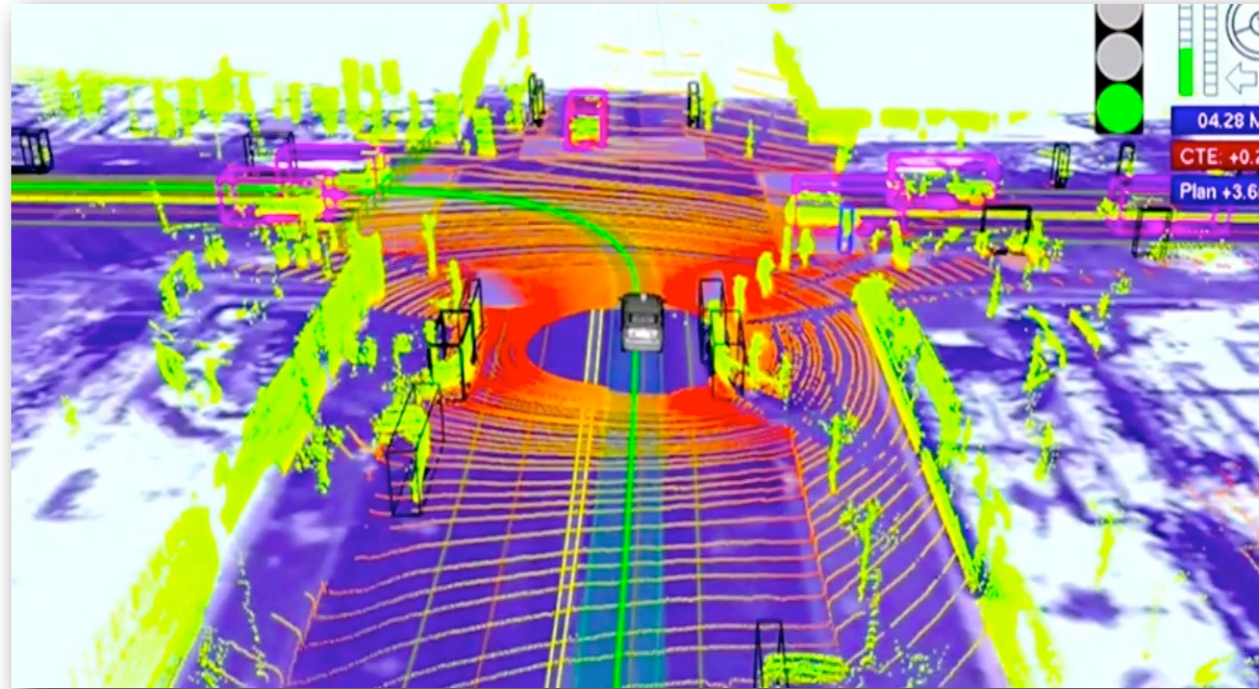


User Interaction: Localization beyond Satellite Systems

Assoc. Professor Donald J. Patterson
INF 133 Fall 2014



Google's self-driving car

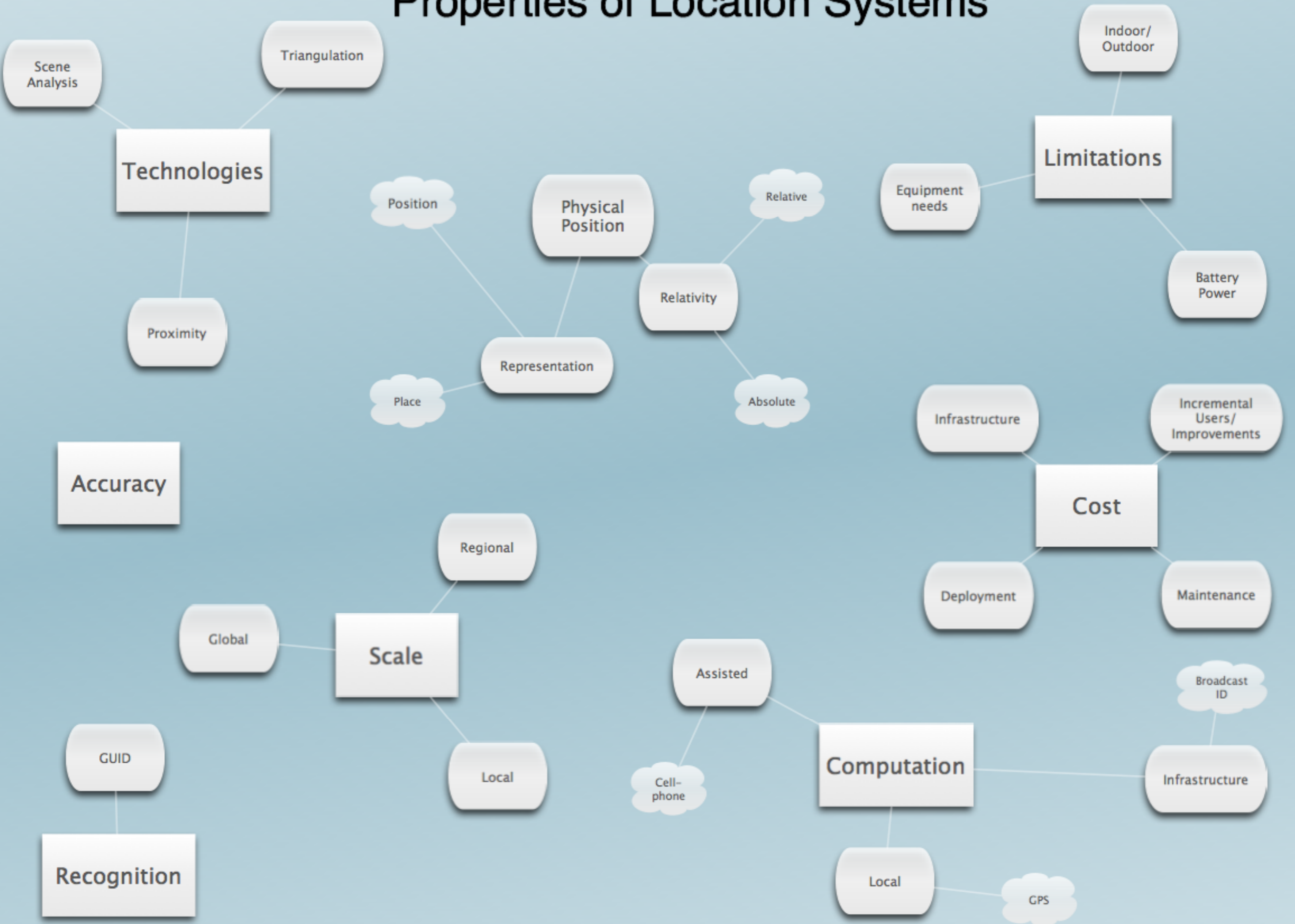


Two things seem particularly interesting about Google's approach. First, it relies on very detailed maps of the roads and terrain, something that Urmson said is essential to determine accurately where the car is. Using GPS-based techniques alone, he said, the location could be off by several meters.

