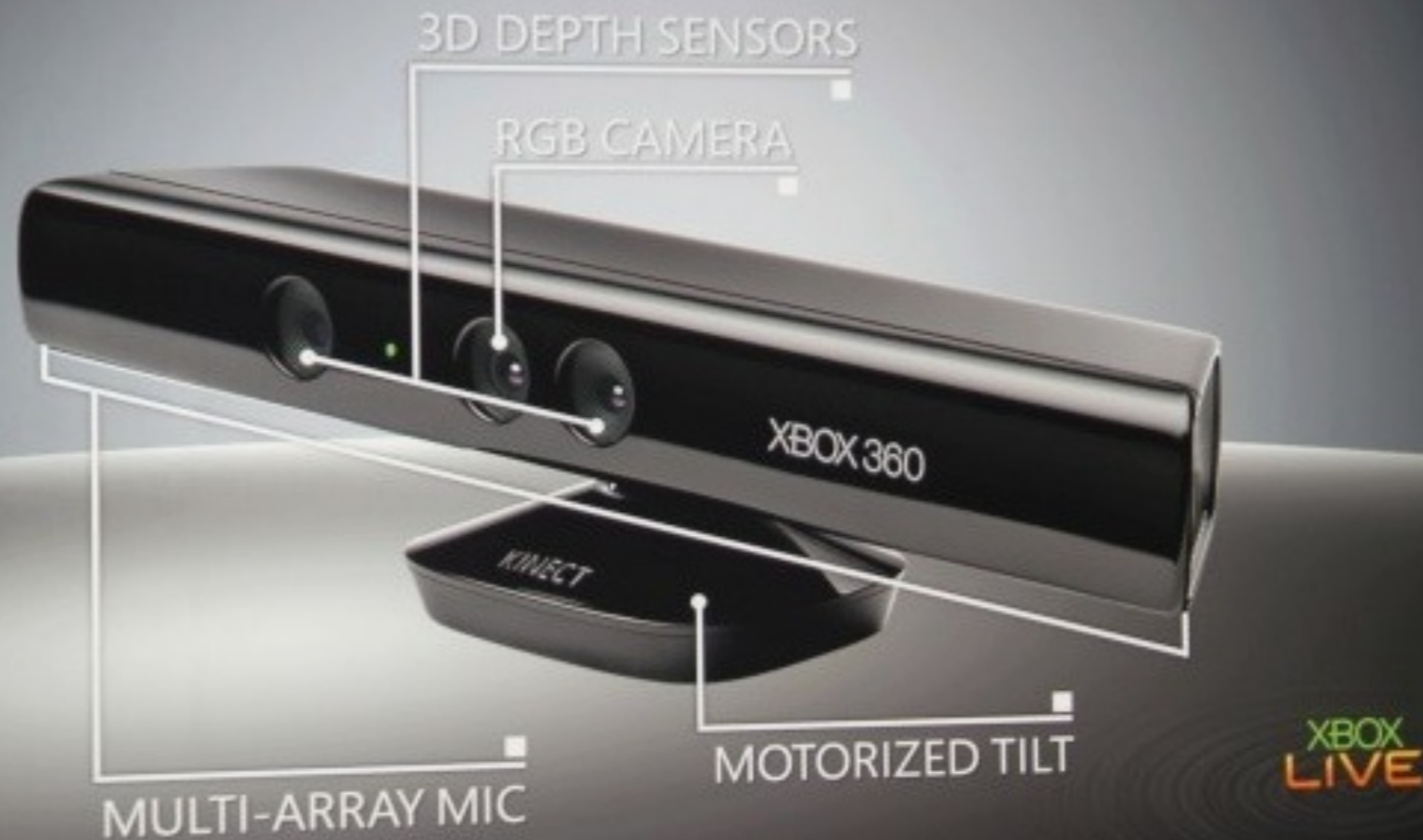
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Intro to Kinect



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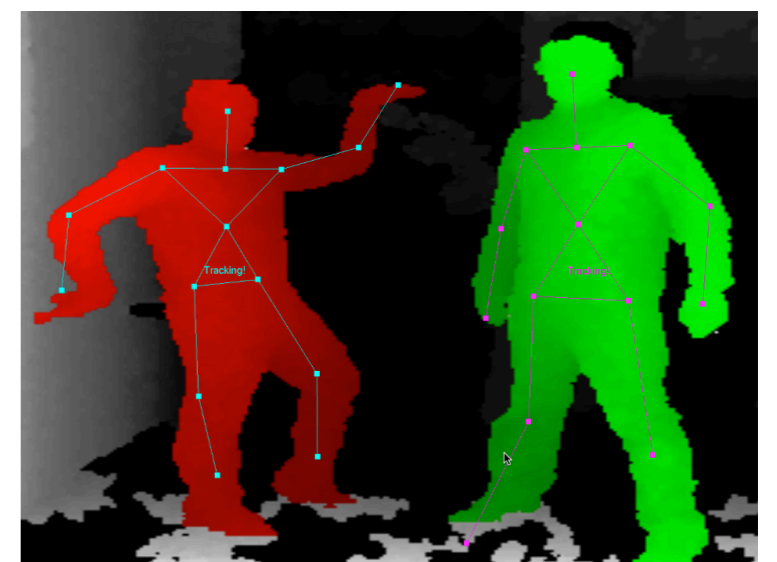
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- Code name was “Project Natal”
- Released in late 2010
- Based on software developed by Microsoft Game Studios
- Based on company “PrimeSense”
 - developed hardware to decode gestures
 - using infrared projector
 - infrared camera
 - algorithms implemented on chip for speed

<http://en.wikipedia.org/wiki/Kinect>

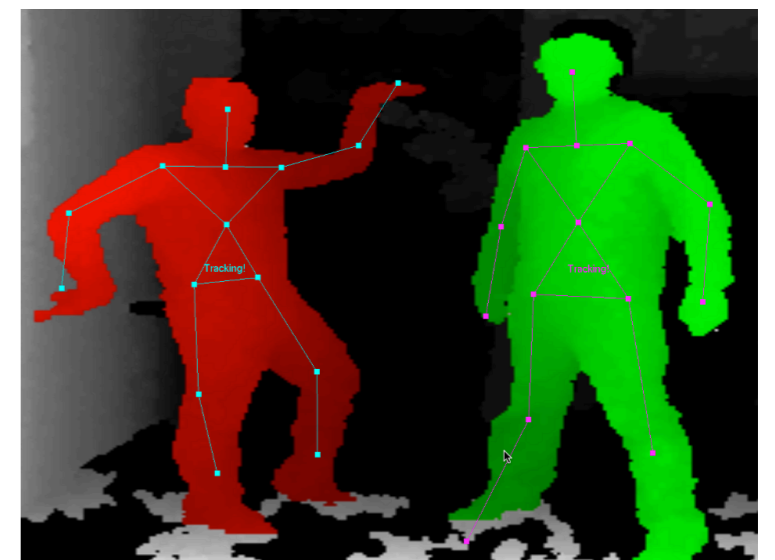
Intro to Kinect



<http://en.wikipedia.org/wiki/Kinect>

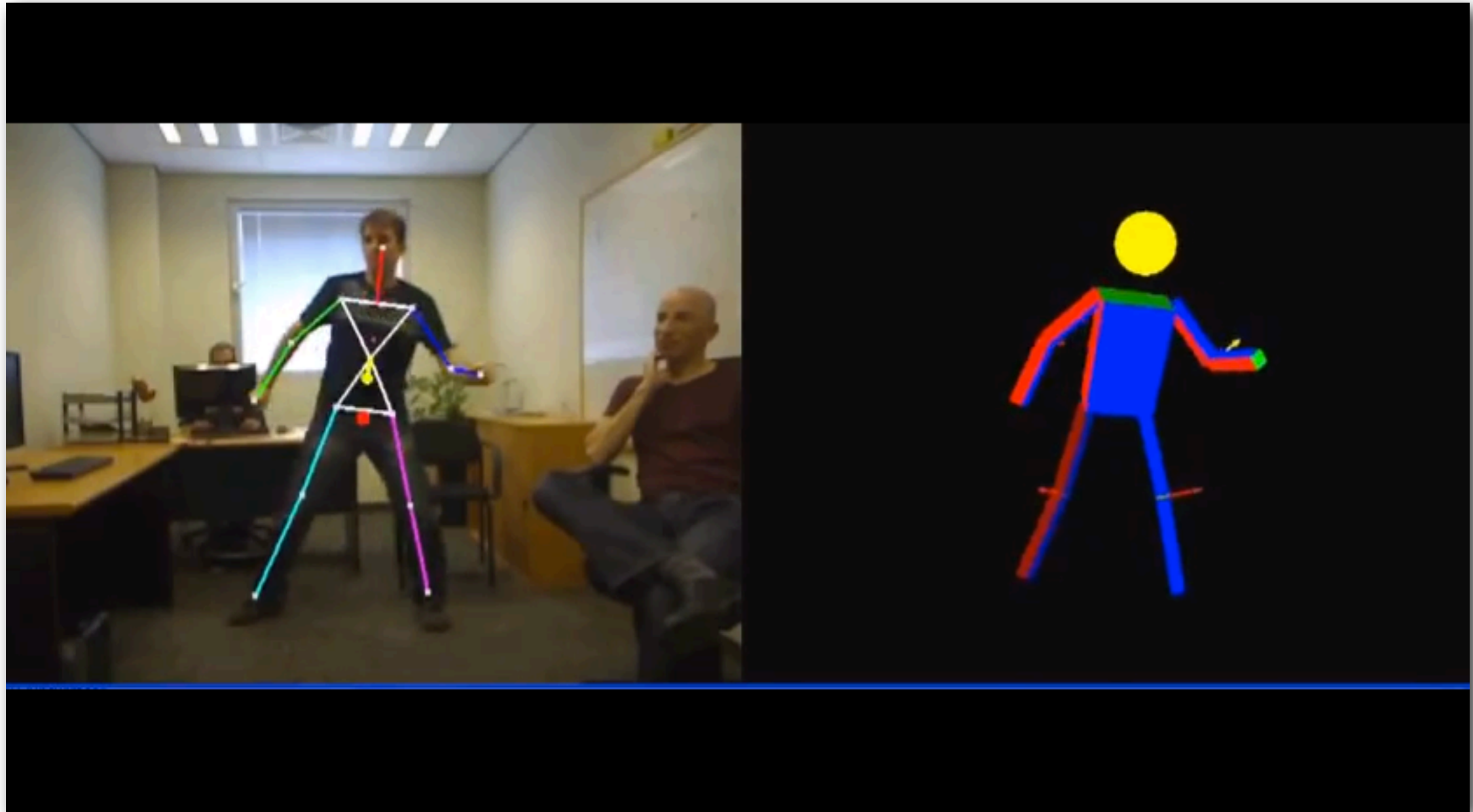
Intro to Kinect

- Specs of gesture recognition
 - Can track 6 people total
 - 2 active players
 - Tracks in the range of 3 - 11 ft using XBox software
 - Uses ~10-15% of the CPU of Kinect
 - requires 190 MB of storage space for software
- API available
 - official: Kinect for Windows 1.5 (released in May 2012)
 - open: NITE by OpenNI



