

# Nondeterministic Finite Automata

Nondeterminism  
Subset Construction

# Nondeterminism

- A *nondeterministic finite automaton* has the ability to be in several states at once.
- Transitions from a state on an input symbol can be to any set of states.

# Nondeterminism – (2)

- Start in one start state.
- Accept if any sequence of choices leads to a final state.
- **Intuitively**: the NFA always “guesses right.”

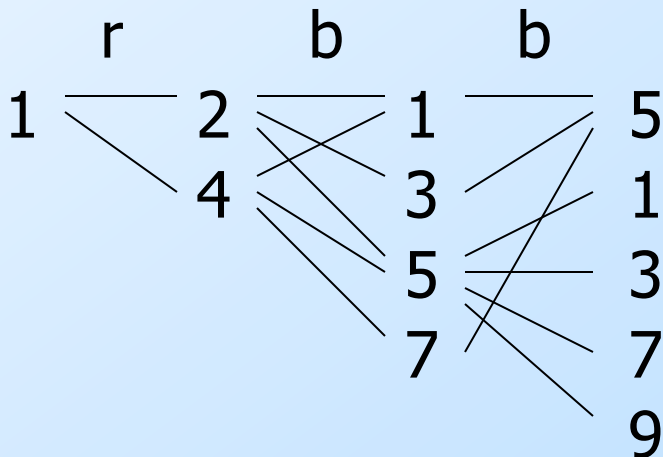
# Example: Moves on a Chessboard

- States = squares.
- Inputs = r (move to an adjacent red square) and b (move to an adjacent black square).
- Start state, final state are in opposite corners.

# Example: Chessboard – (2)

1	2	3
4	5	6
7	8	9

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5



← Accept, since final state reached

# Formal NFA

- A finite set of states, typically  $Q$ .
- An input alphabet, typically  $\Sigma$ .
- A transition function, typically  $\delta$ .
- A start state in  $Q$ , typically  $q_0$ .
- A set of final states  $F \subseteq Q$ .

# Transition Function of an NFA

- $\delta(q, a)$  is a set of states.
- Extend to strings as follows:
- **Basis:**  $\delta(q, \epsilon) = \{q\}$
- **Induction:**  $\delta(q, wa) =$  the union over all states  $p$  in  $\delta(q, w)$  of  $\delta(p, a)$

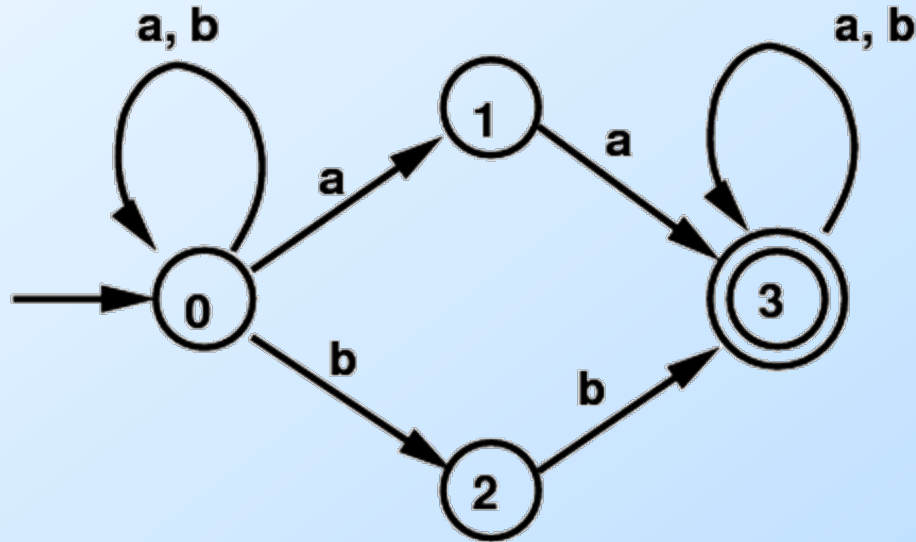
# Language of an NFA

- A string  $w$  is **accepted** by an NFA if  $\delta(q_0, w)$  contains at least one final state.
- That is, **there exists** a sequence of valid transitions from  $q_0$  to a final state given the input  $w$ .
- The language of the NFA is the set of strings it accepts.



# Example NFA

- Set of all strings with two consecutive a's or two consecutive b's:



- Note that some states have an empty transition on an a or b, and some have multiple transitions on a or b.

## Example 2: Language of an NFA

1	2	3
4	5	6
7	8	9

- For our chessboard NFA we saw that  $rbb$  is accepted.
- If the input consists of only  $b$ 's, the set of accessible states alternates between  $\{5\}$  and  $\{1,3,7,9\}$ , so only even-length, nonempty strings of  $b$ 's are accepted.
- What about strings with at least one  $r$ ?

