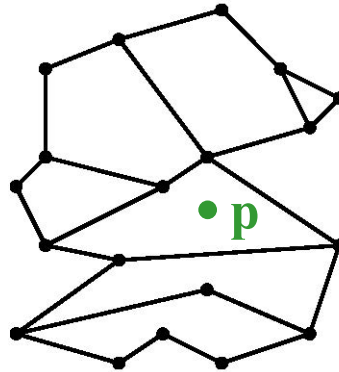


Computational Geometry



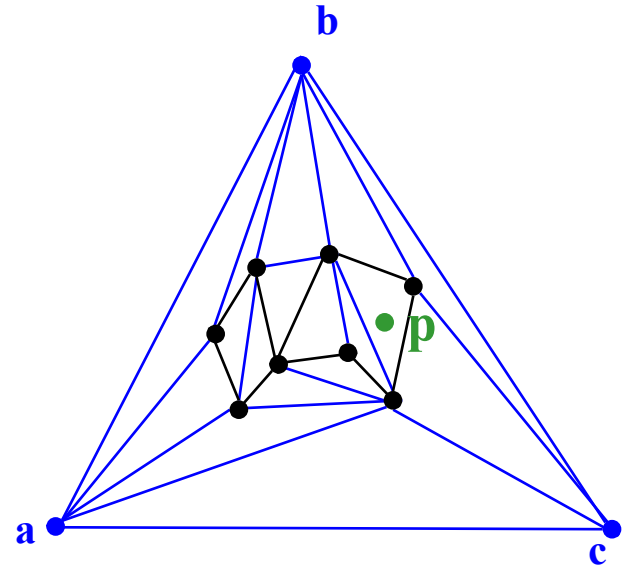
Kirkpatrick's Point Location Algorithm

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with slides from Carola Wenk

Kirkpatrick's Point Location Algorithm

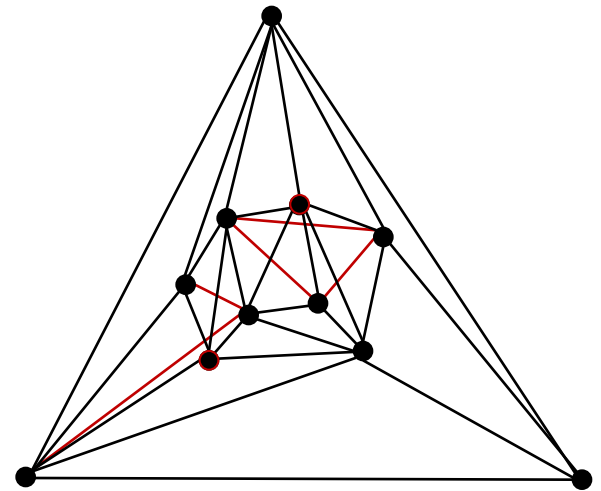
- Needs a triangulation as input.
- One can convert a planar subdivision with n vertices into a triangulation:
 - Triangulate each face, keep same label as original face.
 - If the outer face is not a triangle:
 - Compute the convex hull of the subdivision.
 - Triangulate pockets between the subdivision and the convex hull.
 - Add a large triangle (new vertices **a**, **b**, **c**) around the convex hull, and triangulate the space in-between.



- The size of the triangulated planar subdivision is still $O(n)$, by Euler's formula.
- The conversion can be done in $O(n)$ time.
- Given p , if we find a triangle containing p we also know the (label of) the original subdivision face containing p .

