

# Load balancing on a heterogeneous cluster.

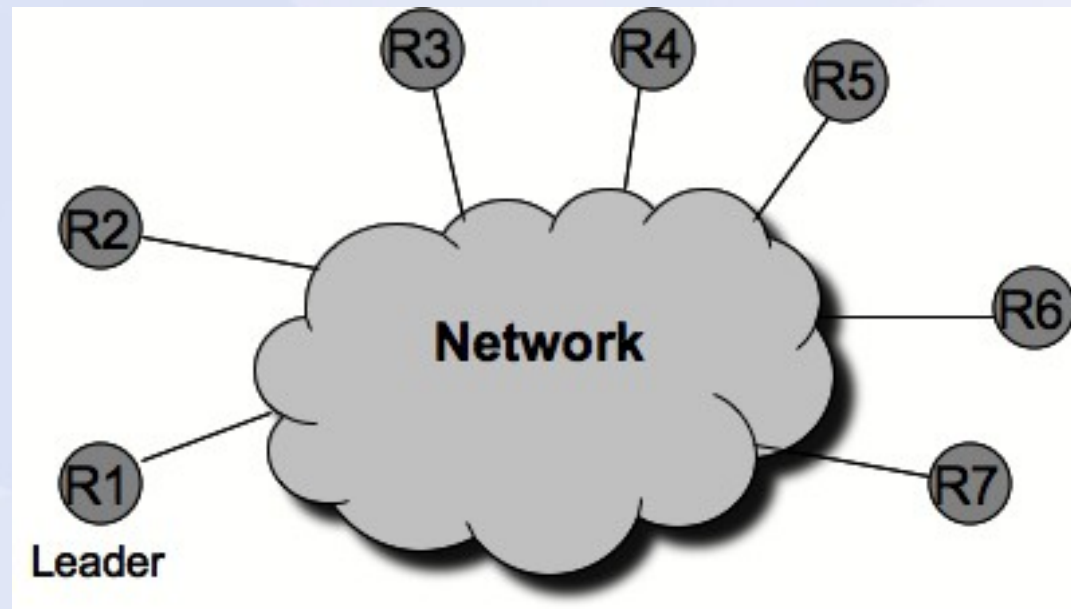
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# **Dynamic Load-Balancing on Heterogeneous Clusters.**

An extension of the PhD dissertation work of  
John Duselis, under Isaac Scherson.

# Heterogeneous Cluster Connected Via Network



# An Heterogeneous Cluster

Each resource  $i$  is represented by its Performance Vector (PV):

$$P_i = \begin{pmatrix} r_1 \\ r_2 \\ \cdot \\ \cdot \\ \cdot \\ r_m \end{pmatrix}$$

- CPU
- Memory
- GPU
- HDD
- Bandwidth
- Et cetera

# The tasks

A task T represents a computation to execute.

Define K distinct classes of tasks. Membership of a task to a class is determined by a classifier (not covered here).

A class k is defined by its resources requirements:

$$K_i = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \cdot \\ \cdot \\ \cdot \\ \beta_m \end{pmatrix}$$

# Execution Times

Thus, an approximation to the time taken by resource  $i$  to execute a task of class  $k$  is:

$$TaskExecutionTime = \max_j \left( \frac{T_k[j]}{P_i[j]} \right) \text{ for all } j = 1, \dots, m$$

And an approximation to the time taken by resource  $i$  to execute all its assigned task:

$$ExecutionTime = \sum_k N_{i,k} \max_j \left( \frac{T_k[j]}{P_i[j]} \right) \text{ for each } j = 1, \dots, m$$

Where  $N_{i,k}$  denotes the number of tasks of class  $k$  assigned to  $i$ .

# Assignment of Tasks

N task are to be assigned. Each task belongs to a class k. Let:

I : Task is assigned to server i.