<http://en.wikipedia.org/wiki/Kinect>

Intro to Kinect



<http://youtu.be/nuVPiXetfdM>

<http://www.openni.org/files/nite/>

Intro to Kinect



<http://www.youtube.com/watch?v=diy7rkWkDtU>

Intro to Playstation Move

- Playstation Move
 - Game market
 - Wands
 - lit colored balls
 - tracked by camera
 - internal accelerometers



<http://www.youtube.com/watch?v=s9ybHddDMgM>

Intro to Wii

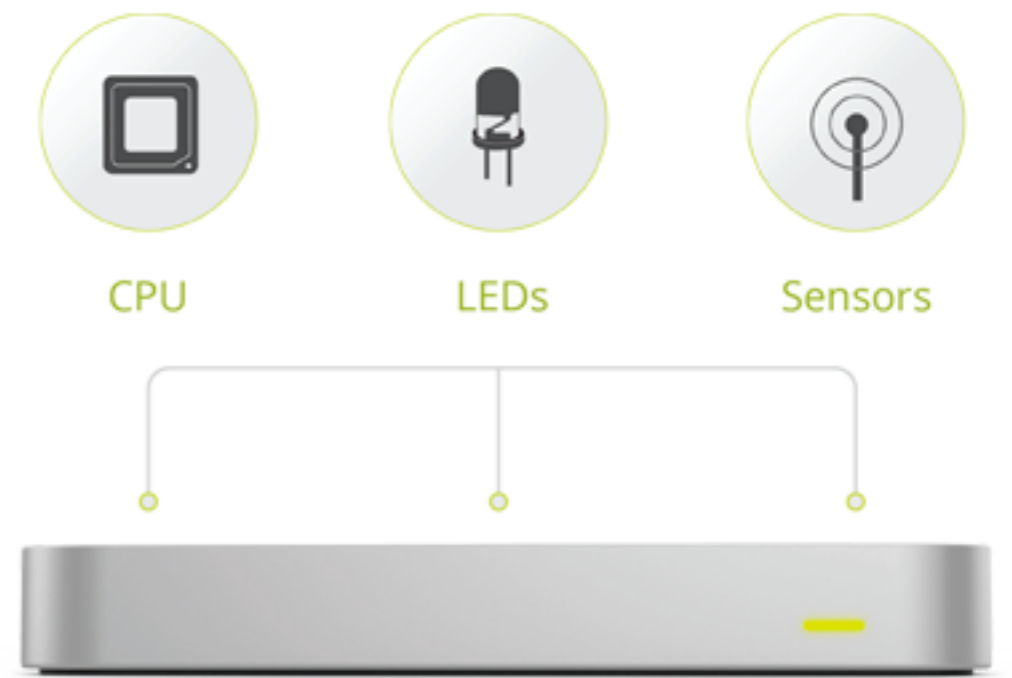


Intro to Wii

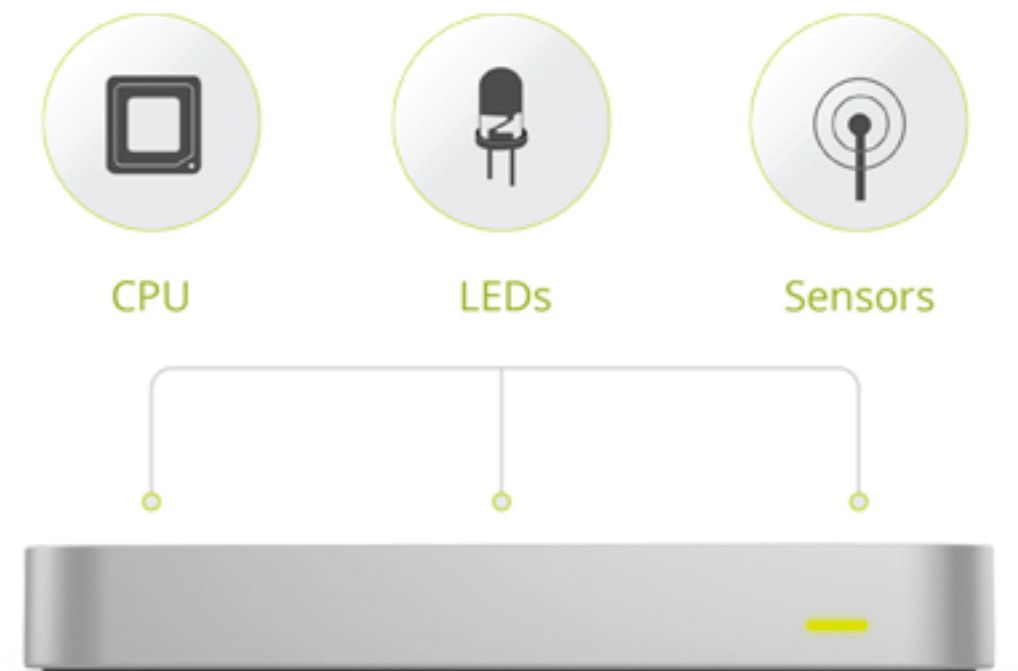
- Wii
 - Game market
 - Wands
 - infrared LEDS
 - tracked by sensor bar on console
 - internal accelerometers



