

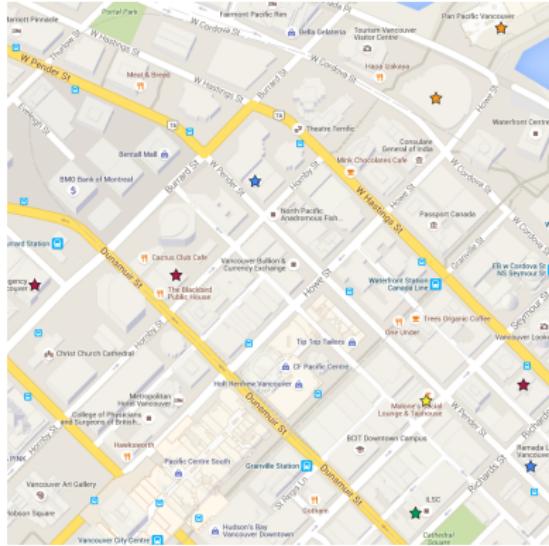
# **Maximizing the Sum of Radii of Disjoint Balls or Disks**

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(CCCG 2016)

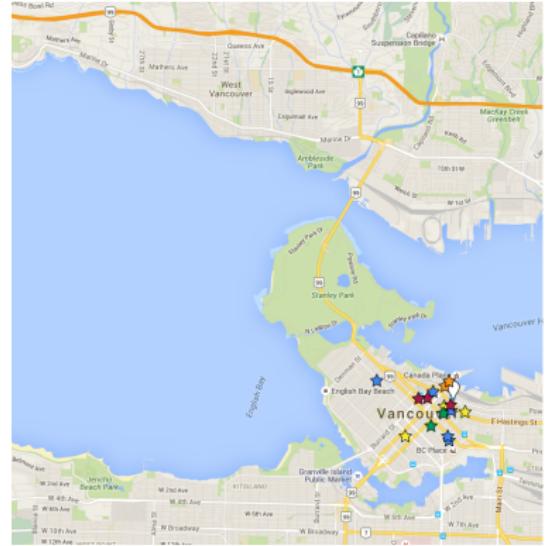
Vancouver, Canada, August 2016

# Tradeoff in label size for map labeling



Too small: hard to find among other features

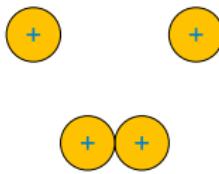
Depends on *local density* more than absolute size



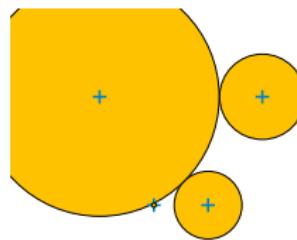
Too big: overlap each other, difficult to separate

# Goal: Find maximum feasible label size

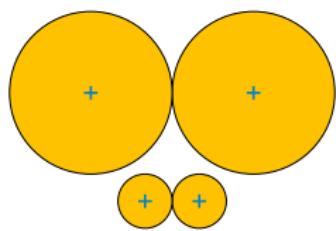
Formally: Place non-overlapping circles with given centers, maximizing some objective function. But what to maximize?



Max min radius:  
easy (min dist/2)  
but too global (one  
close pair makes all  
circles small)



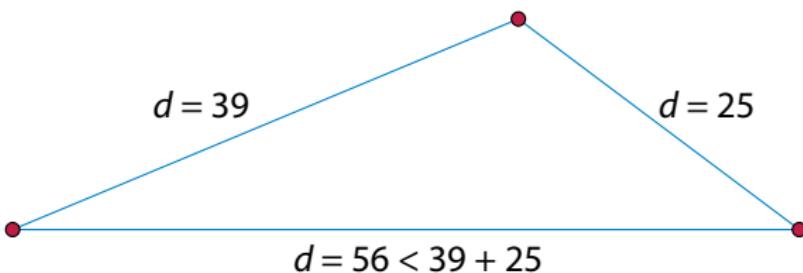
Max total area:  
too unbalanced,  
leads to zero-radius  
circles



**Max sum of radii:**  
connected circles  
can stay balanced,  
disconnected circles  
vary independently

## Detour through abstract metric spaces

Metric space: points with a symmetric non-negative distance function that obeys the triangle inequality: a shortest path from  $x$  to  $y$  is never longer than a path from  $x$  to  $y$  passing through  $z$



Example: Any finite set of points in  $\mathbb{R}^2$  and their distances

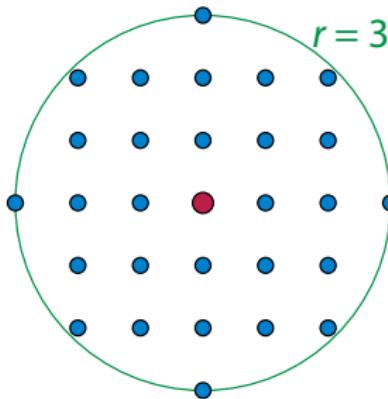
## Metric balls and when they overlap

Wrong definition: Ball = {points within distance  $r$  of center}

Balls overlap when their intersection is nonempty

Difficult to use computationally

Changes when you embed the space into one with more points



Right definition: Ball = pair (center, radius)