Kirkpatrick's Hierarchy

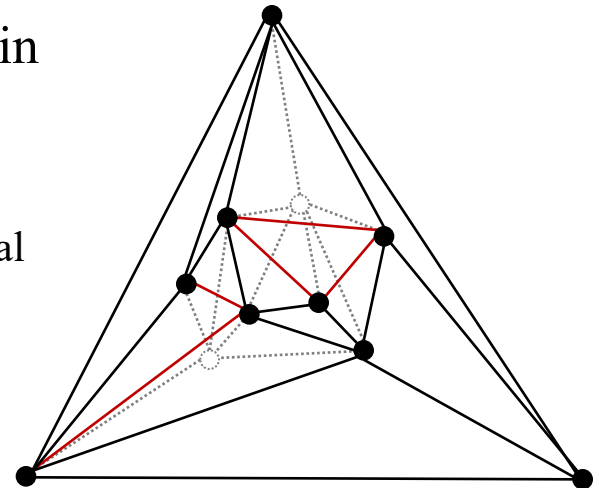
- Compute a sequence T_0, T_1, \dots, T_k of increasingly coarser triangulations such that the last one has constant complexity.
- The sequence T_0, T_1, \dots, T_k should have the following properties:
 - T_0 is the input triangulation, T_k is the outer triangle
 - $k \in O(\log n)$
 - Each triangle in T_{i+1} overlaps $O(1)$ triangles in T_i
- How to build such a sequence?
 - Need to delete vertices from T_i .
 - Vertex deletion creates holes, which need to be re-triangulated.
- How do we go from T_0 of size $O(n)$ to T_k of size $O(1)$ in $k=O(\log n)$ steps?
 - In each step, delete a constant fraction of vertices from T_i .
- We also need to ensure that each new triangle in T_{i+1} overlaps with only $O(1)$ triangles in T_i .



Vertex Deletion and Independent Sets

When creating T_{i+1} from T_i , delete vertices from T_i that have the following properties:

- **Constant degree:**
Each vertex v to be deleted has $O(1)$ degree in the graph T_i .
 - If v has degree d , the resulting hole can be re-triangulated with $d-2$ triangles
 - Each new triangle in T_{i+1} overlaps at most d original triangles in T_i
- **Independent sets:**
No two deleted vertices are adjacent.
 - Each hole can be re-triangulated independently.

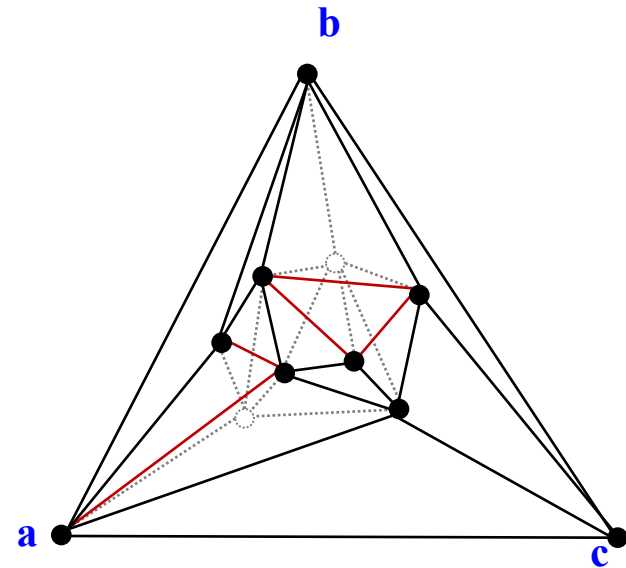


Independent Set Lemma

Lemma: Every triangulated planar graph on $n \geq 4$ vertices contains an independent vertex set of size $n/18$ in which each vertex has degree at most 8. Such a set can be computed in $O(n)$ time.

Use this lemma to construct Kirkpatrick's hierarchy:

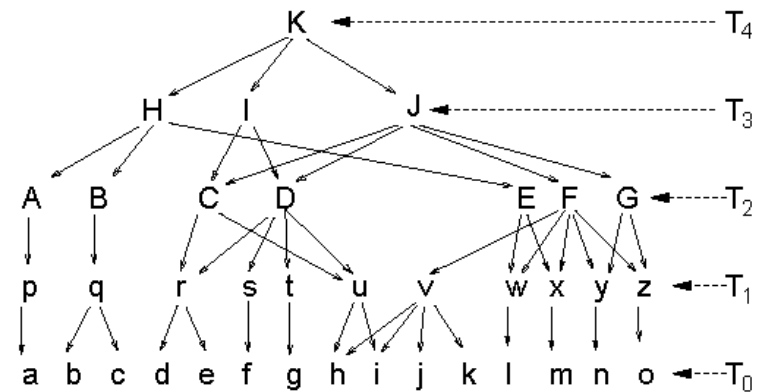
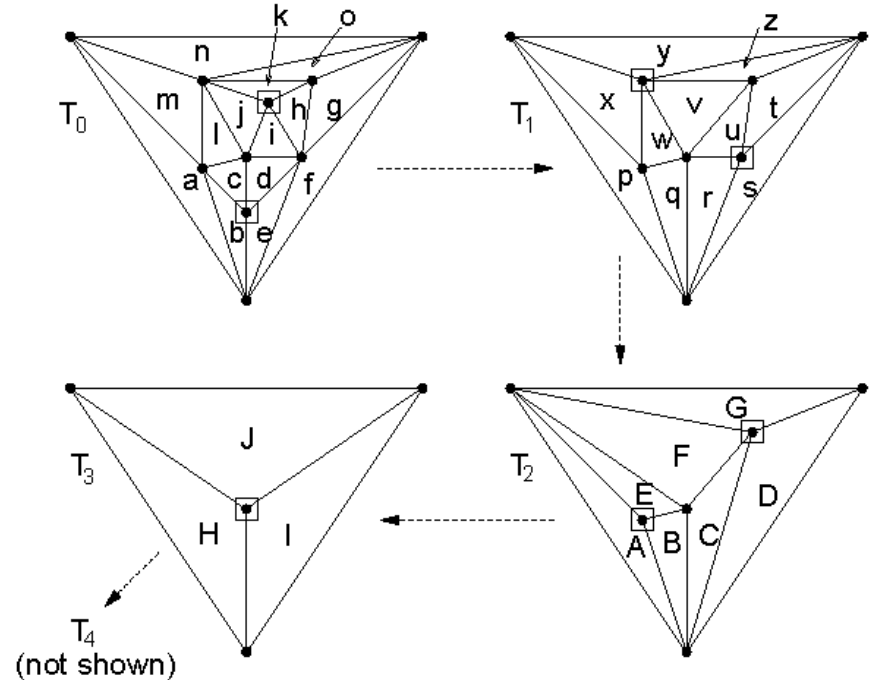
- Start with T_0 , and select an independent set S of size $n/18$ in which each vertex has maximum degree 8. [Never pick the outer triangle vertices a , b , c .]
- Remove vertices of S , and re-triangulate holes.
- The resulting triangulation, T_1 , has at most $17/18n$ vertices.
- Repeat the process to build the hierarchy, until T_k equals the outer triangle with vertices a , b , c .
- The depth of the hierarchy is $k = \log_{18/17} n$



Hierarchy Example

Use this lemma to construct Kirkpatrick's hierarchy:

- Start with T_0 , and select an independent set S of size $n/18$ in which each vertex has maximum degree 8. [Never pick the outer triangle vertices a, b, c .]
- Remove vertices of S , and re-triangulate holes.
- The resulting triangulation, T_1 , has at most $17/18n$ vertices.
- Repeat the process to build the hierarchy, until T_k equals the outer triangle with vertices a, b, c .
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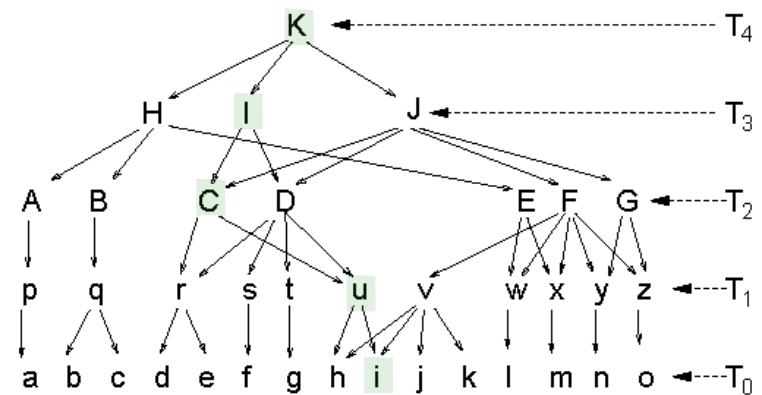
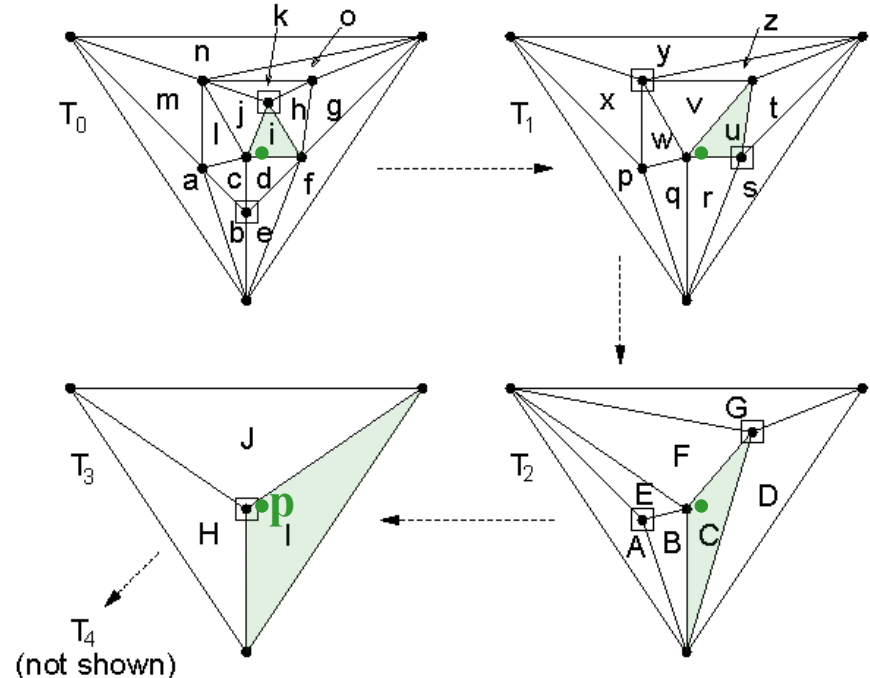
Hierarchy Data Structure