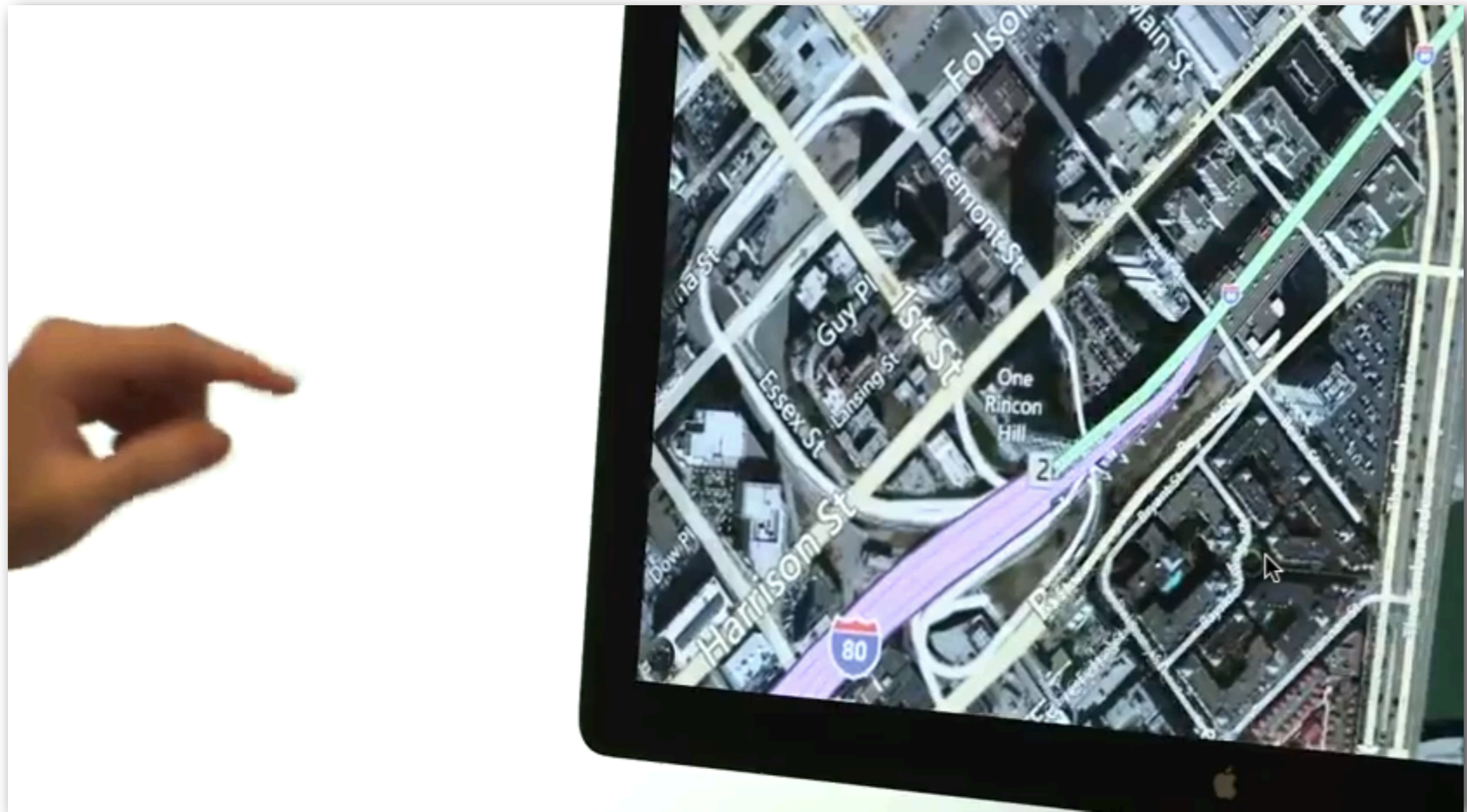
Intro to LEAP



- LEAP
 - High resolution
 - Small observation area
 - cheap \$69.99

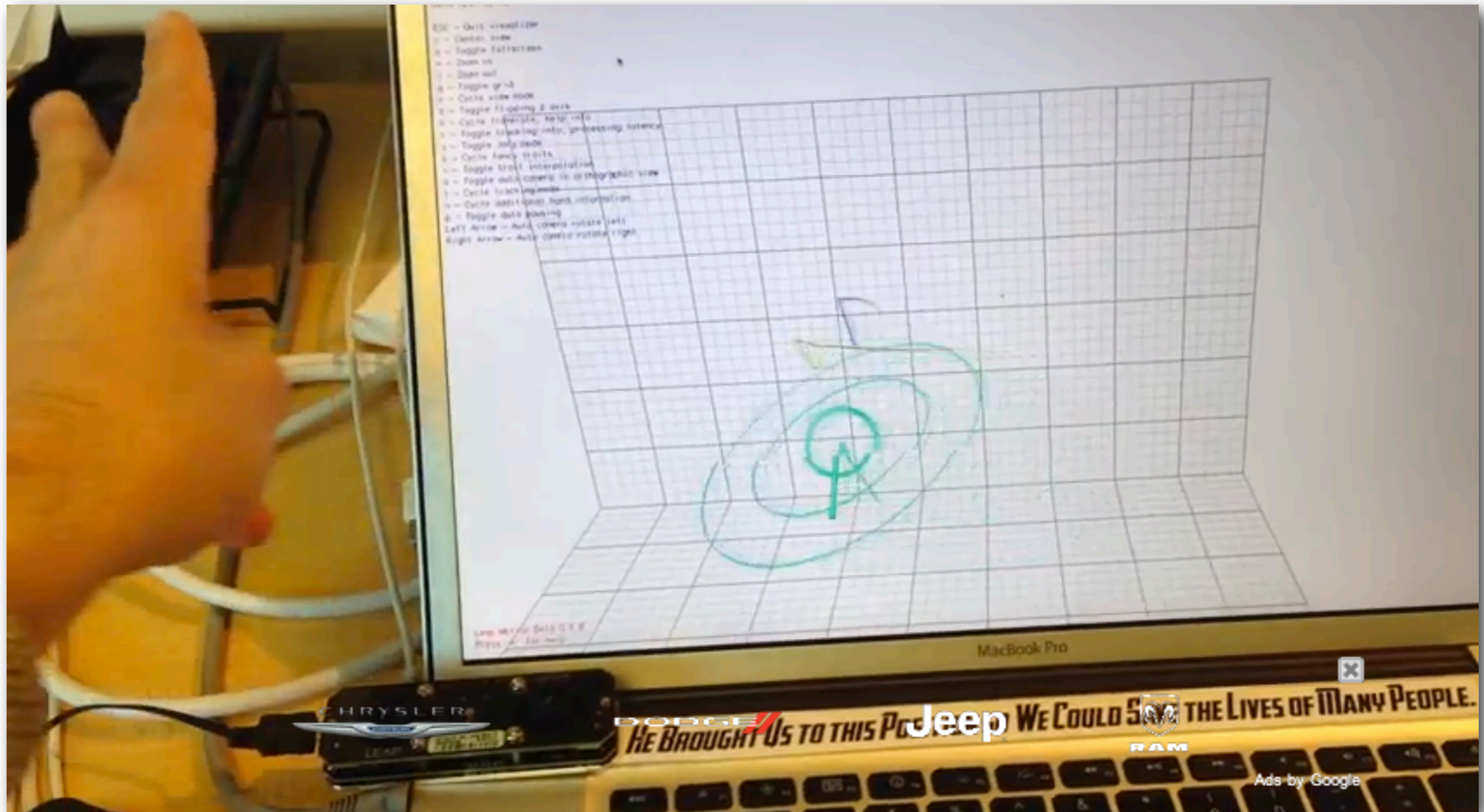


Intro to Kinect



<http://youtu.be/d6KuiutelA>

Intro to Kinect



<http://youtu.be/bZW03AMyGUw>

User Interface Software Projects: Intro to Kinect

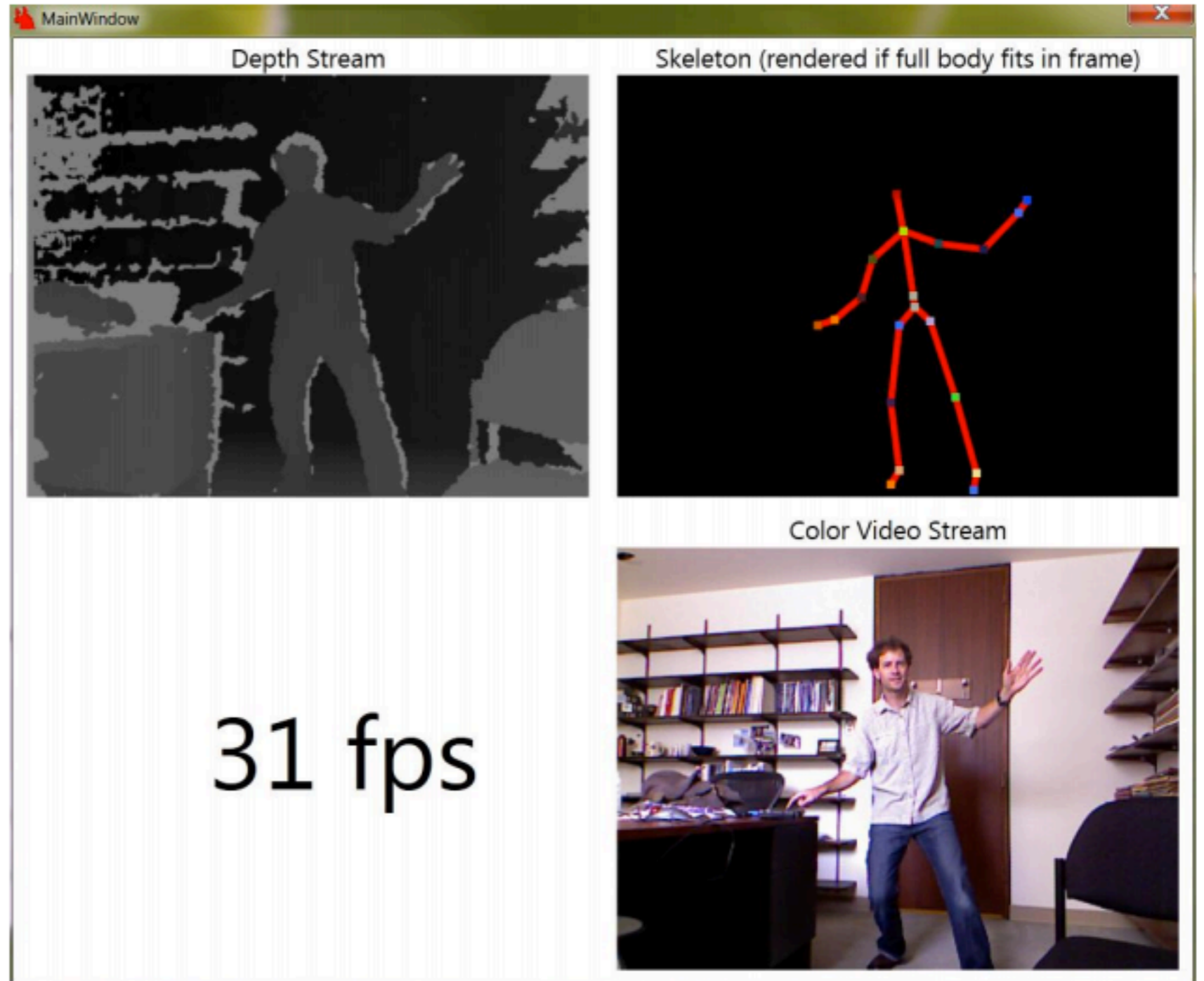
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Slides adapted from John MacCormick, Guido Gerig:

<http://users.dickinson.edu/~jmac/selected-talks/kinect.pdf>

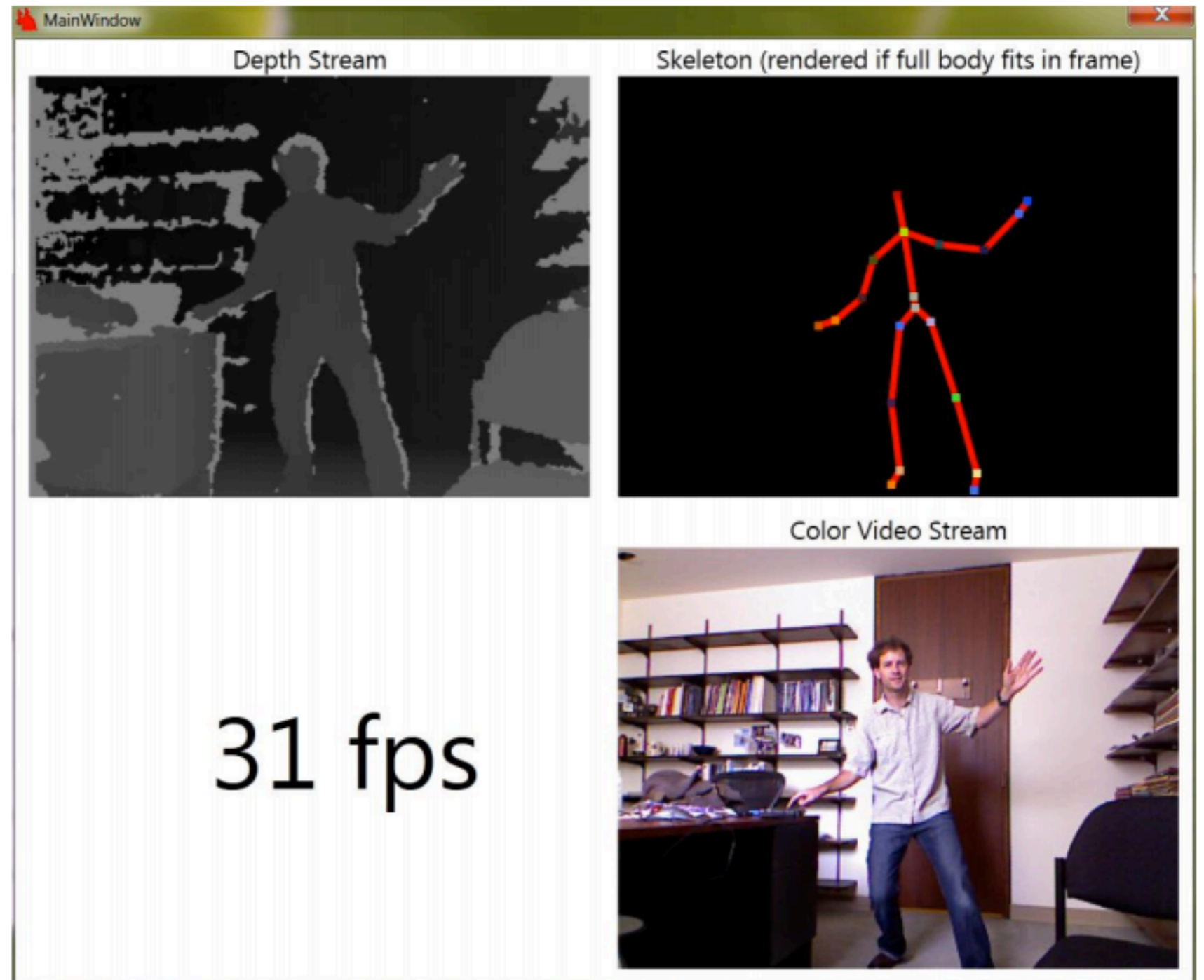
<http://www.sci.utah.edu/~gerig/CS6320-S2012/Materials/CS6320-CV-S2012-StructuredLight.pdf>