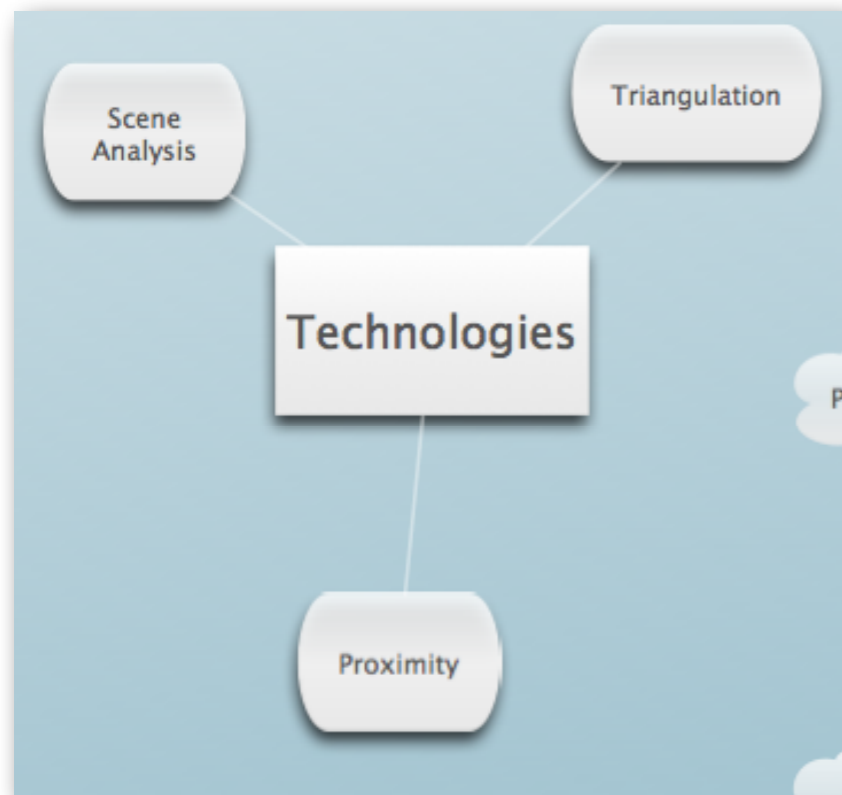
Global Location GPS



Properties of Location Systems

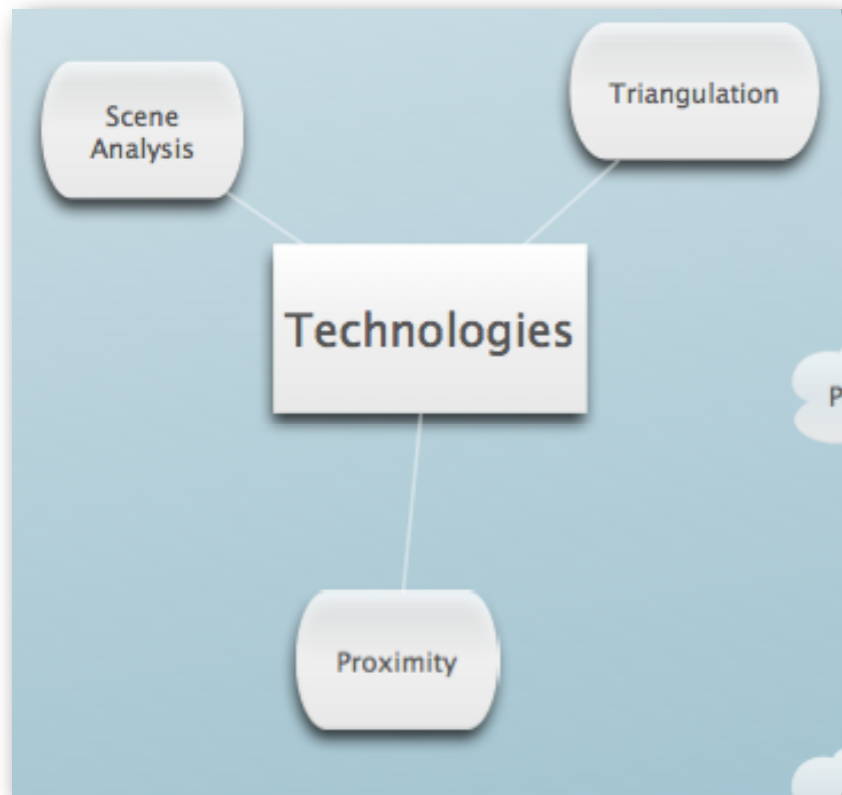


Properties of Location Systems



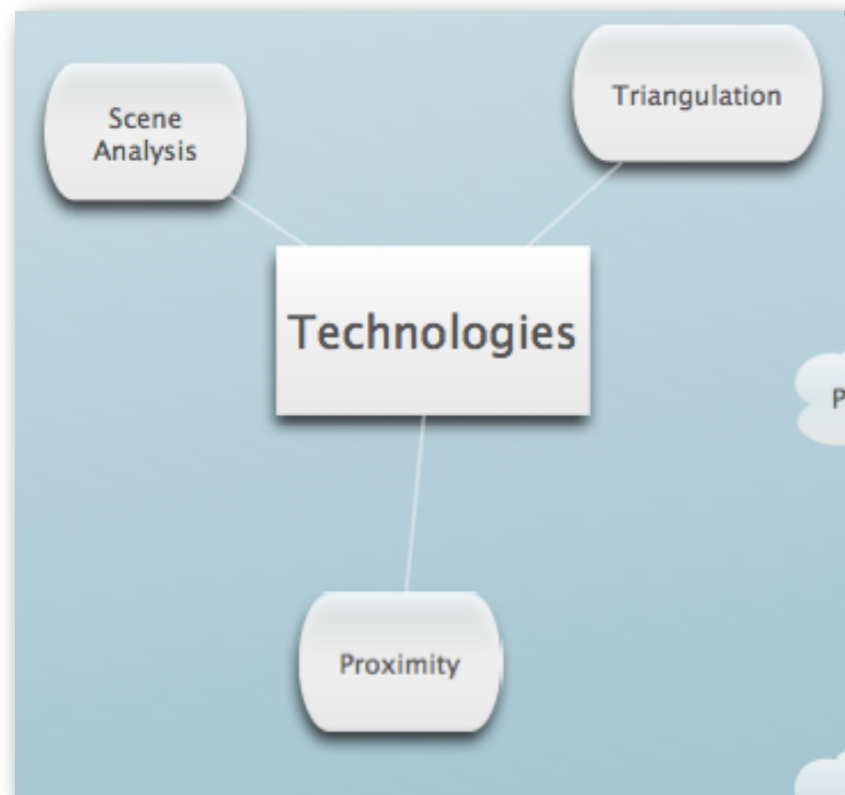
- Technologies
 - Triangulation
 - GPS is an example
 - Multiple references to fixed locations which resolve position

Properties of Location Systems



- Technologies
 - Proximity
 - Knowing that you are near a fixed location
 - Typically based on non-localization technology
 - Cell-towers, Credit card usage, login information

