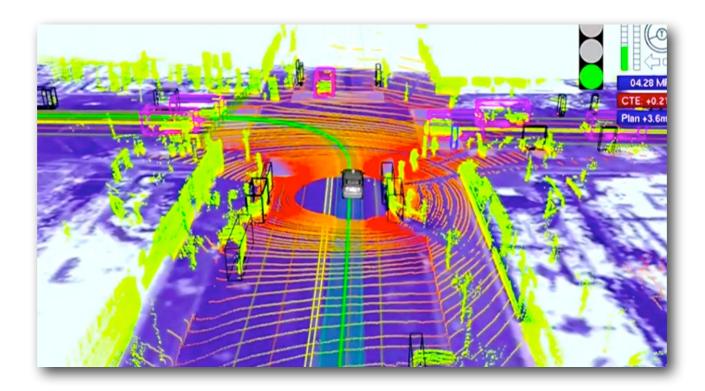
Localization beyond Satellite Systems

Mobile and Ubiquitous Games ICS 163 Donald J. Patterson

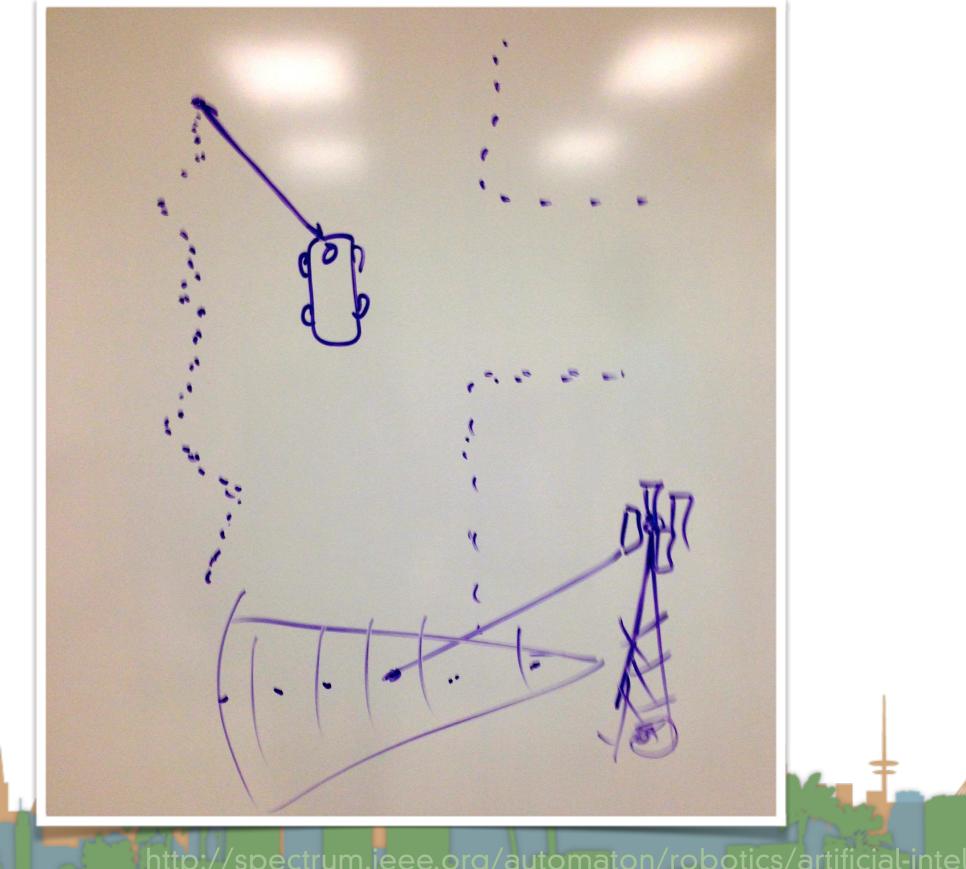
Google's self-driving car



Two things seem particularly interesting about Google's approach. First, it relies on very detailed maps of the roads and terrain, something that Urmson said is essential to determine accurately where the car is. Using GPS-based techniques alone, he said, the location could be off by several meters.