How does the Kinect Gesture Tracking Work



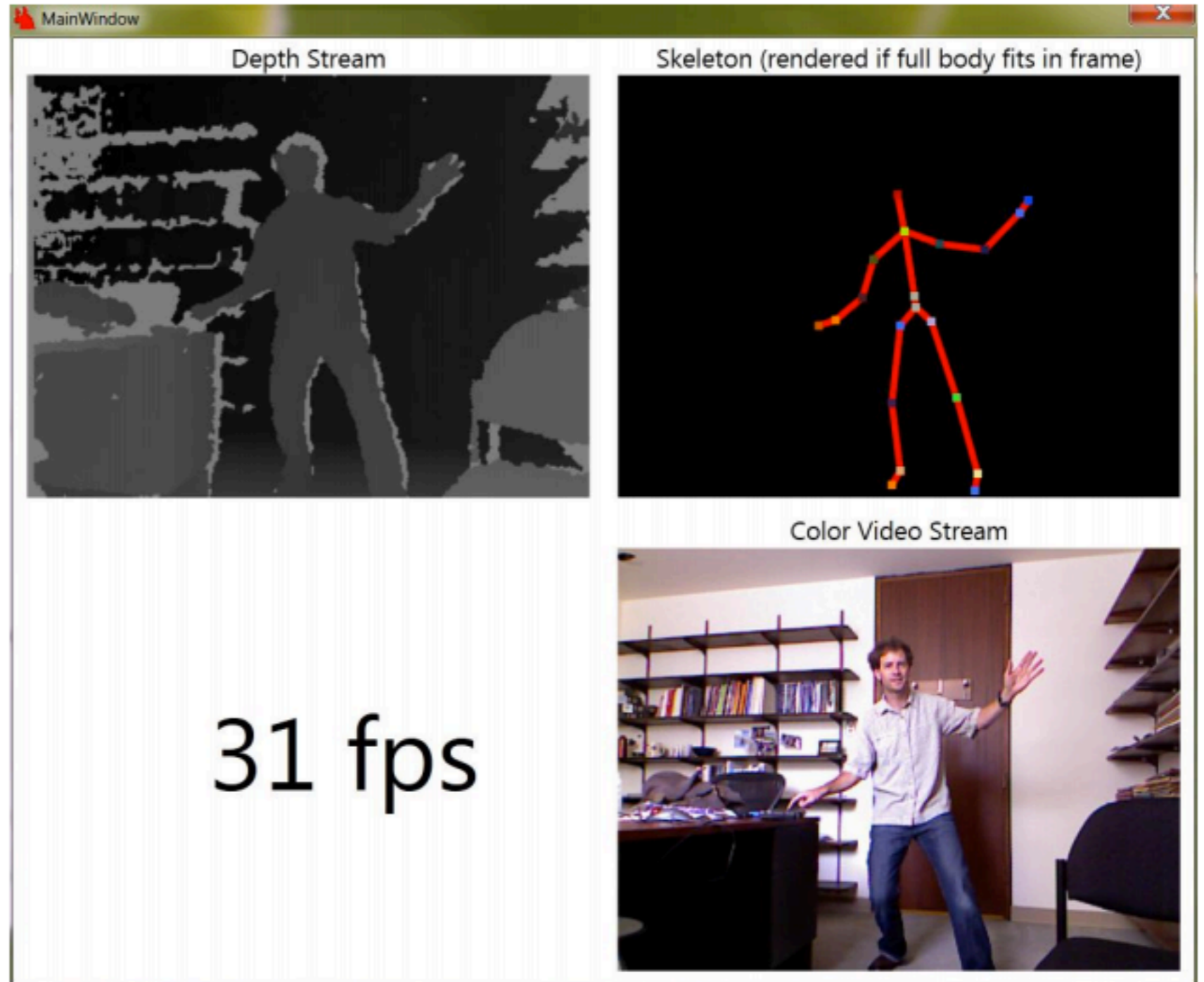
How does the Kinect Gesture Tracking Work

- Depth Video Stream



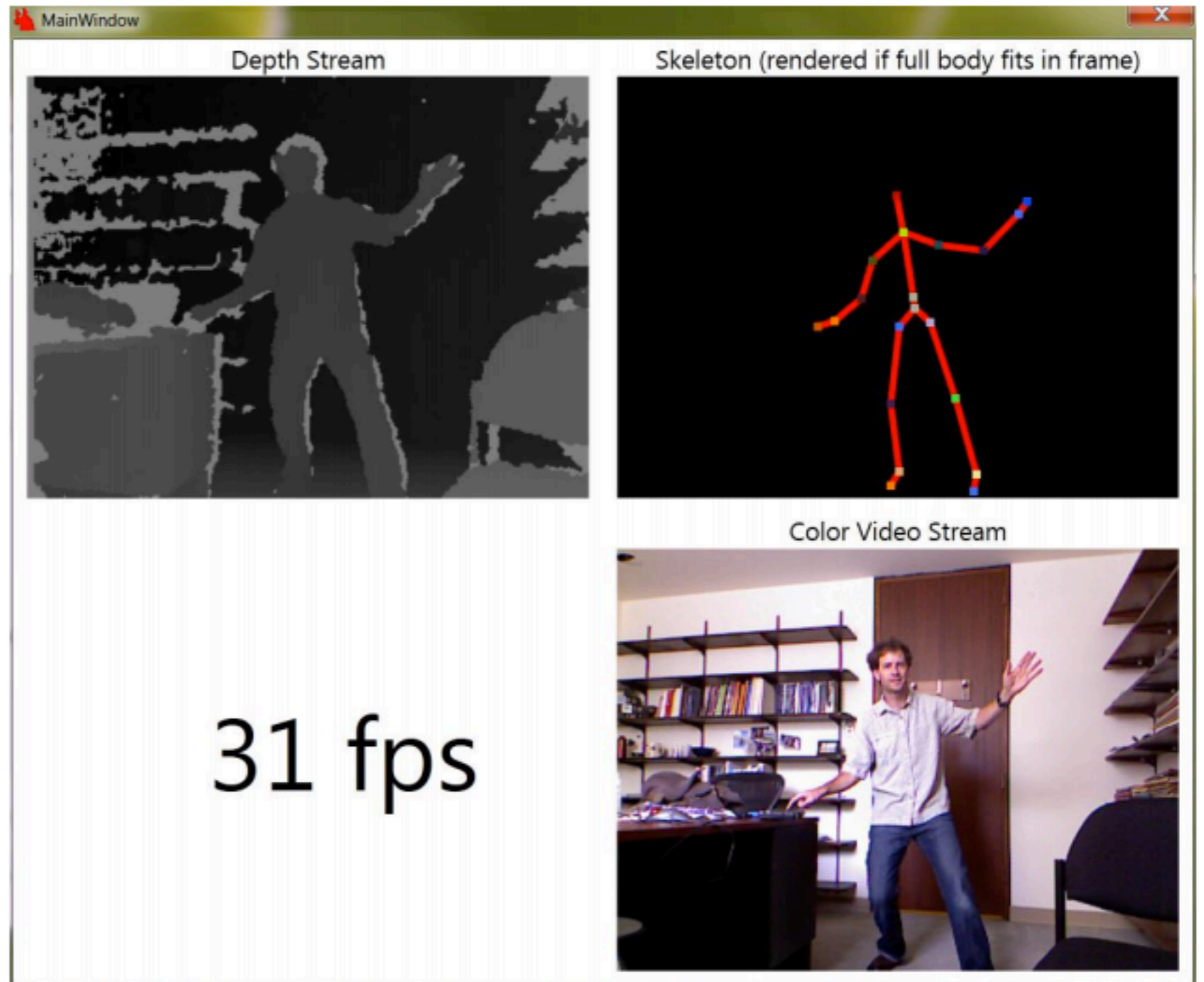
How does the Kinect Gesture Tracking Work

- Depth Video Stream
- Skeleton detection



How does the Kinect Gesture Tracking Work

- Depth Video Stream
- Skeleton detection
- Color Video Stream



How does the Kinect Gesture Tracking Work

How does the Kinect Gesture Tracking Work

- Several key technologies
 - to compute a depth image
 - Structured light
 - Depth from focus
 - Depth from stereo
 - Machine learning to infer skeleton position

How does the Kinect Gesture Tracking Work

How does the Kinect Gesture Tracking Work

- **Structured light**

- The depth map is constructed by analyzing a projected speckle pattern of infrared laser light
 - Microsoft licensed this technology from PrimeSense
- The depth computation is done by the PrimeSense hardware in the Kinect
- Details are not public, the following is speculation based on patent applications

How does the Kinect Gesture Tracking Work

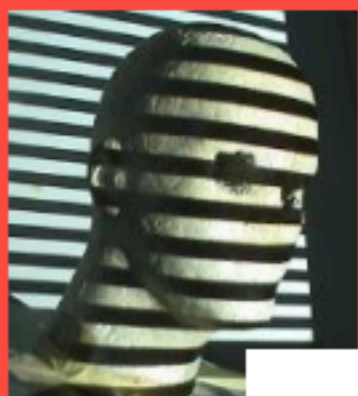
How does the Kinect Gesture Tracking Work

- **Structured light**
 - A Computer Vision concept
 - Based on projecting a known light pattern onto a scene
 - Analyzing how the observed light differs from the known projection
 - Assuming that the differences are due to the topology of the world

How does the Kinect Gesture Tracking Work

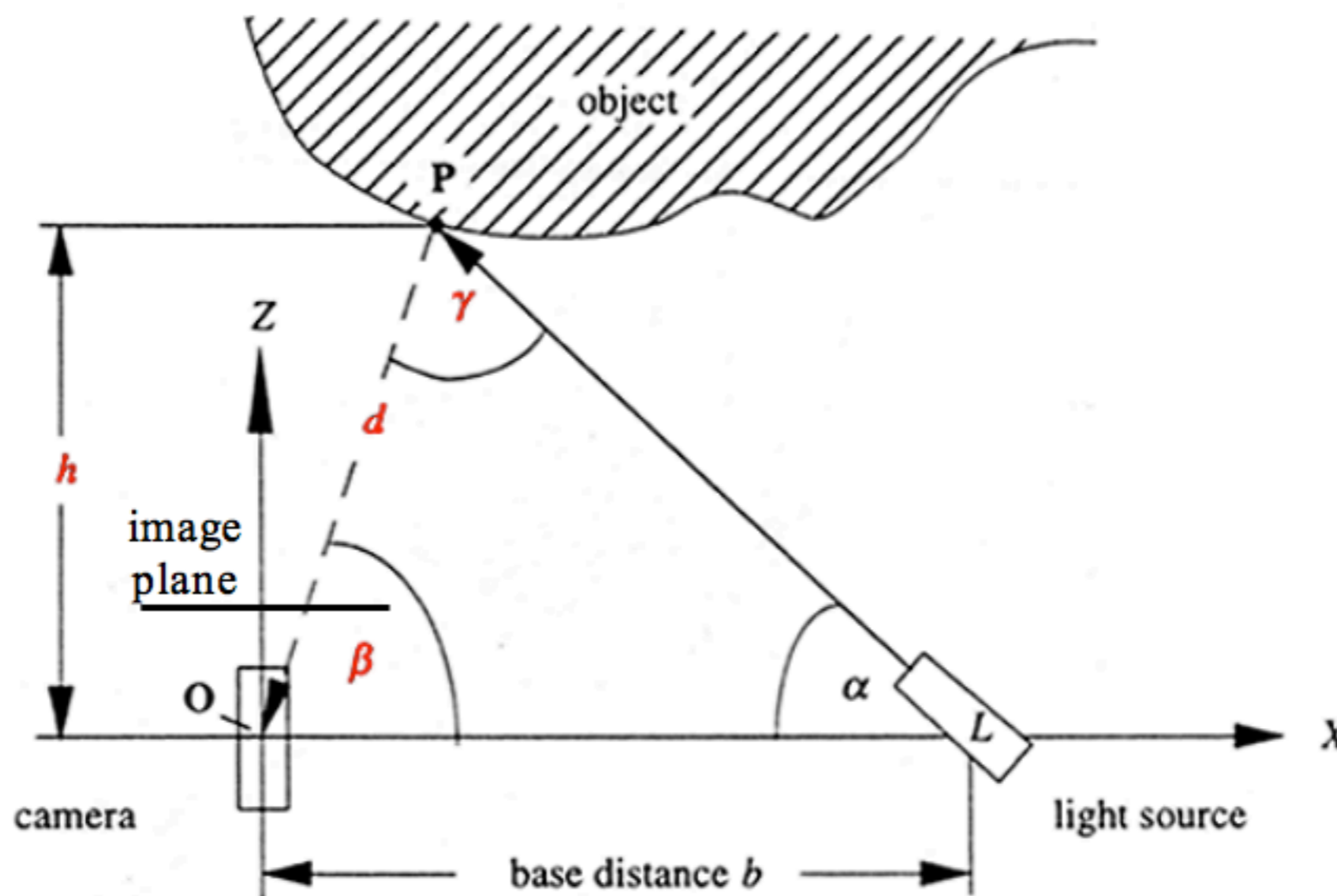
How does the Kinect Gesture Tracking Work