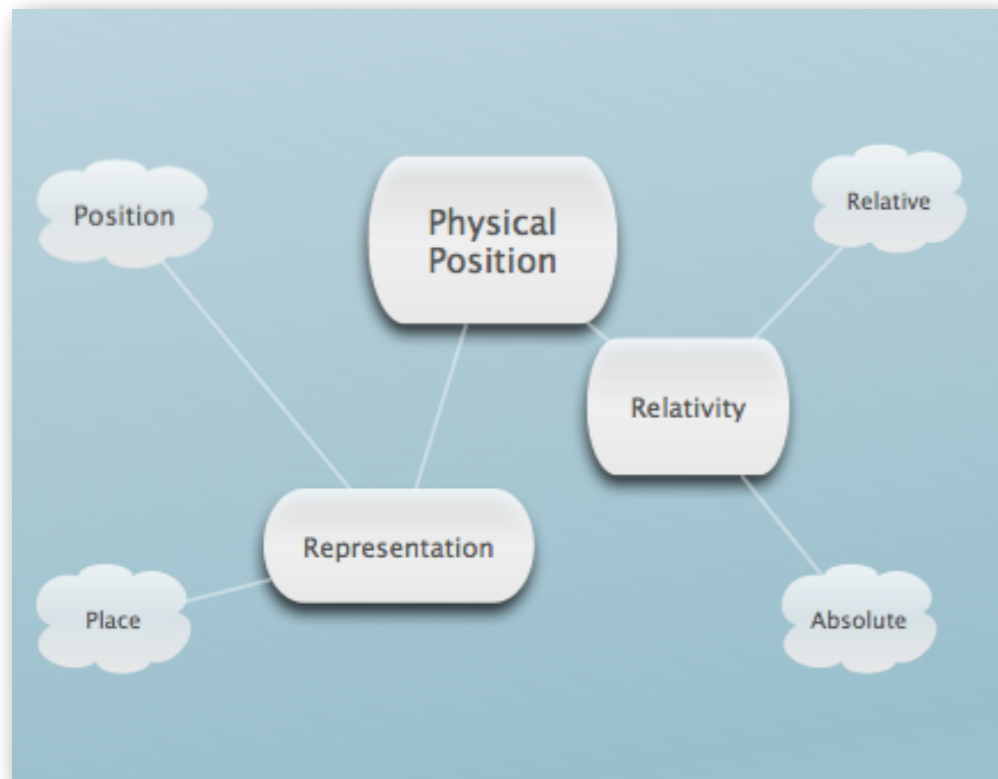
Properties of Location Systems



- Technologies
 - Scene Analysis
 - Evaluating content from a fixed camera
 - Color histograms from doorways
 - Evaluating content from a mobile camera
 - tour guide scene matching