K: Task is of type k.

$$\begin{aligned}x_{i,k} &= \text{Prob}(I|K) \\ &= \frac{\text{Prob}(I, K)}{\text{Prob}(K)}\end{aligned}$$

$$\text{Prob}(I, K) = x_{i,k} \text{Prob}(K)$$

Note that the conditional probability of assigning N tasks of class k to a server i follows a multinomial probability

# Expected Execution Times

The expected execution time for a server  $i$  is:

$$E[ExecutionTime] = E \left[ \sum_k N_{i,k} \max_j \left( \frac{T_k[j]}{P_i[j]} \right) \right]$$

$$= \sum_k E[N_{i,k}] \max_j \left( \frac{T_k[j]}{P_i[j]} \right)$$

$$= \sum_k N x_{i,k} Prob(K=k) \max_j \left( \frac{T_k[j]}{P_i[j]} \right)$$

Since  $N_{i,k}$  is Multinomial, its expected value is  $(N Prob(i,K))$



# Total Execution Time

Assuming p.d.f of  $K$  is known, then:

$$Prob(K=k) \max_j \left( \frac{T_k[j]}{P_i[j]} \right) = q_{i,k}$$

...which is a constant value.

Total system execution time is:

$$= \max_i \left( \sum_k x_{i,k} Prob(K=k) \max_j \left( \frac{T_k[j]}{P_i[j]} \right) \right)$$

$$= \max_i \left( \sum_k x_{i,k} q_{i,k} \right)$$

= Time of last server to finish

# Problem Formulation

$$X' = \begin{pmatrix} x_{1,1} & x_{2,1} & \dots & x_{s,1} \\ \dots & \dots & \dots & \dots \\ x_{1,s} & x_{2,s} & \dots & x_{s,k} \end{pmatrix}$$

$X_i = \text{the } i\text{th column vector of } X'$

$$Q = \begin{pmatrix} q_{1,1} & q_{2,1} & \dots & q_{s,1} \\ \dots & \dots & \dots & \dots \\ q_{1,s} & q_{2,s} & \dots & q_{s,k} \end{pmatrix}$$

$Q_i = \text{the } i\text{th column vector of } Q$

$$X = \begin{pmatrix} x_{1,1} \\ \dots \\ x_{1,s} \\ x_{2,1} \\ \dots \\ x_{2,s} \\ \dots \\ x_{1,s} \\ \dots \\ x_{k,s} \end{pmatrix}$$

# Minimization Problem

$$\operatorname{argmin}_X \max_i \left( X_i C_i^T \right)$$

Subject to:

$$X_{i,k} \geq 0$$

$$J_{i,k} X_i = 1$$

# Minimization Problem

$$\operatorname{argmin}_X t$$

Subject to:

$$X_i C_i^T - t \leq 0$$

$$-X_{i,k} \leq 0$$

$$J_{i,k} X_i - 1 = 0$$

# KKT Conditions

$$P_i C_i^T \leq t$$

$$P_{i,k} \geq 0$$

$$J_{i,k} P_i = 1$$

$$\lambda_i \geq 0$$

$$-\lambda_{i',k} P_{i,k} = 0$$

$$\lambda_i C_i^T - \lambda_{i',k} 1 + \nu J_{i,k} = 0$$

# Accounting for Variance

Assume that:

$$Y_{i,k} := \max_j \left( \frac{T_k[j]}{P_i[j]} \right) \text{ be a random variable.}$$

From previous problem we know:

$$ExecutionTime = \sum_k N_{i,k} \max_j \left( \frac{T_k[j]}{P_i[j]} \right)$$

$$Var[ExecutionTime] = Var \left[ \sum_k N_{i,k} Y_{i,k} \right]$$

# Accounting for Variance

$$\text{Var}[ExecTime] = E[Y^2](N^2 p^2 + Np(1-p)) + E[Y]^2(Np(1-p) - N^2 p^2)$$

Is a quadratic convex function, let's denote this by:

$$V(i)$$

(Variance in execution time for server i)

# New Minimization Problem

$$\operatorname{argmin}_X \max_i \left( X_i C_i^T + s V(i) \right)$$

Subject to:

$$-X_{i,k} \leq 0$$

$$J_{i,k} X_i - 1 = 0$$

Where  $s$  is a parameter to be found using training set. Where  $s \geq 0$



# New Minimization Problem

$$\operatorname{argmin}_X t$$

Subject to:

$$X_i C_i^T + s V(i) - t \leq 0$$

$$-X_{i,k} \leq 0$$

$$J_{i,k} X_i - 1 = 0$$

This is a Quadratically Constrained Quadratic Program (QCQP).