- **Structured light**
 - Technique #1



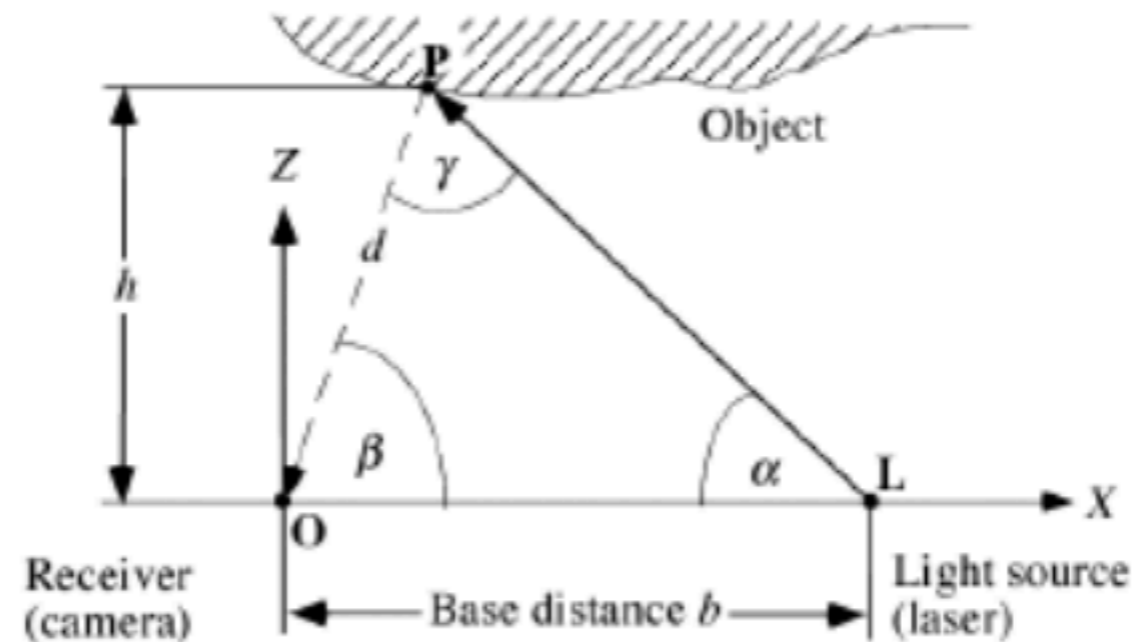
Light Spot Projection 2D

Assume point-wise illumination by laser beam, only 2D





Light Spot Projection 2D



O , L , and P define a triangle, and we determine the position of P by *triangulation*, using basic formulas about triangles such as the law of sines:

$$\frac{d}{\sin \alpha} = \frac{b}{\sin \gamma}$$

It follows that

$$d = \frac{b \cdot \sin \alpha}{\sin \gamma} = \frac{b \cdot \alpha}{\sin(\pi - \alpha - \beta)} = \frac{b \cdot \alpha}{\sin(\alpha + \beta)}$$

and, finally, $\mathbf{P} = (d \cdot \cos \beta, d \cdot \sin \beta)^T$. Note that β is determined by the position of the projected (illuminated) point P in the 1D image.



Light Spot Projection 2D

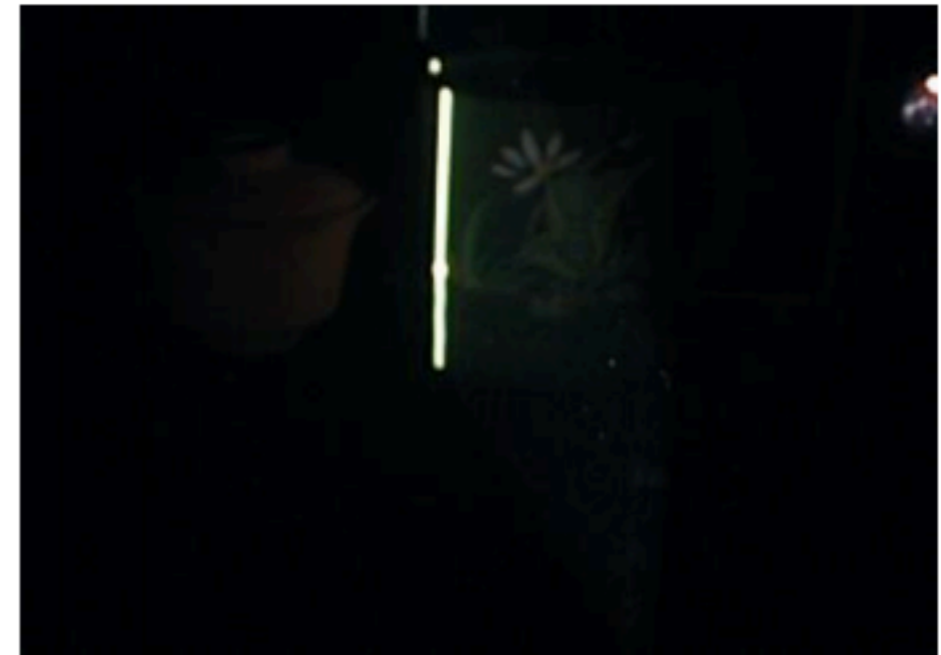
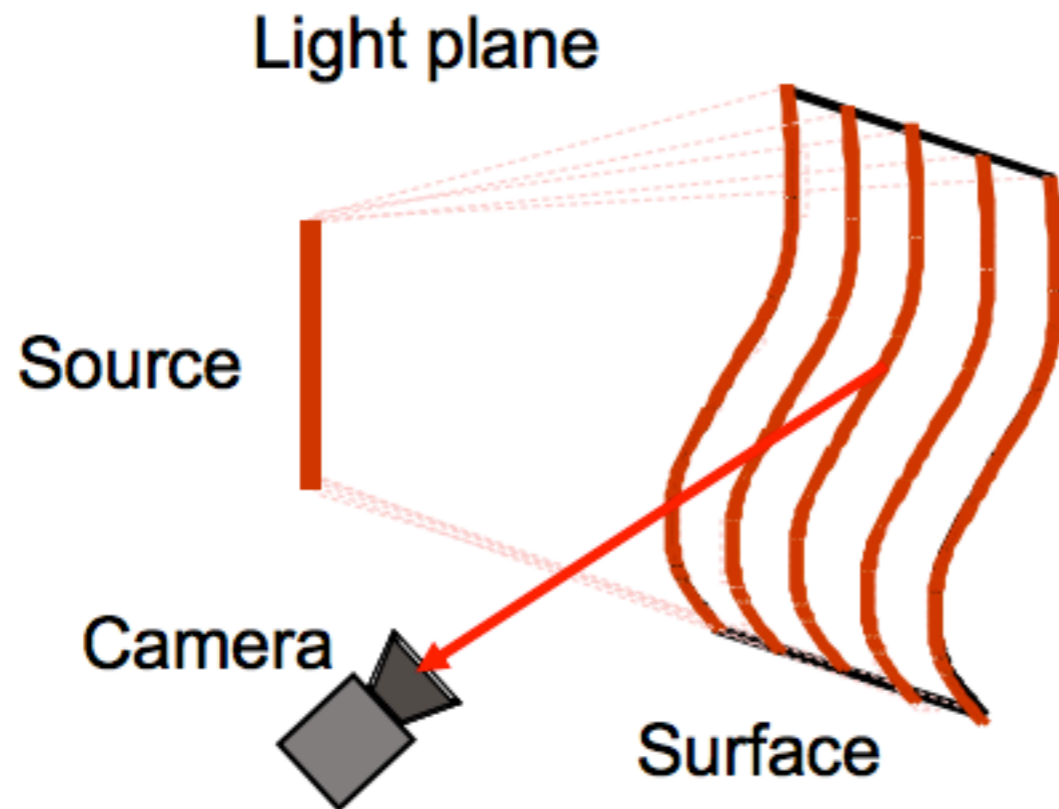
- Coordinates found by triangulation
 - β can be found by projection geometry
 - $d = b \cdot \sin(\alpha) / \sin(\alpha + \beta)$
 - $X_0 = d \cdot \cos(\beta)$
 - $Z_0 = h = d \cdot \sin(\beta)$
- Concept:
 - known b and α
 - β defined by projection geometry
 - Given image coordinate u and focal length f -> calculate β
 - Given b, α, β -> calculate d