Store the hierarchy as a DAG:

- The root is T_k .
- Nodes in each level correspond to triangles T_i .
- Each node for a triangle in T_{i+1} stores pointers to all triangles of T_i that it overlaps.

How to locate point p in the DAG:

- Start at the root. If p is outside of T_k then p is in exterior face; done.
- Else, set Δ to be the triangle at the current level that contains p .
- Check each of the at most $6 = 8-2$ triangles of T_{k-1} that overlap with Δ , whether they contain p . Update Δ and descend in the hierarchy until reaching T_0 .
- Output Δ .



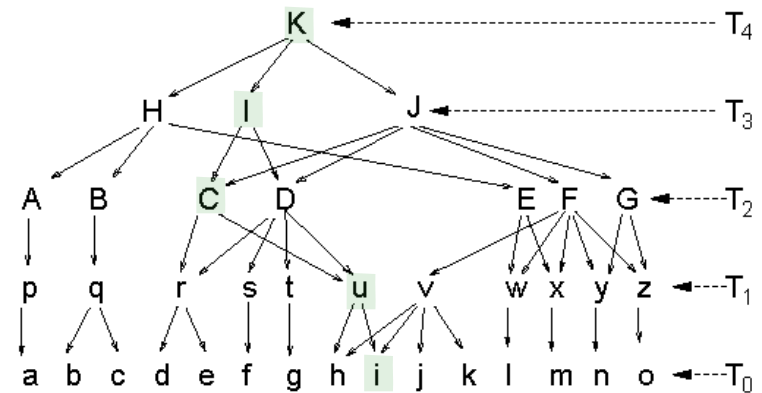
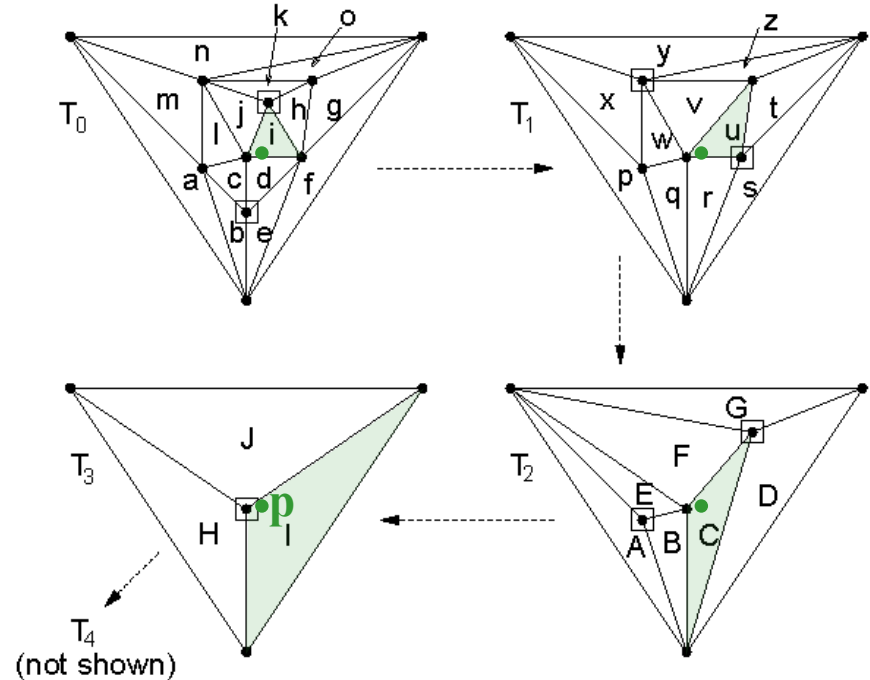
Analysis