Google's self-driving car



http://spectrum.ieee.org/automaton/robotics/artificial-intelligence/ how-google-self-driving-car-works

Intro to Location

Global Location GPS



A Survey and Taxonomy of Location Systems for Ubiquitous Computing

Jeffrey Hightower and Gaetano Borriello University of Washington, Computer Science and Engineering Box 352350, Seattle, WA 98195

Technical Report UW-CSE 01-08-03

August 24, 2001

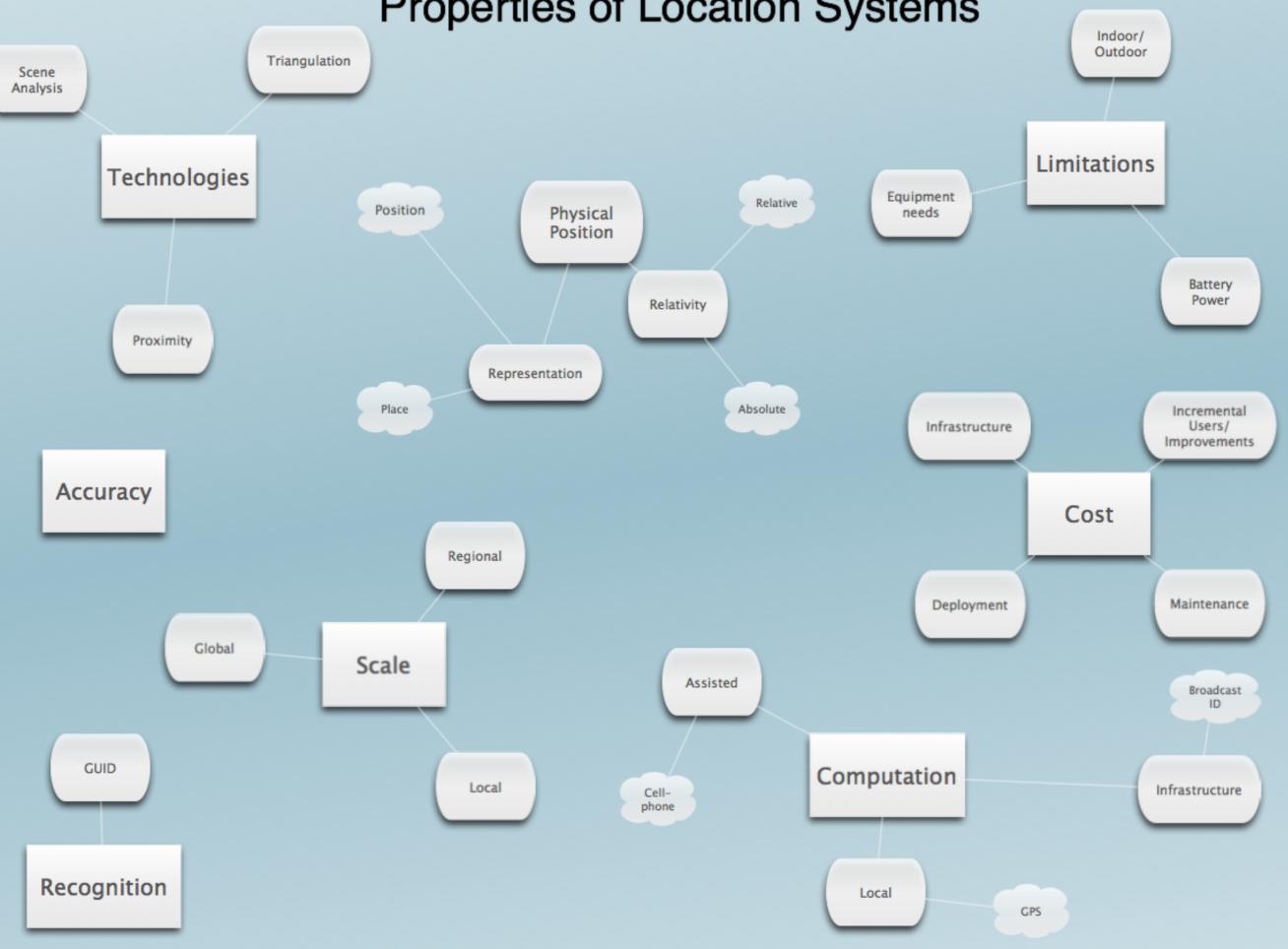
Abstract

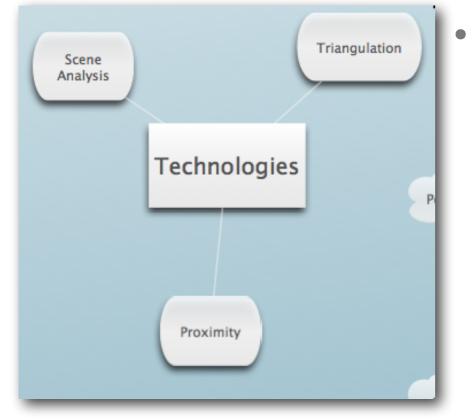
Emerging mobile computing applications often need to know where things are physically located. To meet this need, many different location systems and technologies have been developed. In this paper we present a the basic techniques used for location-sensing, describe a taxonomy of location system properties, present a survey of research and commercial location systems that define the field, show how the taxonomy can be used to evaluate location-sensing systems, and offer suggestions for future research. It is our hope that this paper is a useful reference for researchers and location-aware application builders alike for understanding and evaluating the many options in this domain.