How does the Kinect Gesture Tracking Work

How does the Kinect Gesture Tracking Work

- **Structured light**
 - Technique #2

Light Stripe Scanning – Single Stripe

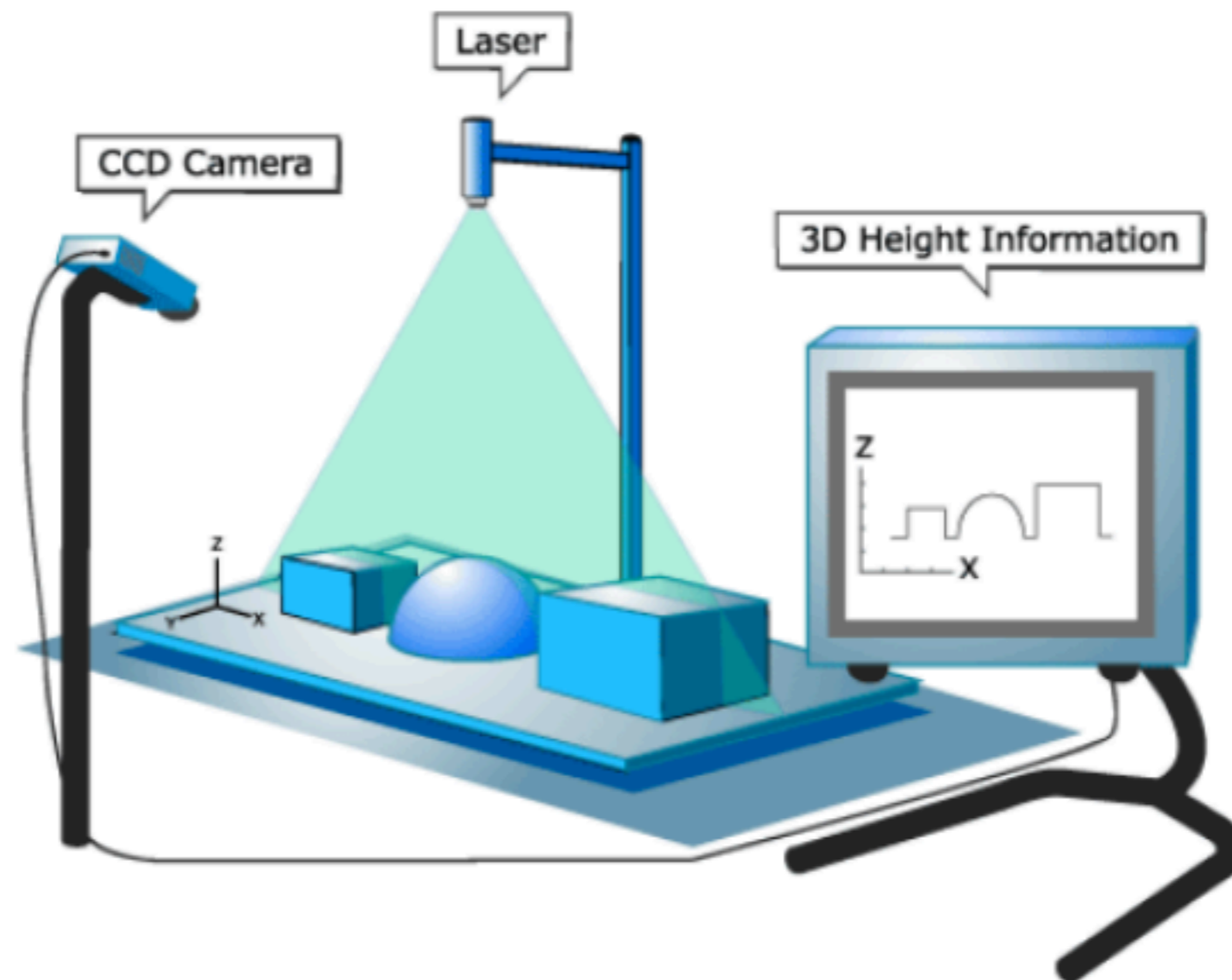


- Optical triangulation
 - Project a single stripe of laser light
 - Scan it across the surface of the object
 - This is a very precise version of structured light scanning
 - Good for high resolution 3D, but needs many images and takes time

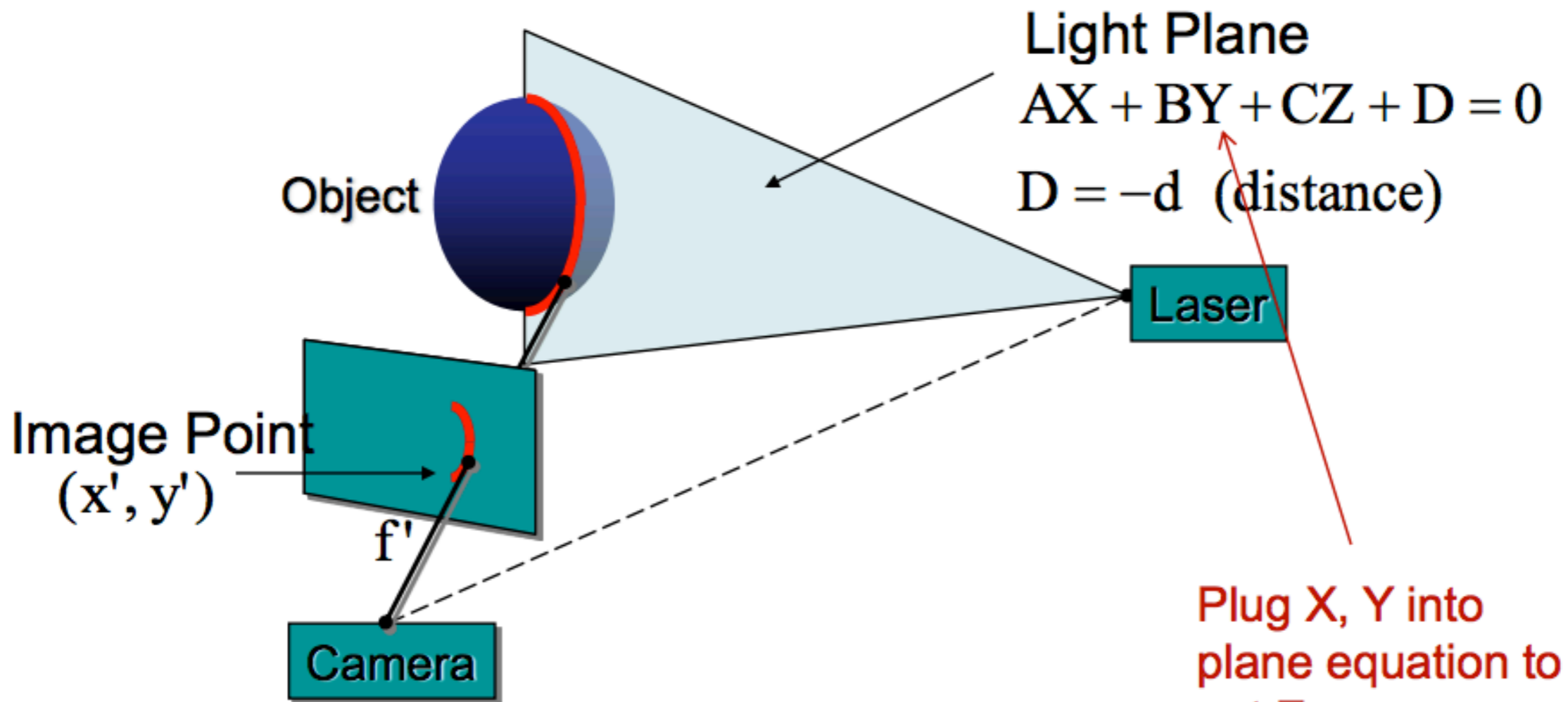


Light Stripe Projection

Structured light is the projection of a light pattern (ray, plane, grid, encoded light, and so forth) under calibrated geometric conditions onto an object whose shape needs to be recovered.



Triangulation



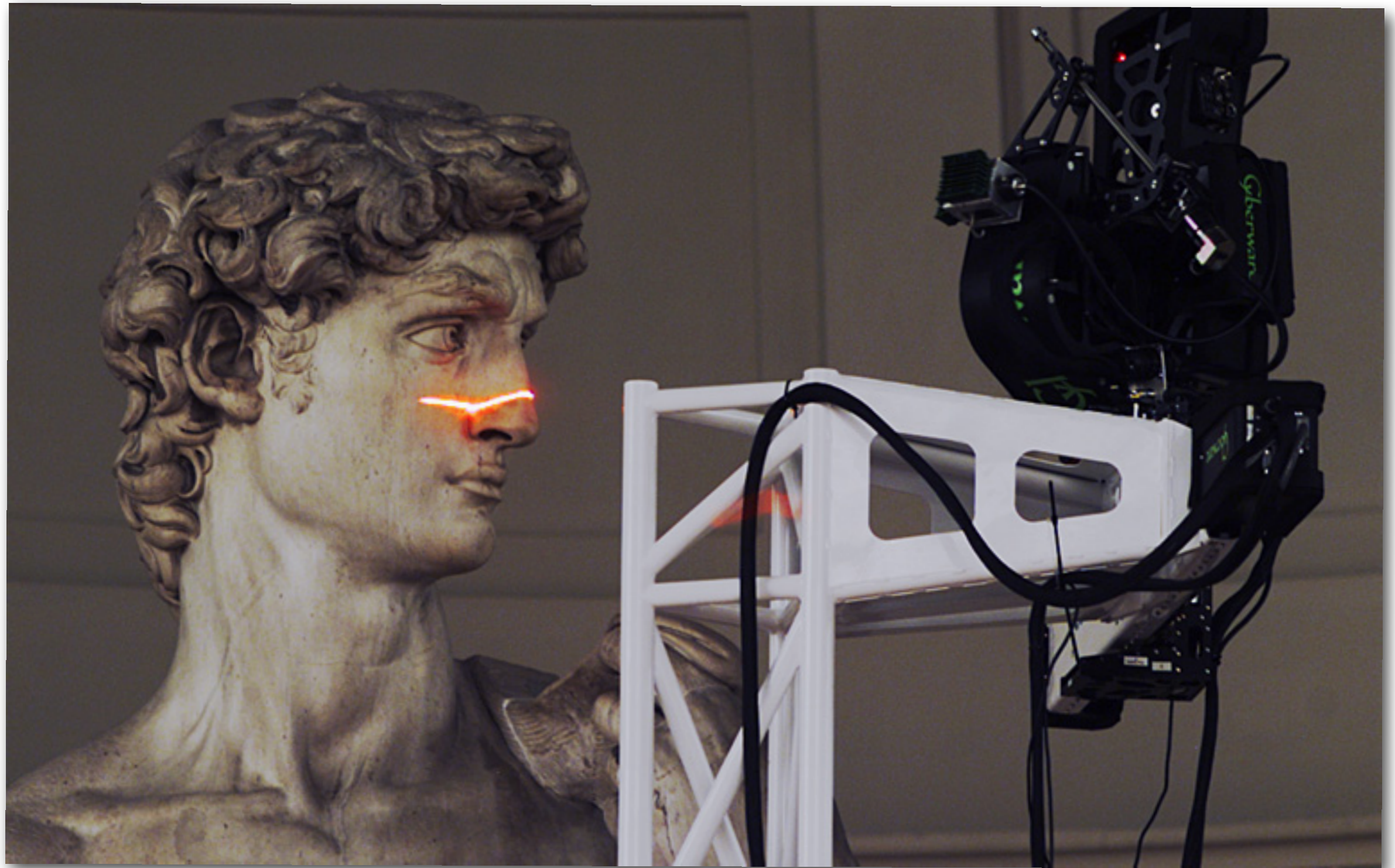
Plug X, Y into plane equation to get Z

- Depth from ray-plane triangulation:
 - Intersect camera ray with light plane

$$\begin{aligned}
 X &= x'Z / f' \\
 Y &= y'Z / f' \\
 Z &= \frac{-Df'}{Ax' + By' + Cf'}
 \end{aligned}$$