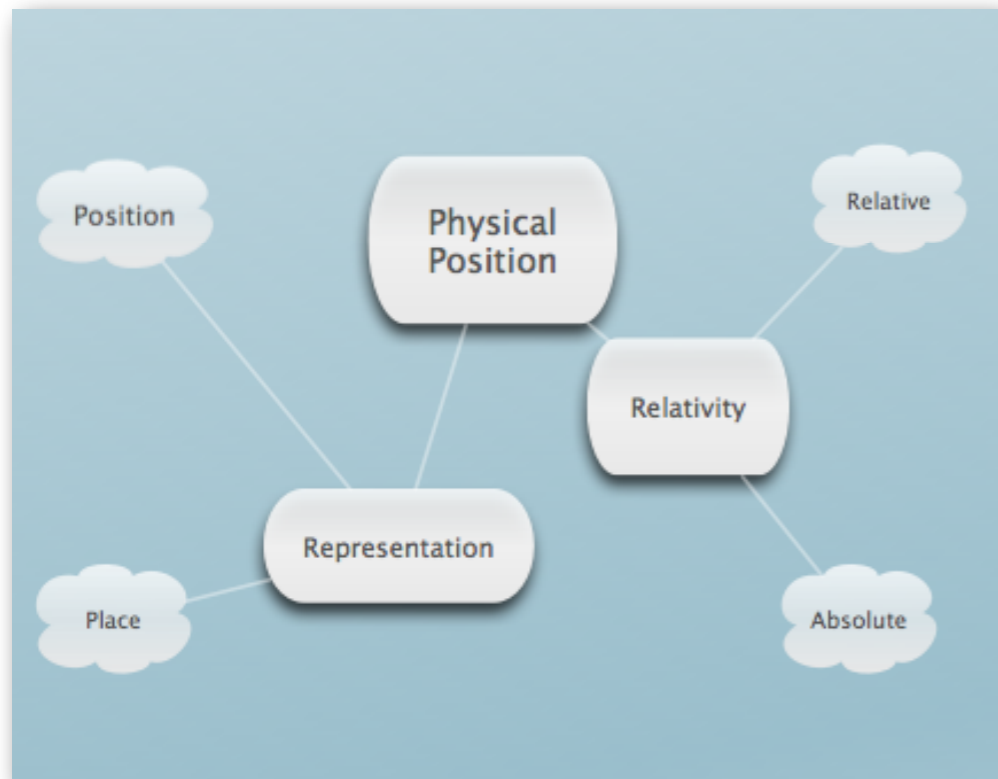
Properties of Location Systems



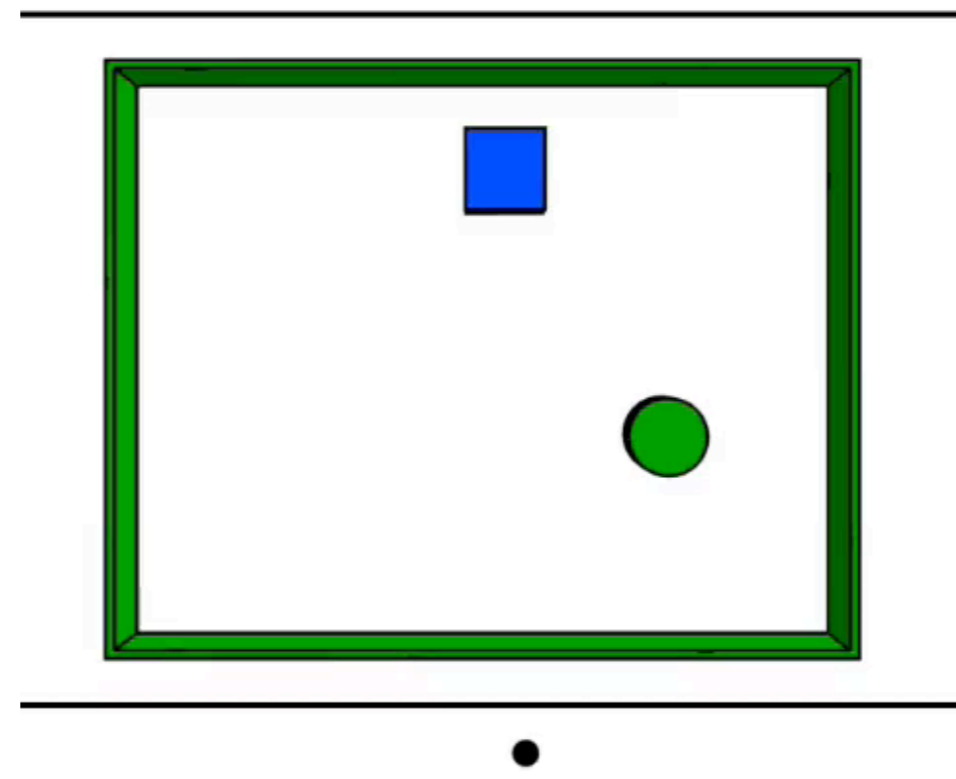
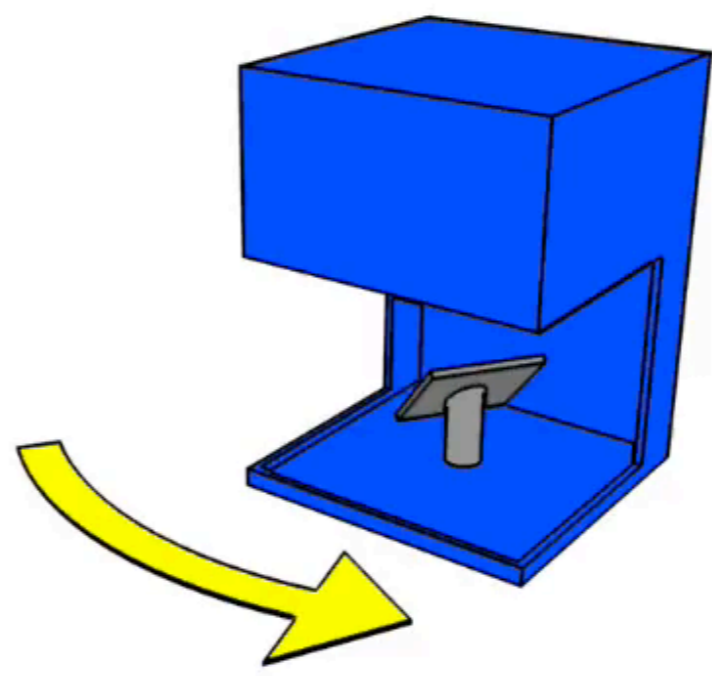
- Properties
 - Physical Position/Symbolic location
 - Position
 - Exact, Unambiguous, Machine friendly
 - Place
 - Inexact, Ambiguous, Human Friendly



Properties of Location Systems



- Properties
 - Absolute/Relative
 - GPS is absolute
 - Laser range finder is relative
 - Transforming between the two is possible with additional information