1 Introduction

To serve us well, emerging mobile computing applications will need to know the physical location of things so that they can record them and report them to us: Are we almost to the campsite? What lab bench was I standing by when I prepared these tissue samples? How should our search-and-rescue team move to quickly locate all the avalanche victims? Can I automatically display this stock devaluation chart on the large screen I am standing next to? Where is the nearest cardiac defibrillation unit?

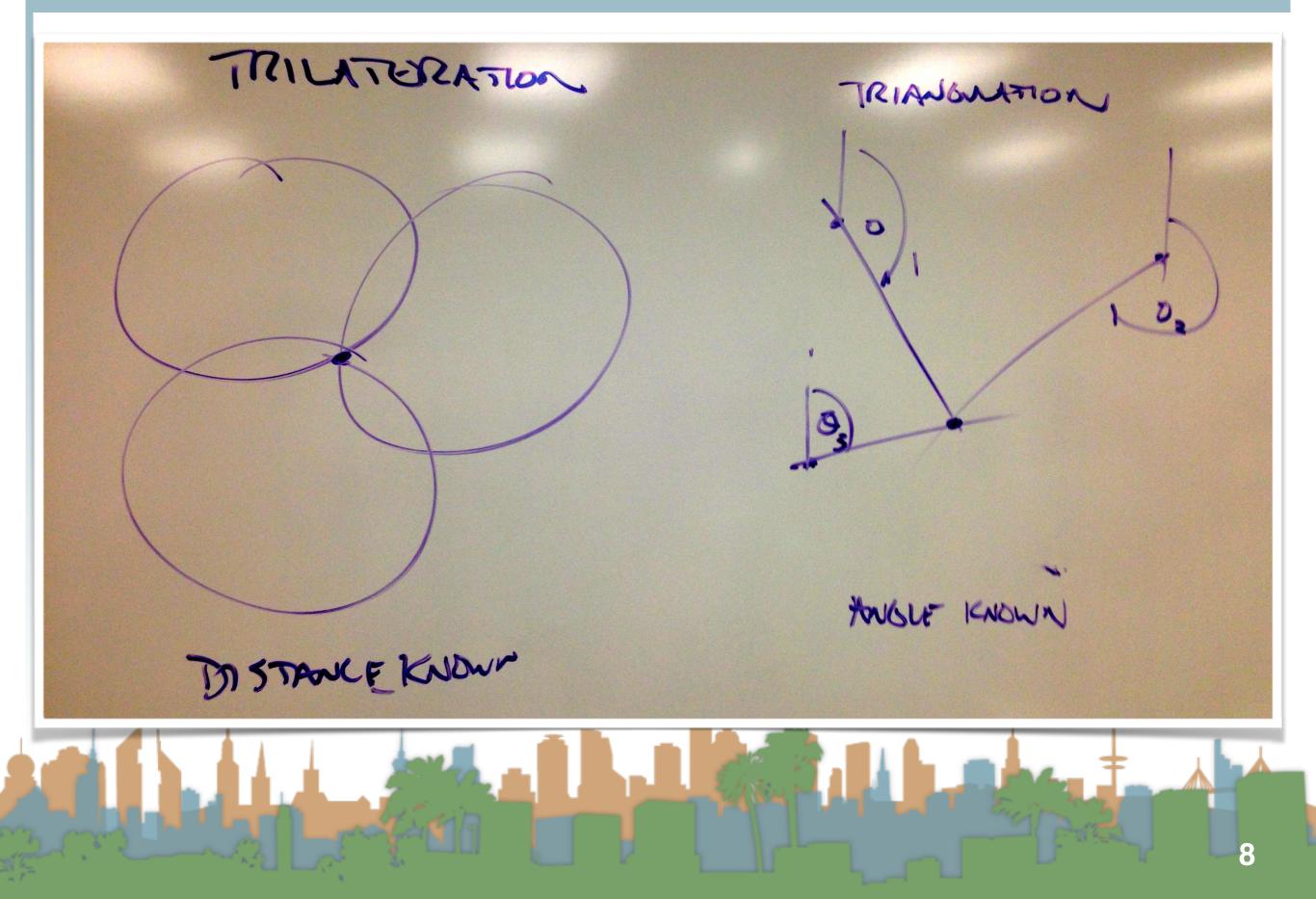
Researchers are working to meet these and similar needs by developing systems and technologies that automatically locate people, equipment, and other This technical report is an extended version of the article *Location Systems for Ubiquitous Computing* [22] ©Copyright IEEE. Personal use of this material is permitted. However, permission to reprint/republish this material for advertising or promotional purposes or for creating new collective works for resale or redistribution to servers or lists, or to reuse any copyrighted component of this work in other works must be obtained from the IEEE.