Courtesy S. Narasimhan, CMU

Structured Light Technique #2



<http://graphics.stanford.edu/projects/mich/more-david/scanner-head-and-david-head-s.jpg>

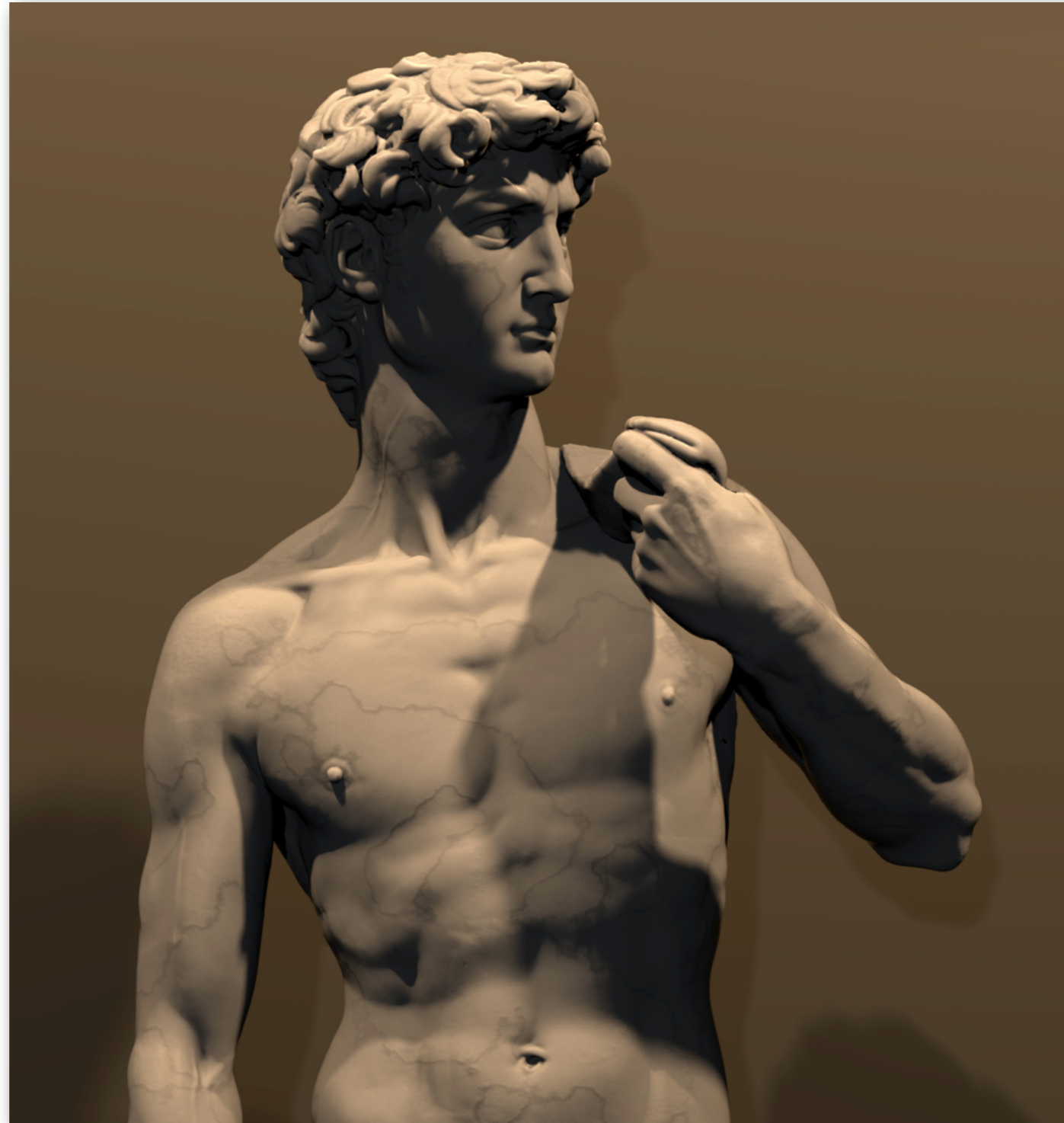
Application of Structured Light Scanning

Application of Structured Light Scanning



<http://www.flickr.com/photos/nathaninsandiego/6165296066/sizes/z/in/photostream/>

Application of Structured Light Scanning

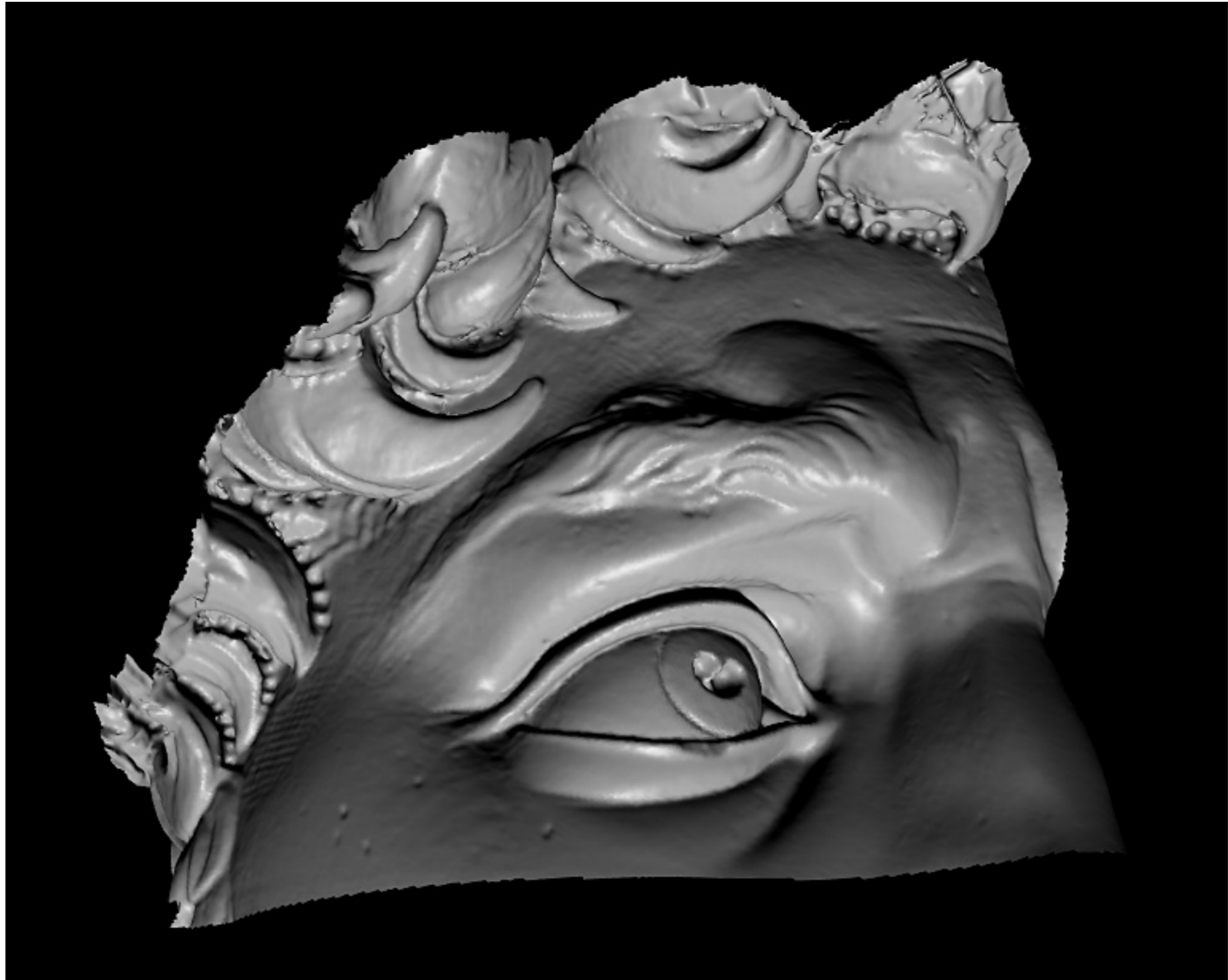


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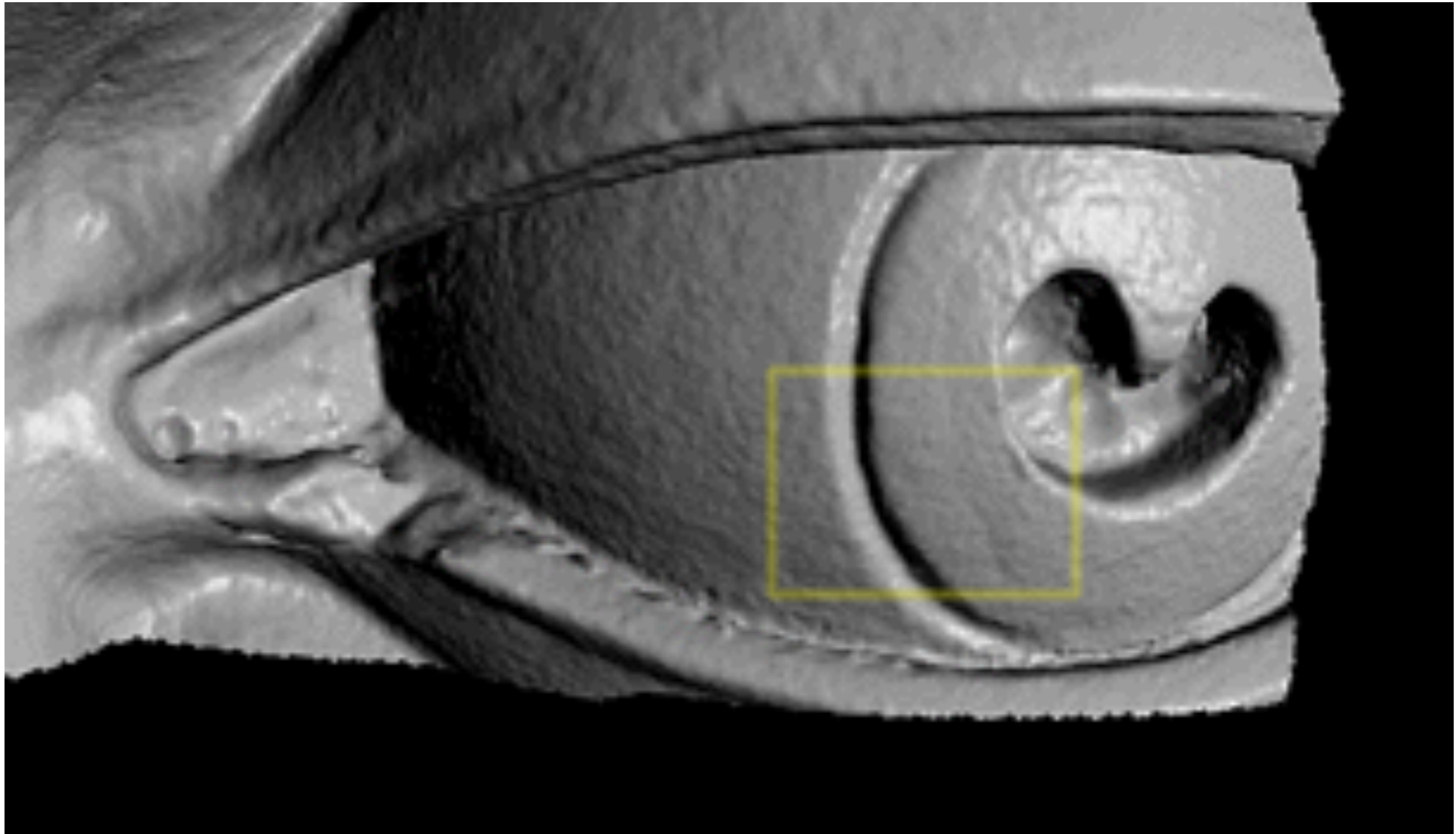
Application of Structured Light Scanning



