1. $\mathbf{3 0}$ points. Define each of the following terms (using at most 2 sentences each):
(a) convex hull,
(b) planar subdivision,
(c) trapezoidal decomposition.
2. 30 points. Describe an efficient method for finding the convex hull of $n$ points in the plane.

NOTE: For the remainder of this exam you may assume that you have a subroutine for any problem we discussed in class, provided you can correctly characterize its performance bounds.
3. 30 points. Describe an efficient algorithm for determining the width of a set $S$ of $n$ points in the plane. Recall that the width of a point set is the smallest distance between two parallel lines that contain the points of $S$ between them.
4. 30 points. Suppose you are given a set $S$ of $n$ line segments in the plane, such that each makes a positive angle with the $x$-axis of either $30^{\circ}$ or $60^{\circ}$ (so there are only two possible slopes for the lines in $S$ ). Sketch an efficient algorithm for finding all the pairs of intersecting segments in $S$. What is the running time of your method?
5. 30 points. Describe a dynamic data structure that can store a set of $n$ intervals in $\mathbf{R}$ that all have integer endpoints in the range $[1, N]$. Mention how your structure efficiently supports each of the following operations (hint: think of left and right endpoints separately):
(a) $\operatorname{Insert}([a, b])$ : insert a new interval $[a, b]$ to the set.
(b) Delete $([a, b])$ : remove a interval $[a, b]$ from the set.
(c) Outside $([a, b])$ : report all the intervals in the set that do not intersect $[a, b]$.

What is the running time for each method?