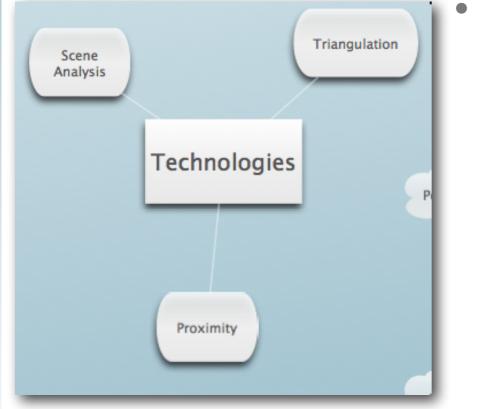




Technologies

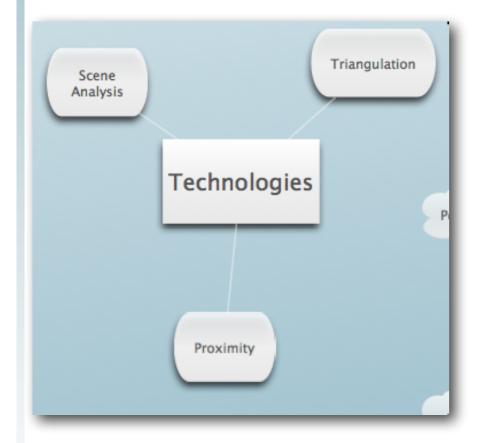
- Triangulation
 - Multiple references to fixed locations which resolve position using angles
- Trilateration
 - GPS is an example
 - multiple references to fixed locations which resolve position using circles



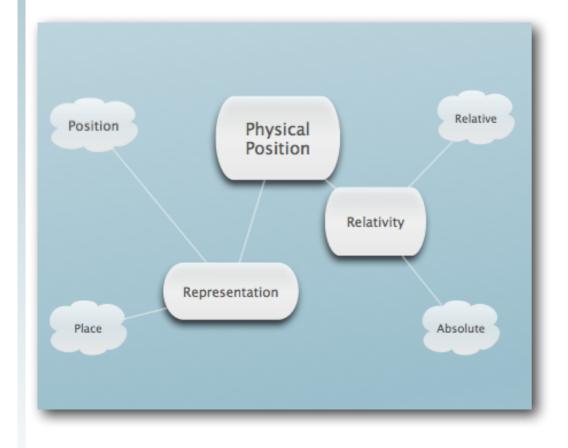


- Technologies
 - Proximity
 - Knowing that you are near a fixed location
 - Typically based on non-localization technology
 - Cell-towers, Credit card usage, login information