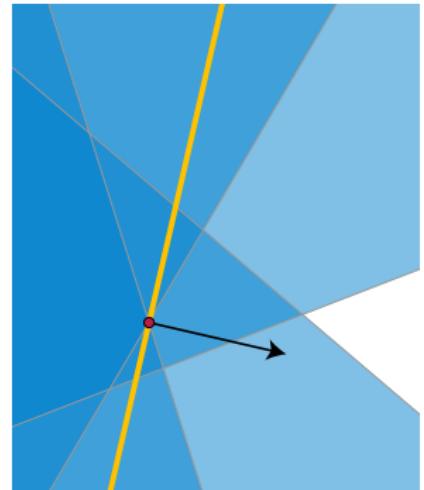
Balls overlap when sum of radii > distance of centers

# Metric radius-sum maximization

Given a finite metric space  $(X, d)$   
(the circle centers and their distances):

- ▶ Choose a radius  $r_i \geq 0$  for each center  $x_i$  in  $X$
- ▶ Obey non-overlapping circle constraints  $r_i + r_j \leq d(x_i, x_j)$
- ▶ Maximize  $\sum r_i$

This is a linear program!



. . . but does it have a combinatorial solution?

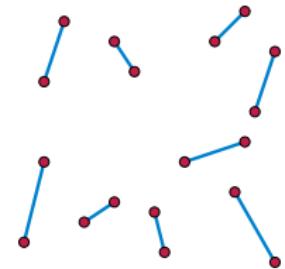
## Linear programming duality

Every linear program has a *dual* with:

- ▶ a variable for each primal constraint
- ▶ a constraint for each primal variable
- ▶ the same solution value

Our linear program's dual is:

- ▶ Find a weight  $w_{ij} \geq 0$  for each pair  $(i, j)$
- ▶ With each point  $x_i$  having total weight  $\sum_j w_{ij} \geq 1$
- ▶ Minimizing  $\sum_{i,j} w_{ij} d(x_i, x_j)$



This is the LP relaxation of minimum-length perfect matching on the complete graph of the given center points

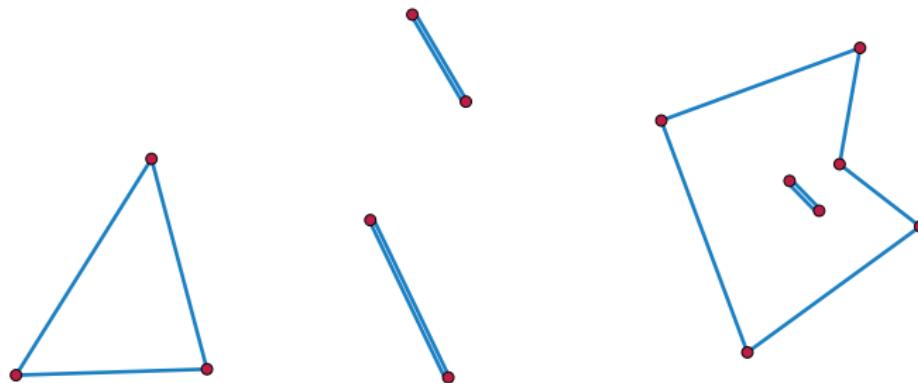
Matching: all weights  $w_{ij}$  are 0 or 1; matched edges have weight 1

Relaxation: optimal weights may be 0, 1, or 1/2

## What the dual of our LP actually solves

Choose  $2w_{ij}$  edges between each pair of points  $(x_i, x_j)$

The result is the minimum-length 2-regular multigraph over  $K_n$   
(a partition of the vertices into odd cycles and 2-cycles)

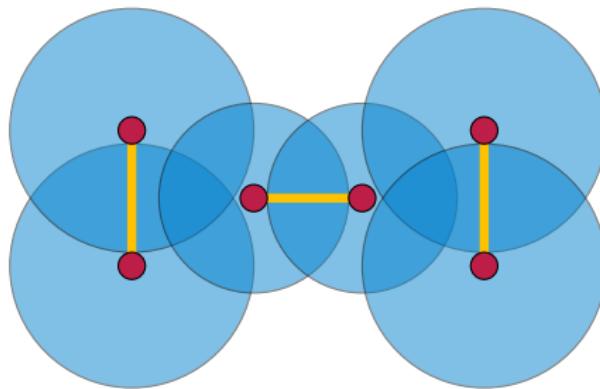


Equivalent (up to unimportant choice of orientation for  $>2$ -cycles)  
to minimum-length matching of the *bipartite double cover*  
 $K_2 \times K_n$ , a graph with two vertices for each input point  $x_i$

