Machine Learning and Data Mining

Clustering

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Unsupervised learning

- Supervised learning
 - Predict target value ("y") given features ("x")
- Unsupervised learning
 - Understand patterns of data (just "x")
 - Useful for many reasons
 - Data mining ("explain")
 - Missing data values ("impute")
 - Representation (feature generation or selection)
- One example: *clustering*



Clustering and Data Compression

- Clustering is related to vector quantization
 - Dictionary of vectors (the cluster centers)
 - Each original value represented using a dictionary index
 - Each center "claims" a nearby region (Voronoi region)





Hierarchical Agglomerative Clustering

Initially, every datum is a cluster



- Another simple clustering algorithm
- Define a distance between clusters (return to this)
- Initialize: every example is a cluster
- Iterate:
 - Compute distances between all clusters (store for efficiency)
 - Merge two closest clusters
- Save both clustering and sequence of cluster operations
- "Dendrogram"

Iteration 1





Iteration 2





Iteration 3

 Builds up a sequence of clusters ("hierarchical")





 Algorithm complexity O(N²) (Why?)

In matlab: "linkage" function (stats toolbox)

Dendrogram





Example: microarray expression

- Measure gene expression
- Various experimental conditions
 - Cancer, normal
 - Time
 - Subjects
- Explore similarities
 - What genes change together?
 - What conditions are similar?
- Cluster on both genes and conditions



K-Means Clustering

- A simple clustering algorithm
- Iterate between
 - Updating the assignment of data to clusters
 - Updating the cluster's summarization
- Suppose we have K clusters, c=1..K
 - Represent clusters by locations ¹_c
 - Example i has features x_i
 - Represent assignment of ith example as z_i in 1..K
- Iterate until convergence:
 - For each datum, find the closest cluster

$$z_i = \arg\min_c \|x_i - \mu_c\|^2 \qquad \forall i$$

- Set each cluster to the mean of all assigned data:

$$\forall c, \qquad \mu_c = \frac{1}{N_c} \sum_{i \in S_c} x_i$$

$$S_c = \{i : z_i = c\}, \ N_c = |S_c|$$

Choosing the number of clusters

With cost function

$$C(\underline{z},\underline{\mu}) = \sum_{i} \|x_i - \mu_{z_i}\|^2$$

what is the optimal value of k? (can increasing k ever increase the cost?)

- This is a model complexity issue
 - Much like choosing lots of features they only (seem to) help
 - But we want our clustering to generalize to new data
- One solution is to penalize for complexity
 - Bayesian information criterion (BIC)
 - Add (# parameters) * log(N) to the cost
 - Now more clusters can increase cost, if they don't help "enough"



Scree is a loose accumulation of broken rock at the base of a cliff or mountain.

Mixtures of Gaussians

- K-means algorithm
 - Assigned each example to exactly one cluster
 - What if clusters are overlapping?
 - Hard to tell which cluster is right
 - Maybe we should try to remain uncertain
 - Used Euclidean distance
 - What if cluster has a non-circular shape?
- Gaussian mixture models
 - Clusters modeled as Gaussians
 - Not just by their mean
 - EM algorithm: assign data to cluster with some *probability*



Multivariate Gaussian models

$$\mathcal{N}(\underline{x} \; ; \; \underline{\mu}, \Sigma) = \frac{1}{(2\pi)^{d/2}} |\Sigma|^{-1/2} \exp\left\{-\frac{1}{2}(\underline{x} - \underline{\mu})^T \Sigma^{-1}(\underline{x} - \underline{\mu})\right\}$$



Maximum Likelihood estimates

$$\hat{\mu} = \frac{1}{N} \sum_{i} x^{(i)}$$
$$\hat{\Sigma} = \frac{1}{N} \sum_{i} (x^{(i)} - \hat{\mu})^T (x^{(i)} - \hat{\mu})$$

We'll model each cluster using one of these Gaussian "bells"...

EM Algorithm: E-step

- Start with parameters describing each cluster
- Mean μ_c , Covariance Σ_c , "size" π_c
- E-step ("Expectation")
 - For each datum (example) x_i,
 - Compute "r_{ic}", the probability that it belongs to cluster c
 - Compute its probability under model c
 - Normalize to sum to one (over clusters c)

$$r_{ic} = \frac{\pi_c \mathcal{N}(x_i \; ; \; \mu_c, \Sigma_c)}{\sum_{c'} \pi_{c'} \mathcal{N}(x_i \; ; \; \mu_{c'}, \Sigma_{c'})}$$

- If x_i is very likely under the cth Gaussian, it gets high weight
- Denominator just makes r's sum to one

EM Algorithm: M-step

- Start with assignment probabilities r_{ic}
- Update parameters: mean μ_c , Covariance Σ_c , "size" π_c
- M-step ("Maximization")
 - For each cluster (Gaussian) x_c,
 - Update its parameters using the (weighted) data points

$$N_c = \sum_i r_{ic}$$
 Total responsibility allocated to cluster c
 $\pi_c = \frac{N_c}{N}$ Fraction of total assigned to cluster c

$$\mu_c = \frac{1}{N_c} \sum_i r_{ic} x_i$$

Weighted mean of assigned data

$$\Sigma_c = \frac{1}{N_c} \sum_i r_{ic} (x_i - \mu_c)^T (x_i - \mu_c)$$

Weighted covariance of assigned data (use new weighted means here)

Expectation-Maximization

Each step increases the log-likelihood of our model

$$\log p(\underline{X}) = \sum_{i} \log \left[\sum_{c} \pi_{c} \mathcal{N}(x_{i} ; \mu_{c}, \Sigma_{c}) \right]$$

(we won't derive this, though)

- Iterate until convergence
 - Convergence guaranteed another ascent method
- What should we do
 - If we want to choose a single cluster for an "answer"?
 - With new data we didn't see during training?





EM ITERATION 1







EM ITERATION 10



EM ITERATION 15



LOG-LIKELIHOOD AS A FUNCTION OF EM ITERATIONS



Summary

- Clustering algorithms
 - Agglomerative clustering
 - K-means
 - Expectation-Maximization
- Open questions for each application
- What does it mean to be "close" or "similar"?
 - Depends on your particular problem...
- "Local" versus "global" notions of similarity
 - Former is easy, but we usually want the latter...
- Is it better to "understand" the data itself (unsupervised learning), to focus just on the final task (supervised learning), or both?