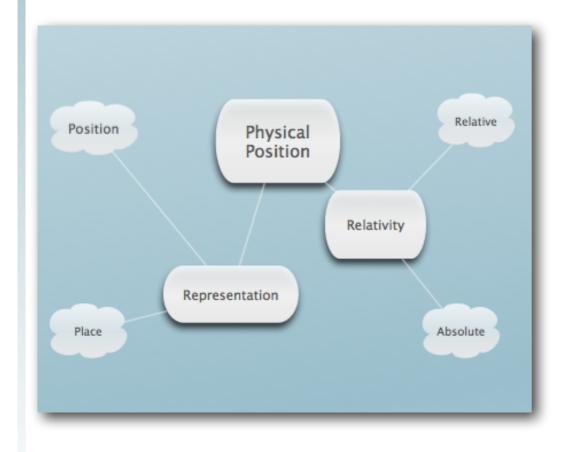




- Technologies
 - Scene Analysis
 - Evaluating content from a fixed camera
 - Color histograms from doorways
 - Evaluating content from a mobile camera
 - tour guide scene matching

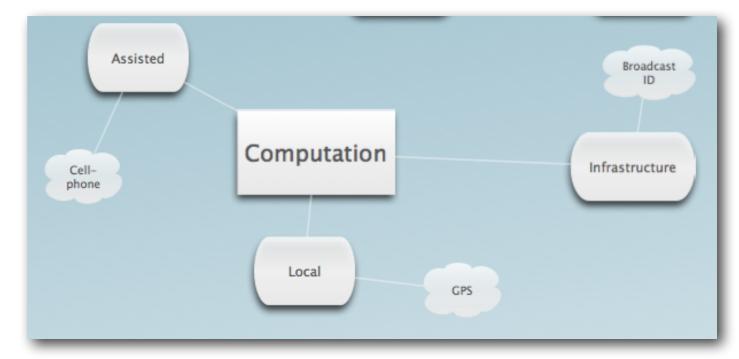


- Properties
 - Physical Position/Symbolic location
 - Position
 - Exact, Unambiguous, Machine friendly
 - Place
 - Inexact, Ambiguous, Human
 Friendly



- Properties
 - Absolute/Relative
 - GPS is absolute
 - Laser range finder is relative
 - Transforming between the two is possible with additional information





- Properties
 - Where is the computation done?
 - GPS locally private, scalable
 - Cell-phone positioning assisted, scalable to a degree, location is revealed

Broadcast ID-badge systems - localization is in infrastructure

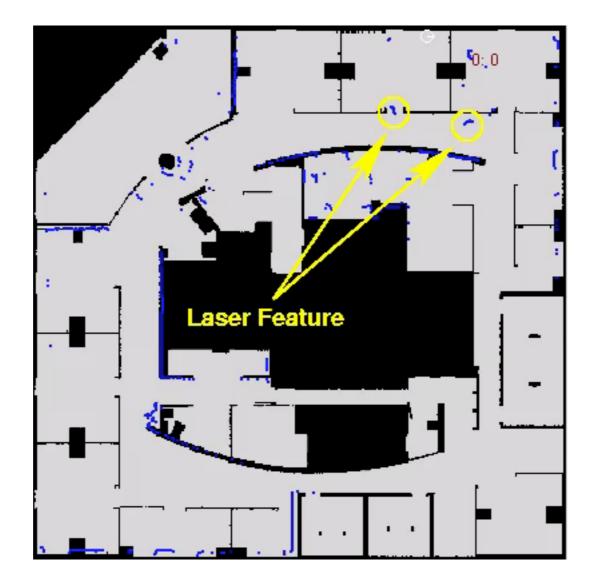
• Properties

Accuracy and precision

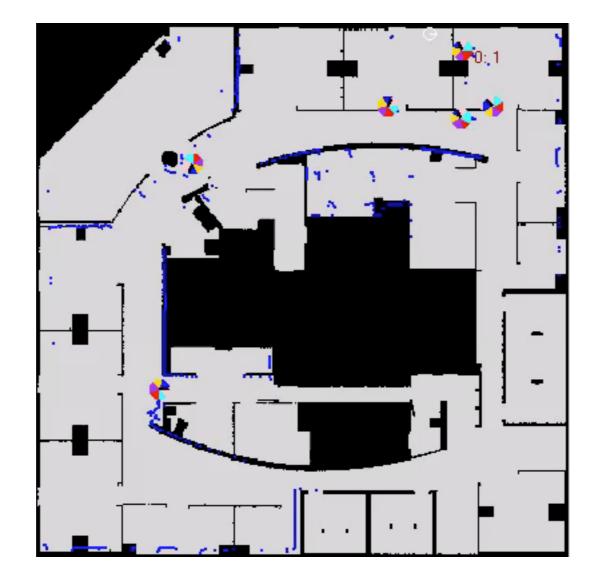


- GPS 15m 95% of the time
- Sensor fusion tries to improve accuracy and/or precision by combining sensors
- Accuracy and precision may change to conserve battery life.