Properties of Location Systems

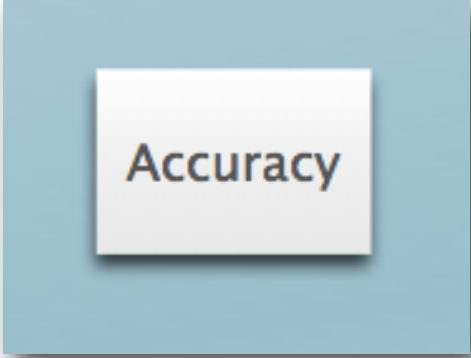


- Properties
 - Where is the computation done?
 - GPS locally - private, scalable
 - Cell-phone positioning - assisted, scalable to a degree, location is revealed
 - Broadcast ID-badge systems - localization is in infrastructure



Properties of Location Systems

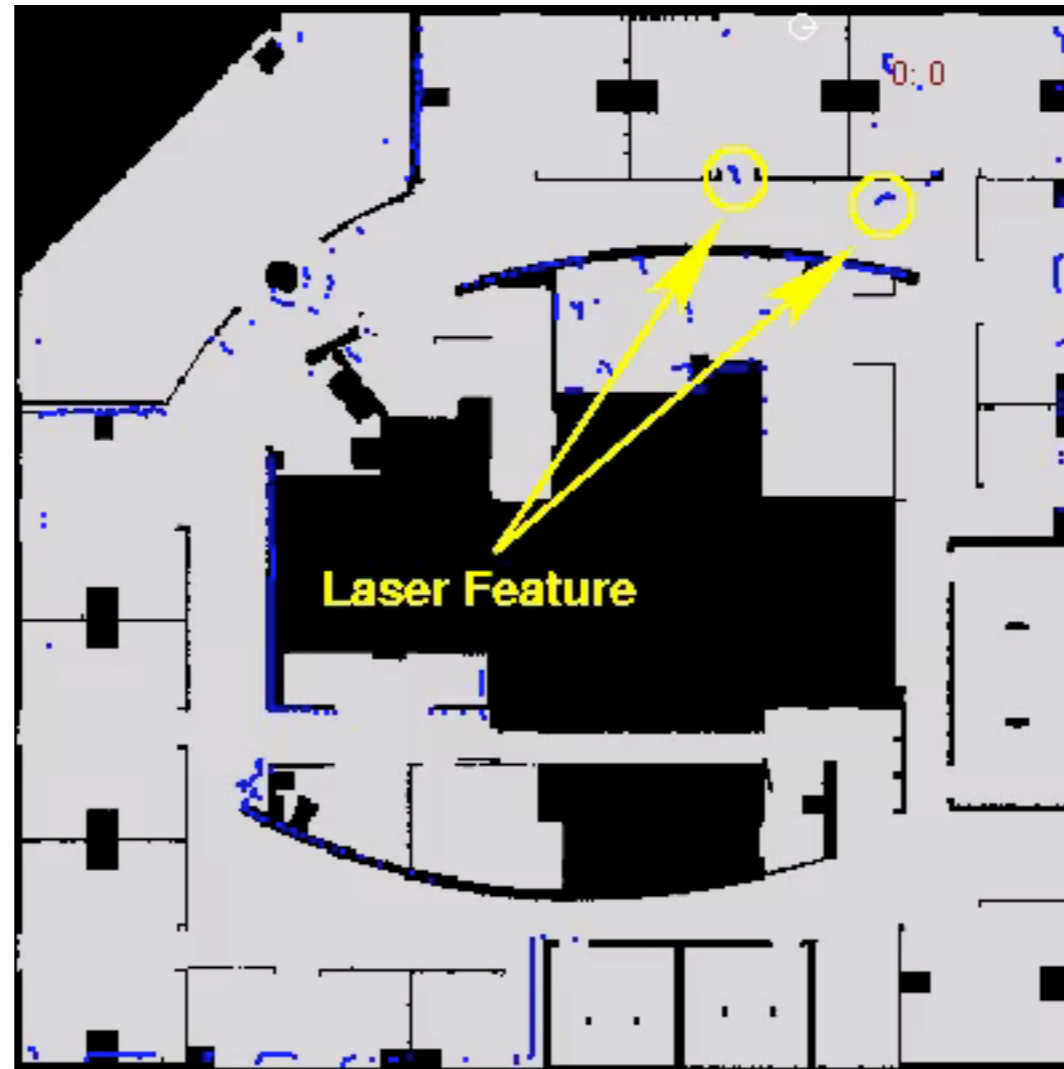
- Properties
 - Accuracy and precision
 - GPS 15m - 95% of the time
 - Sensor fusion tries to improve accuracy and/or precision by combining sensors
 - Accuracy and precision may change to conserve battery life.