## From matching back to optimal radii

Most bipartite matching algorithms are *primal-dual*, giving both matched edges and variables of the dual of the LP relaxation

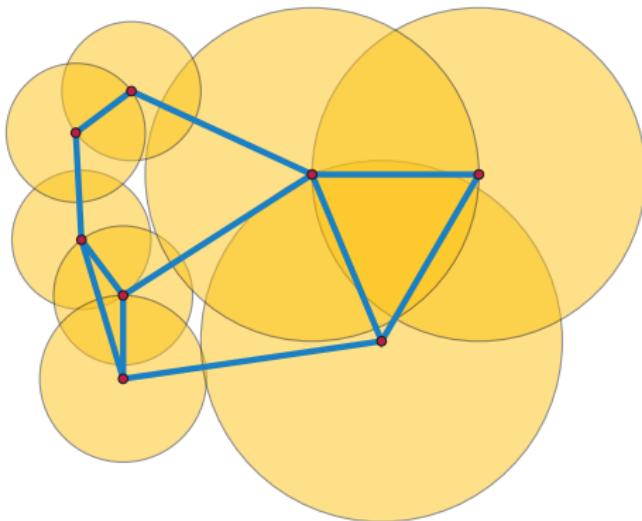
Applying this to matching on  $K_2 \times K_n$  gives us two dual variables per vertex: radii of red and blue circles such that each red-blue pair with different centers are non-overlapping



Averaging these two variables gives one optimal radius per center

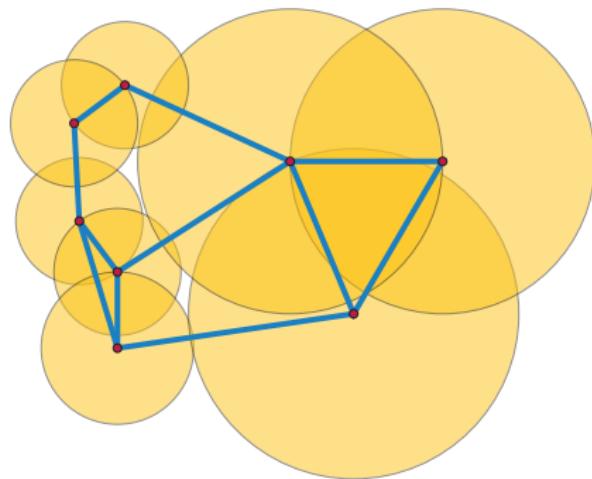
## A better graph than the complete graph

We need a supergraph of the optimal 2-regular multigraph  
...but it doesn't need to be the complete graph



Instead, use intersection graph of  
balls with radius = nearest neighbor distance

## Properties of nearest-neighbor intersection graph



- ▶ Smallest disk intersects  $O(1)$  others
- ▶  $\# \text{edges} = O(n)$
- ▶ *Separator theorem:* split into constant-factor-smaller pieces by removing  $O(n^{1-1/d})$  disks
- ▶ Can be constructed in time  $O(n \log n)$  (for constant  $d$ )

## Separator-based weighted bipartite matching

- ▶ Construct separator hierarchy
- ▶ With separator hierarchy already constructed, shortest paths take linear time [Henzinger et al., JCSS 1997]
- ▶ Recursively solve weighted matching for two subgraphs whose intersection is separator and whose union is the whole graph
- ▶ For each separator vertex, set dual variable to min from two subproblems and keep matched edge from that subproblem
- ▶ Use fast shortest path algorithm to find augmenting paths ( $\leq 1$  per separator vertex) until no more can be found

$$\text{Time} = \text{separator size} \times O(n)$$

Shaves a log from best published bound by Lipton & Tarjan (1980)

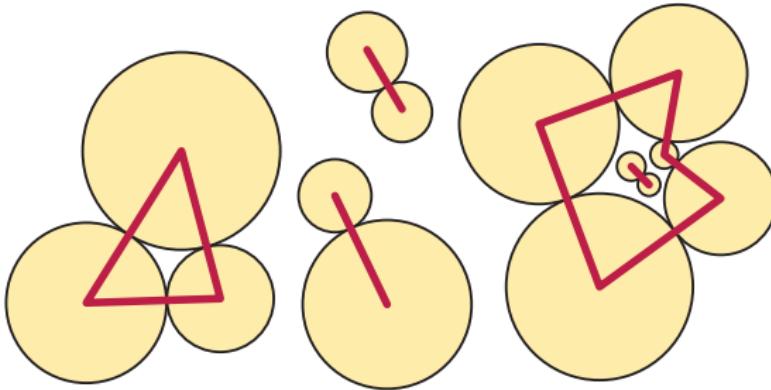
Computes dual variables, not just the matching itself

## Putting it all together

Weighted matching on  $K_2 \times$  nearest-neighbor intersection graph

Average two dual variables per point to get optimal radii

Time  $O(n^3)$  in metric spaces,  $O(n^{2-1/d})$  in Euclidean spaces



Optimal solution = odd cycles + pairs of tangent disks