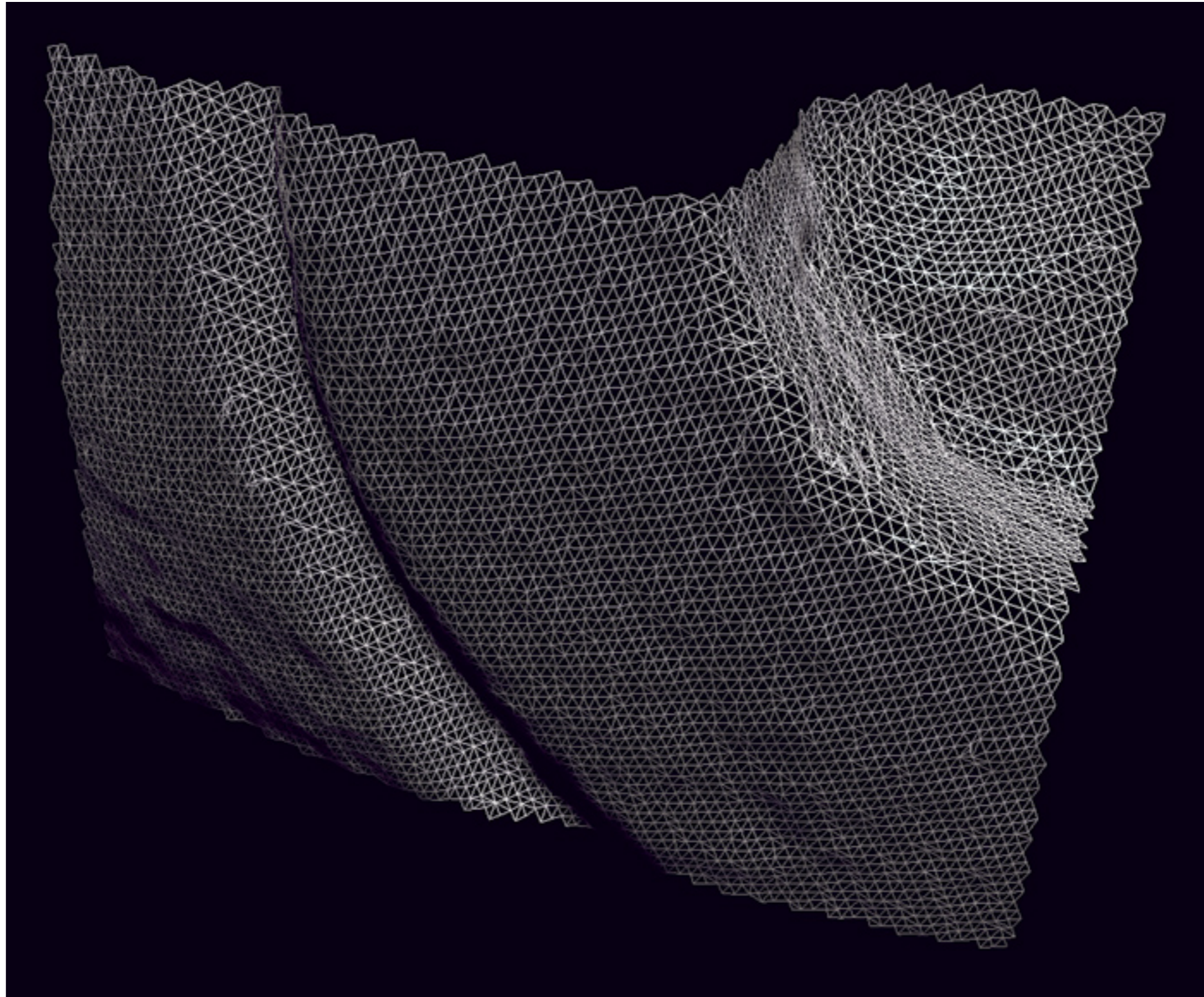
Application of Structured Light Scanning



Application of Structured Light Scanning



Application of Structured Light Scanning



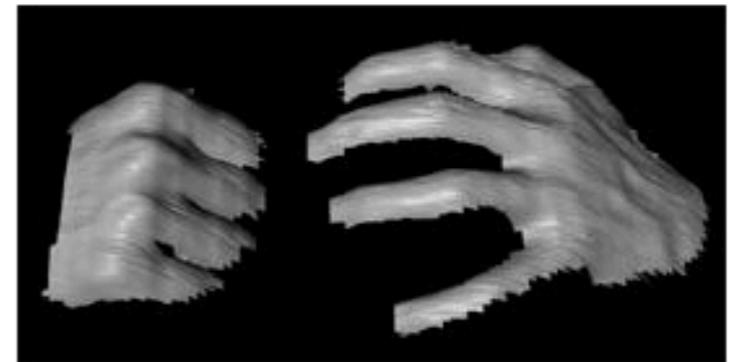
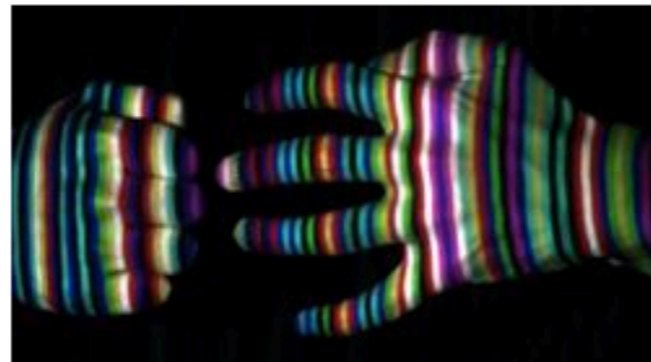
Digital Michelangelo Project:
<http://graphics.stanford.edu/projects/mich/>

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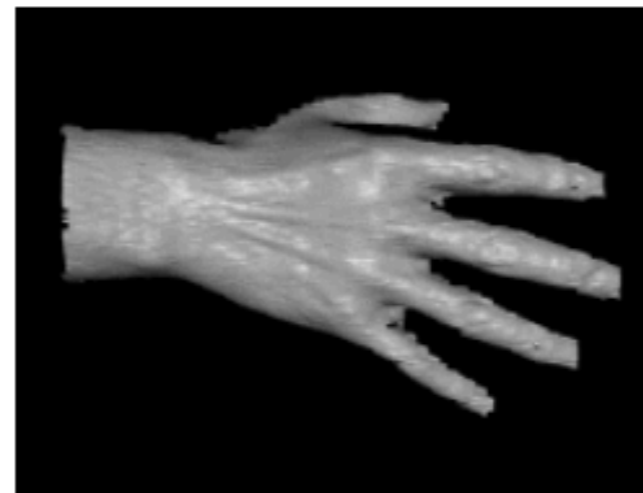
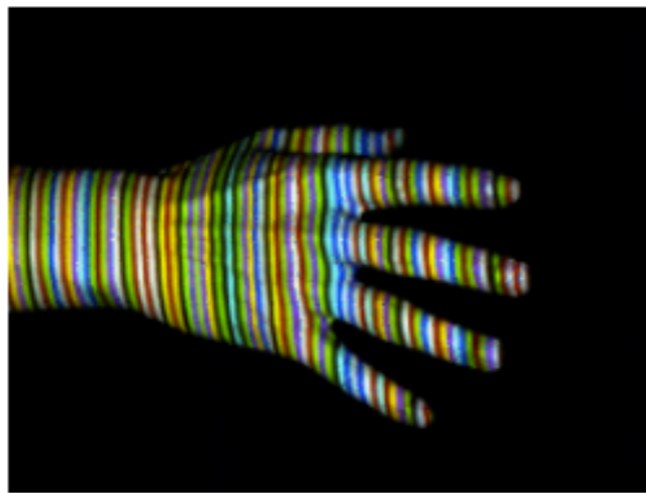
How does the Kinect Gesture Tracking Work

- **Structured light**
 - Technique #3

Real Time by Color Coding



Works despite complex appearances



Works in real-time and on dynamic scenes

- Need very few images (one or two).
- But needs a more complex correspondence algorithm

Zhang et al, 3DPVT 2002

<http://www.sci.utah.edu/~gerig/CS6320-S2012/Materials/CS6320-CV-S2012-StructuredLight.pdf>

How does the Kinect Gesture Tracking Work

How does the Kinect Gesture Tracking Work

- **Structured light**
 - Do it yourself

How does the Kinect Gesture Tracking Work

Build Your Own 3D Scanner: 3D Photography for Beginners



SIGGRAPH 2009 Course Notes

Wednesday, August 5, 2009

Douglas Lanman
Brown University
dlanman@brown.edu

Gabriel Taubin
Brown University
taubin@brown.edu

- Course notes: <http://mesh.brown.edu/byo3d/notes/byo3D.pdf>
- Slides: <http://mesh.brown.edu/byo3d/slides.html>
- Source code: <http://mesh.brown.edu/byo3d/source.html>

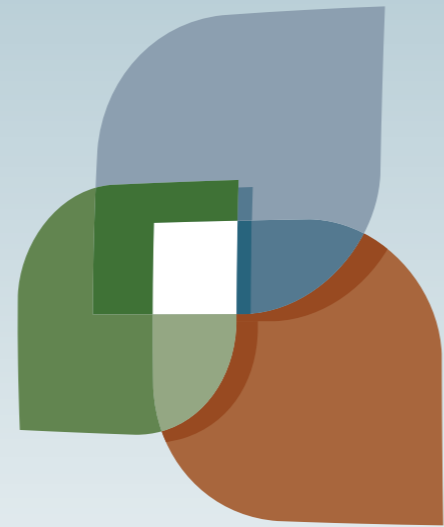
Dual Photography

Pradeep Sen* Billy Chen* Gaurav Garg* Stephen R. Marschner†
Mark Horowitz* Marc Levoy* Hendrik P.A. Lensch*

*Stanford University

†Cornell University





L U C I