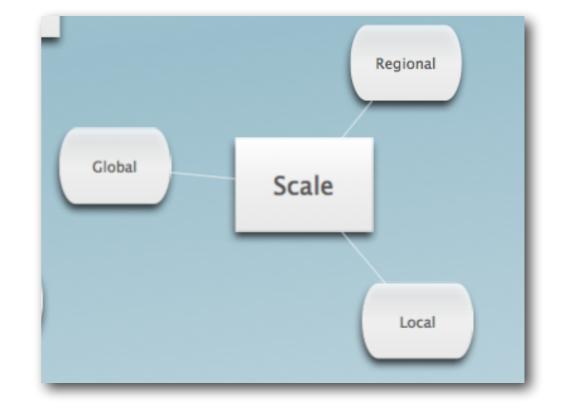




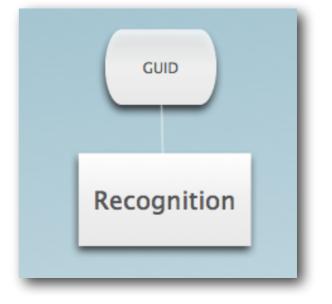








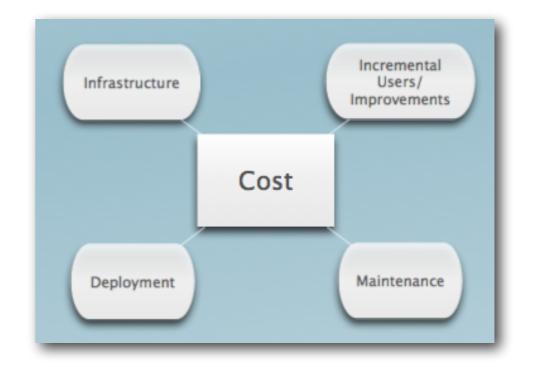
- Properties
 - Scale
 - Global, Regional, Local
 - GPS Global
 - RFID Readers -local
 - Cell-phone localization regional

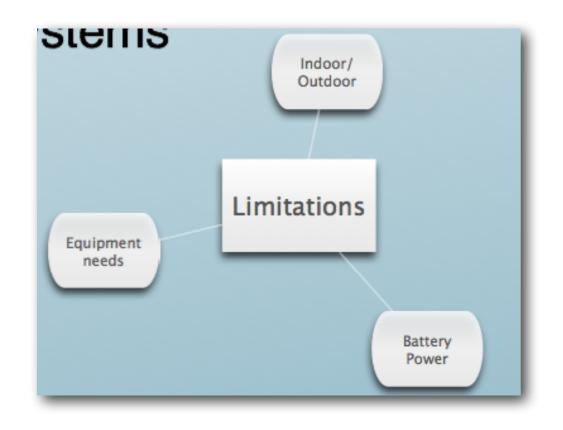


- Properties
 - Recognition
 - GUID globally unique identifier
 - Do we know who or what you are?
 - GPS no
 - Sensor fusion maybe



- Properties
 - Cost
 - Deployment
 - Infrastructure
 - Maintenance
 - Incremental Users or Improvements

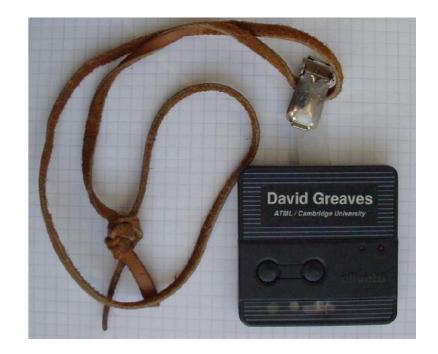




- Properties
 - Limitations
 - Indoor/ Outdoor
 - Battery Power
 - New Equipment



- Active Badge
 - GUID broadcast by infrared
 - symbolic proximity
 - absolute positioning
 - sunlight/fluorescent lighting