- **Query time is $O(\log n)$:** There are $O(\log n)$ levels and it takes constant time to move between levels.

- **Space complexity is $O(n)$:**
 - Sum up sizes of all triangulations in hierarchy.
 - Because of Euler's formula, it suffices to sum up the number of vertices.
 - Total number of vertices:

$$\begin{aligned}
 & n + 17/18 n + (17/18)^2 n + (17/18)^3 n \\
 & + \dots \\
 & \leq 1/(1-17/18) n = 18 n
 \end{aligned}$$

- **Preprocessing time is $O(n \log n)$:**
 - Triangulating the subdivision takes $O(n \log n)$ time.
 - The time to build the DAG is proportional to its size.



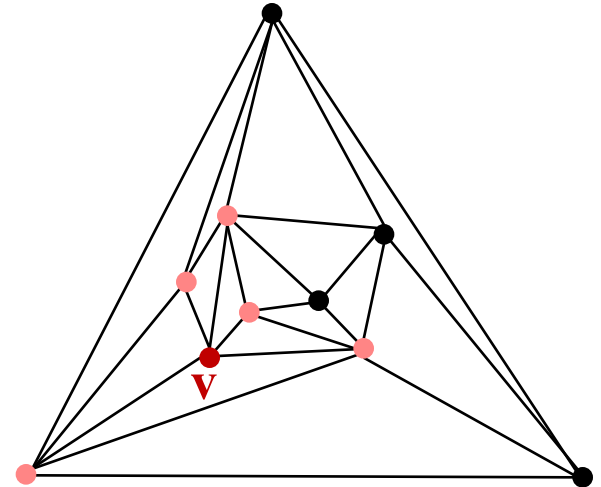
Independent Set Lemma

Lemma: Every triangulated planar graph on $n \geq 4$ vertices contains an independent vertex set of size $n/18$ in which each vertex has degree at most 8. Such a set can be computed in $O(n)$ time.

Proof:

Greedy algorithm to construct an independent set:

- Mark all vertices of degree ≥ 9
- While there is an unmarked vertex
 - Let v be an unmarked vertex
 - Add v to the independent set
 - Mark v and all its neighbors
- Can be implemented in $O(n)$ time: Keep list of unmarked vertices, and store the triangulation in a data structure (DCEL) that allows finding neighbors in $O(1)$ time.



Independent Set Lemma

Still need to prove existence of a *large* independent set.

- Euler's formula for a triangulated planar graph on n vertices:
 $\#edges = 3n - 6$

- Sum over vertex degrees:

$$\sum_v \deg(v) = 2 \#edges = 6n - 12 < 6n$$

- **Claim:** At least $n/2$ vertices have degree ≤ 8 .

Proof: By contradiction. So, suppose otherwise.

→ $n/2$ vertices have degree ≥ 9 . The remaining have degree ≥ 3 .

→ The sum of the degrees is $\geq 9 n/2 + 3 n/2 = 6n$. Contradiction.

- In the beginning of the algorithm, at least $n/2$ nodes are unmarked. Each picked vertex v marks ≤ 8 other vertices, so including itself 9.
- Therefore, the while loop can be repeated at least $n/18$ times.
- This shows that there is an independent set of size at least $n/18$ in which each node has degree ≤ 8 .



Summing Up

- Kirkpatrick's point location data structure needs $O(n)$ preprocessing time, $O(n)$ space, and has $O(\log n)$ query time.
- It involves high constant factors though. So this algorithm, while asymptotically optimal, is mostly of theoretical interest.

