

COMPSCI 276
Homework Assignment 6
Spring 2017

Instructor: Rina Dechter

Due: Wednesday, May 24th

Relevant reading: Class notes (Dechter chapter 6-7 and chapter 8) and Darwiche chapter 15.

1. (5) Please provide comments and typos for chapter 8 (provided in the course schedule).
2. This question investigates the AND/OR search space of the network in Figure 1, assuming each variable has 2 values in its domain. The CPTs are given in Figure 2. The CPTs for G , H and D are identical to the 3-dimensional CPT in Figure 2 and the CPTs for C and F are identical to the two-dimensional CPT in that figure.

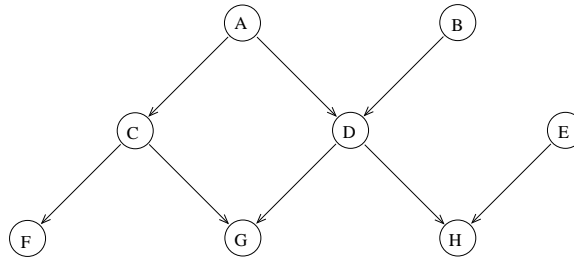


Figure 1: A directed graph

- (a) (5) Find and present a pseudo tree of the network in Figure 1 whose depth is minimal (do the best you can). Call this tree T_1 .
- (b) (10) Generate an AND/OR search tree driven by T_1 assuming each variable has at most two values.
- (c) (5) Annotate the arcs with the appropriate weights.
- (d) (10) What would be the computational cost of computing the probability of evidence $G = 0$ and $H = 1$ in such a network if you use depth-first search over the AND/OR search tree. Demonstrate the computation (compute the value of each node)
- (e) (5) Can the AND/OR search tree be reduced to a smaller AND/OR search graph? if so, demonstrate.
- (f) (5) Compare the time and space complexity of solving this problem by search with context-based caching vs bucket-elimination.
- (g) (10) Assume that the CPT $P(x|y, z)$ is changed by making some entries deterministic, as follows: set the probability column of the first 2 lines to 1 and 0 in that order (from top to bottom). Do the same for the last 2 lines (e.g., we make $P(x = 0|y = 1, z = 1) = 1$). Show what would be the changes in the AND/OR search tree as a result.

a	$p(a)$	b	$p(b)$	e	$p(e)$
0	0.3	0	0.6	0	0.7
1	0.7	1	0.4	1	0.3

z	y	x	$p(x y, z)$
0	0	0	0.25
0	0	1	0.75
0	1	0	0.60
0	1	1	0.40
1	0	0	0.10
1	0	1	0.90
1	1	0	0.20
1	1	1	0.80

y	x	$p(x y)$
0	0	0.10
0	1	0.90
1	0	0.30
1	1	0.70

Figure 2: Conditional probability tables

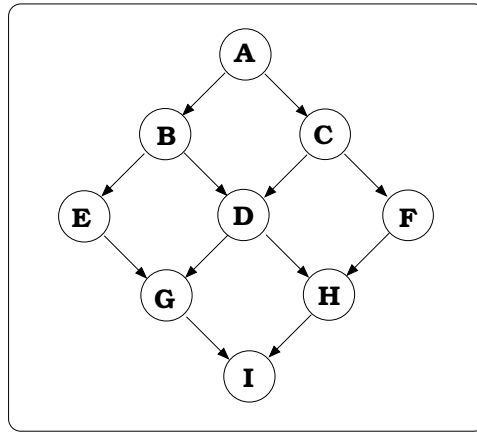


Figure 3: A Bayesian network

3. Consider the Bayes network DAG in Figure 3:

- (10) Discuss the performance of the bucket-elimination algorithm for finding the belief of $P(A|I = 0)$. Demonstrate its performance schematically (describe algebraically what function is computed in each bucket). What would be the complexity of the algorithm?
- (10) Apply the approximation algorithm $\text{mbe-bel}(i=3)$ for the task of finding the belief in A . Trace the algorithm's performance schematically (show functions, no numbers). What is the time and space complexity of the algorithm?
- Apply the weighted mini-bucket algorithm $\text{wmbe-bel}(i=3)$ with uniform weights for the task of finding the belief in A . Trace the algorithm's performance schematically (show functions, no numbers). What is the time and space complexity of the algorithm?
- (10) Apply $\text{mbe-mpe}(i=3)$ to find an upper bound for the mpe of the network given evidence $I = 0$. Trace the algorithms. Show how you construct an approximate mpe tuple.
- (10) Propose a node duplication simplification for the network that will correspond to the mini-bucket scheme you used in your answer above.

4. (20) Consider the coding networks in the class notes in chapter 8 (figure 8.7),

- (a) What is the relaxed network, generated by variable duplication that would correspond to the mini-bucket execution of this example. Draw the relaxed network.
- (b) Apply schematically, mini-clustering to find the belief of each variable. Show the tree-decomposition over which the mini-clustering algorithm executes.