Accuracy



Properties of Location Systems

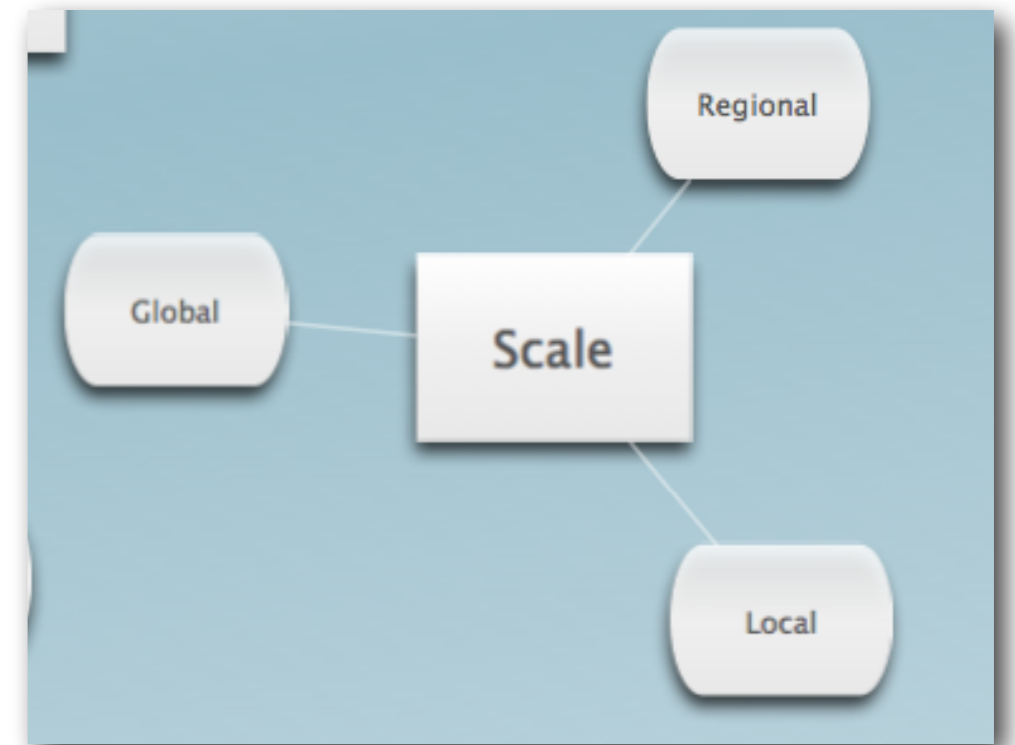


Properties of Location Systems



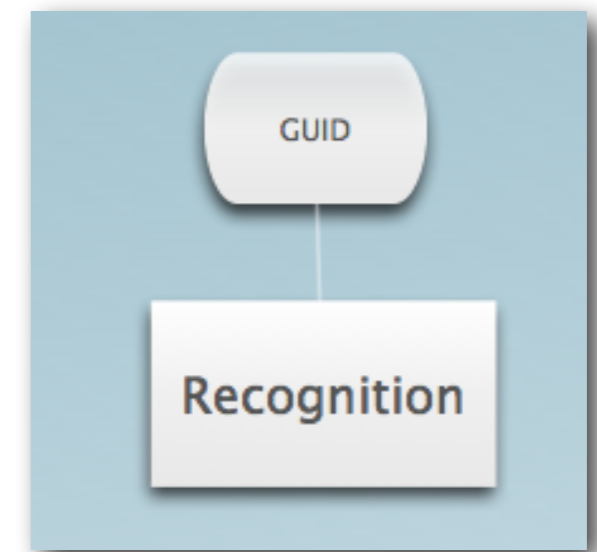
Properties of Location Systems

- Properties
 - Scale
 - Global, Regional, Local
 - GPS - Global
 - RFID Readers -local
 - Cell-phone localization regional