Examples

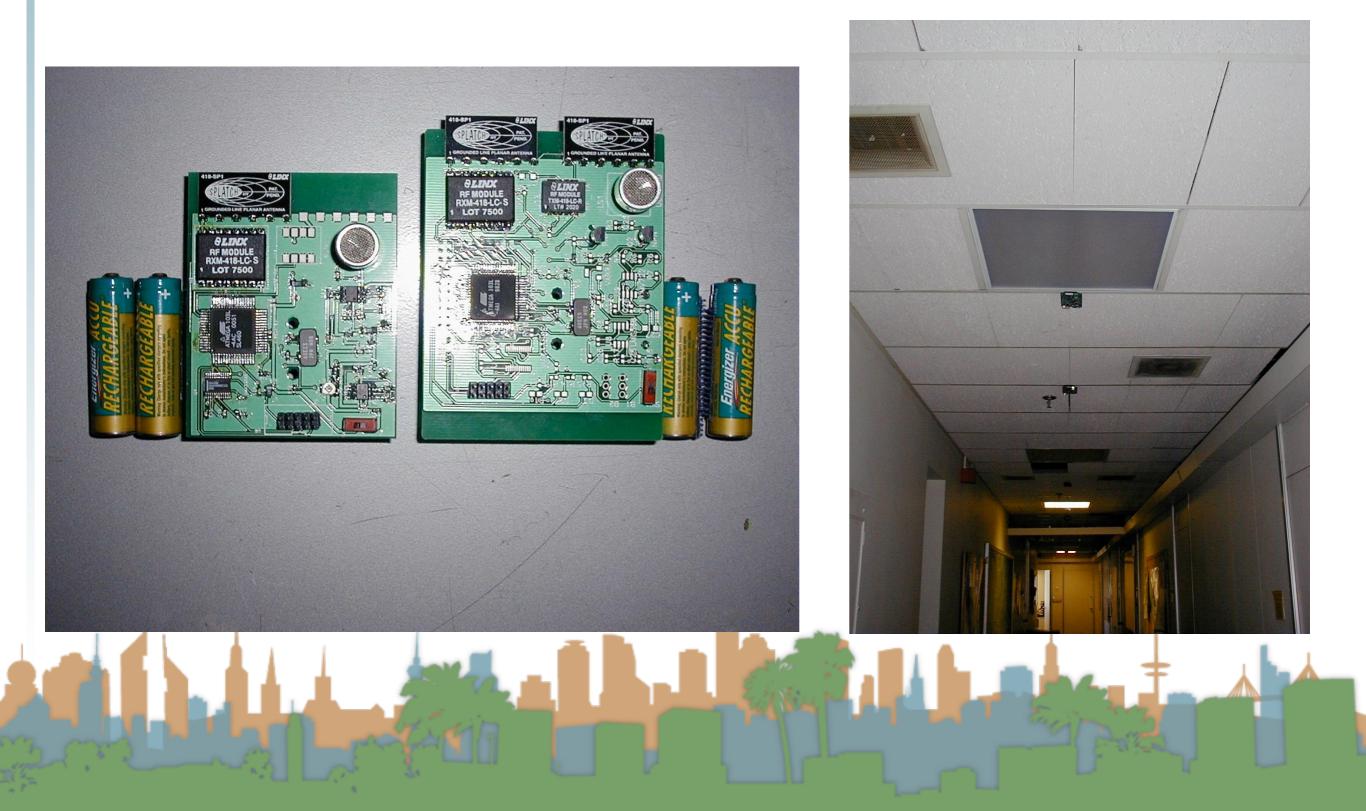
• Active Bat



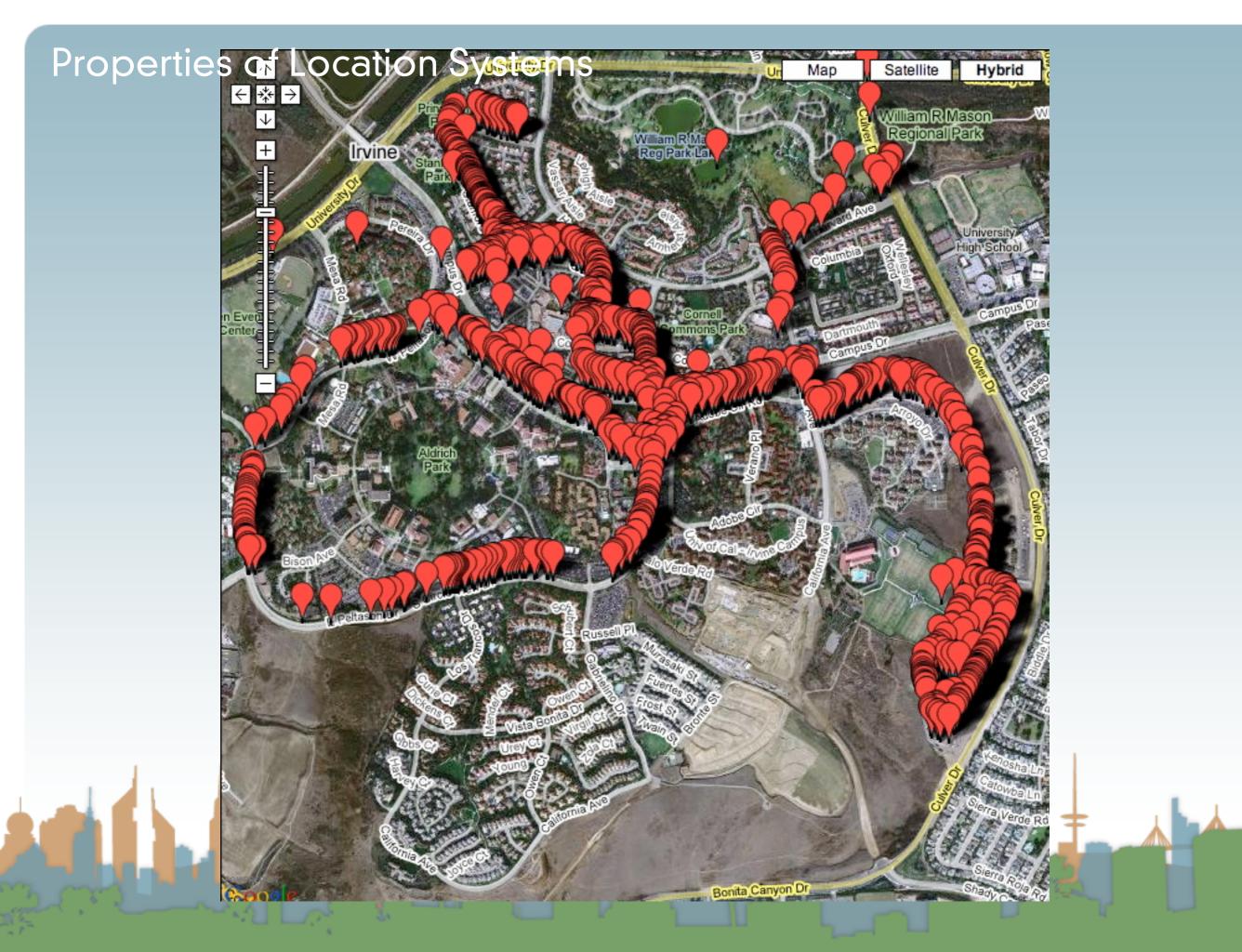
- GUID ultrasonic broadcast by radio request
- infrastructure computes absolute proximity
- 9cm 95% of the time
- bad scalability, hard to deploy, maybe costly



- Cricket
 - Object based ultrasonic localization
 - radio frequency control signal
 - trilateration base on time-of-flight
 - private, decentralized scalability
 - local computation -> power drain



- RADAR
 - building-wide tracking system
 - 2-D Wifi based localization
 - "scene analysis" through fingerprinting
 - local computation -> power drain



- Smart Floor
 - local tracking
 - anonymous
 - no additional equipment for a person
 - poor scalability
 - costly





How does a phone find your location?

- "Real" GPS
- "Assisted" GPS
 - Help with "Real" GPS
 - Send your position
 - Cell-tower based localization
- WiFi based localization
- IP based localization

- What are the properties of each?
- What are other crazy ideas of how to figure out your location?

Geo-Cache Assignment



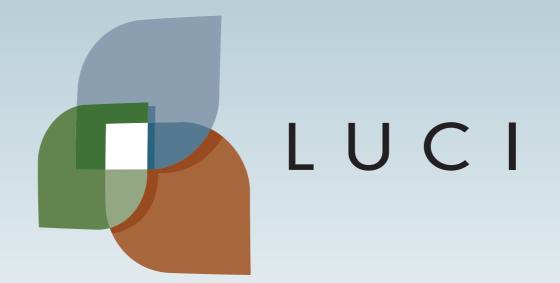
http://www.ics.uci.edu/~djp3/classes/2014_03_ICS163/tasks/geocach



Geo-Cache Assignment







El Martin