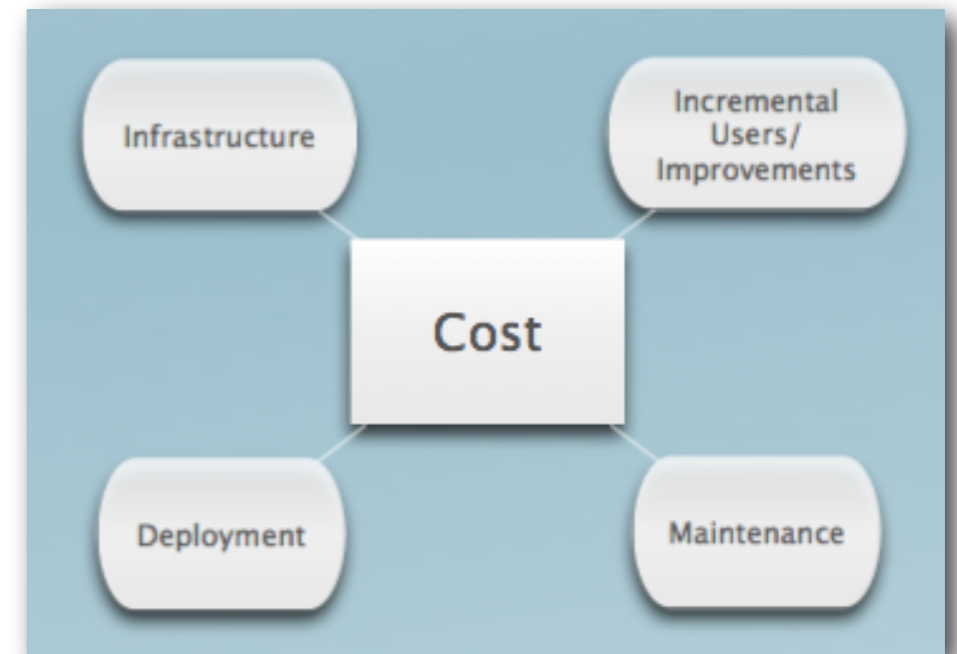
Properties of Location Systems

- Properties
 - Recognition
 - GUID - globally unique identifier
 - Do we know who or what you are?
 - GPS - no
 - Sensor fusion - maybe

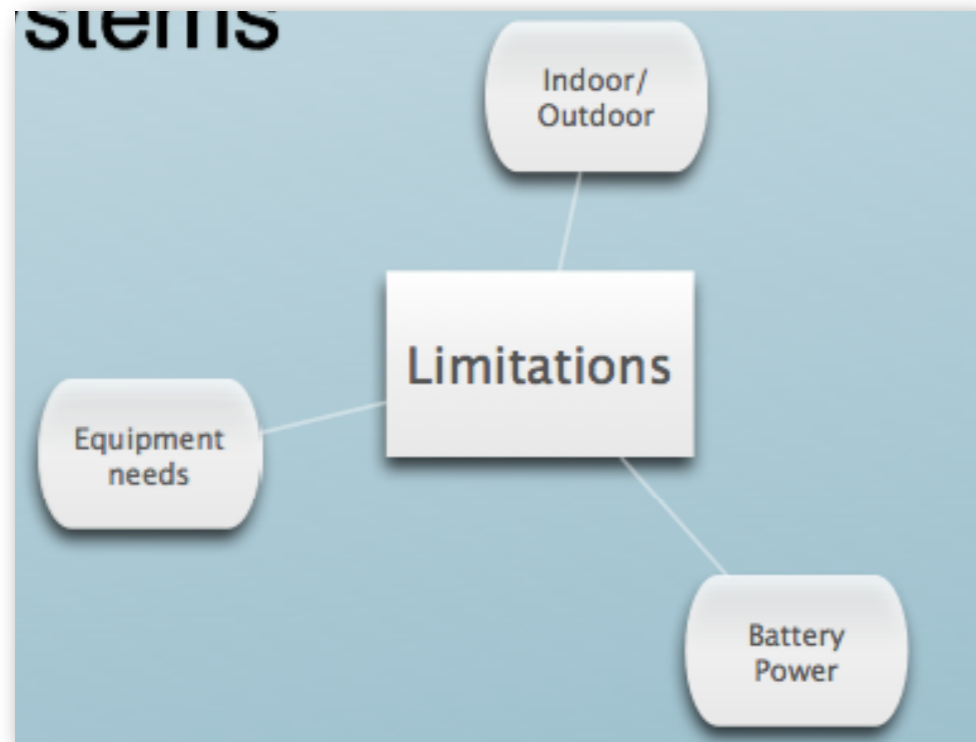


Properties of Location Systems

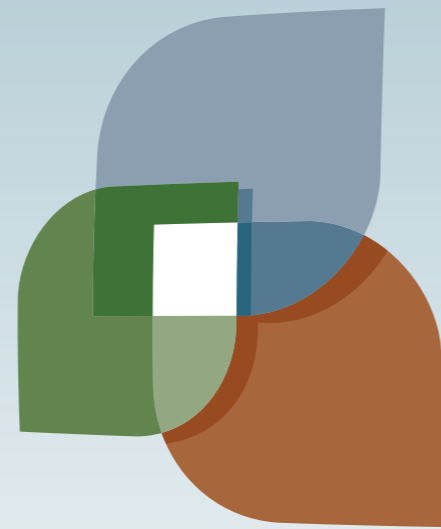
- Properties
 - Cost
 - Deployment
 - Infrastructure
 - Maintenance
 - Incremental Users or Improvements



Properties of Location Systems



- Properties
- Limitations
 - Indoor/ Outdoor
 - Battery Power
 - New Equipment



L U C I