# Equivalence of DFA' s, NFA' s

- A DFA can be turned into an NFA that accepts the same language.
- If  $\delta_D(q, a) = p$ , let the NFA have  $\delta_N(q, a) = \{p\}$ .
- Then the NFA is always in a set containing exactly one state – the state the DFA is in after reading the same input.

# Equivalence – (2)

- Surprisingly, for any NFA there is a DFA that accepts the same language.
- Proof is the *subset construction*.
- The number of states of the DFA can be exponential in the number of states of the NFA.
- Thus, NFA's accept **exactly** the regular languages.

# Subset Construction

- Given an NFA with states  $Q$ , inputs  $\Sigma$ , transition function  $\delta_N$ , state state  $q_0$ , and final states  $F$ , construct equivalent DFA with:
  - States  $2^Q$  (Set of subsets of  $Q$ ).
  - Inputs  $\Sigma$ .
  - Start state  $\{q_0\}$ .
  - Final states = all those with a member of  $F$ .

# Critical Point

- The DFA states have *names* that are sets of NFA states.
- But as a DFA state, an expression like  $\{p,q\}$  must be read as a single symbol, not as a set.
- **Analogy**: a class of objects whose values are sets of objects of another class.

# Subset Construction – (2)

- The transition function  $\delta_D$  is defined by:  
 $\delta_D(\{q_1, \dots, q_k\}, a)$  is the union over all  $i = 1, \dots, k$  of  $\delta_N(q_i, a)$ .
- **Example:** We'll construct the DFA equivalent of our “chessboard” NFA.

# Example: Subset Construction

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5

	r	b
→ {1}	{2,4}	{5}
{2,4}		
{5}		

**Alert:** What we're doing here is the *lazy* form of DFA construction, where we only construct a state if we are forced to.



# Example: Subset Construction

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5

	r	b
→ {1}	{2,4}	{5}
{2,4}	{2,4,6,8}	{1,3,5,7}
{5}		
{2,4,6,8}		
{1,3,5,7}		

# Example: Subset Construction

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5

	r	b
→ {1}	{2,4}	{5}
{2,4}	{2,4,6,8}	{1,3,5,7}
{5}	{2,4,6,8}	{1,3,7,9}
{2,4,6,8}		
{1,3,5,7}		
* {1,3,7,9}		

# Example: Subset Construction

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5

	r	b
→ {1}	{2,4}	{5}
{2,4}	{2,4,6,8}	{1,3,5,7}
{5}	{2,4,6,8}	{1,3,7,9}
{2,4,6,8}	{2,4,6,8}	{1,3,5,7,9}
{1,3,5,7}		
* {1,3,7,9}		
* {1,3,5,7,9}		

# Example: Subset Construction

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5

	r	b
→ {1}	{2,4}	{5}
{2,4}	{2,4,6,8}	{1,3,5,7}
{5}	{2,4,6,8}	{1,3,7,9}
{2,4,6,8}	{2,4,6,8}	{1,3,5,7,9}
{1,3,5,7}	{2,4,6,8}	{1,3,5,7,9}
* {1,3,7,9}		
* {1,3,5,7,9}		

# Example: Subset Construction

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5

	r	b
→ {1}	{2,4}	{5}
{2,4}	{2,4,6,8}	{1,3,5,7}
{5}	{2,4,6,8}	{1,3,7,9}
{2,4,6,8}	{2,4,6,8}	{1,3,5,7,9}
{1,3,5,7}	{2,4,6,8}	{1,3,5,7,9}
* {1,3,7,9}	{2,4,6,8}	{5}
* {1,3,5,7,9}		

# Example: Subset Construction

	r	b
→ 1	2,4	5
2	4,6	1,3,5
3	2,6	5
4	2,8	1,5,7
5	2,4,6,8	1,3,7,9
6	2,8	3,5,9
7	4,8	5
8	4,6	5,7,9
* 9	6,8	5

	r	b
→ {1}	{2,4}	{5}
{2,4}	{2,4,6,8}	{1,3,5,7}
{5}	{2,4,6,8}	{1,3,7,9}
{2,4,6,8}	{2,4,6,8}	{1,3,5,7,9}
{1,3,5,7}	{2,4,6,8}	{1,3,5,7,9}
* {1,3,7,9}	{2,4,6,8}	{5}
* {1,3,5,7,9}	{2,4,6,8}	{1,3,5,7,9}

# Proof of Equivalence: Subset Construction

- The proof is almost a pun.
- Show by induction on  $|w|$  that

$$\delta_N(q_0, w) = \delta_D(\{q_0\}, w)$$

- **Basis:**  $w = \epsilon$ :  $\delta_N(q_0, \epsilon) = \delta_D(\{q_0\}, \epsilon) = \{q_0\}$ .

# Induction

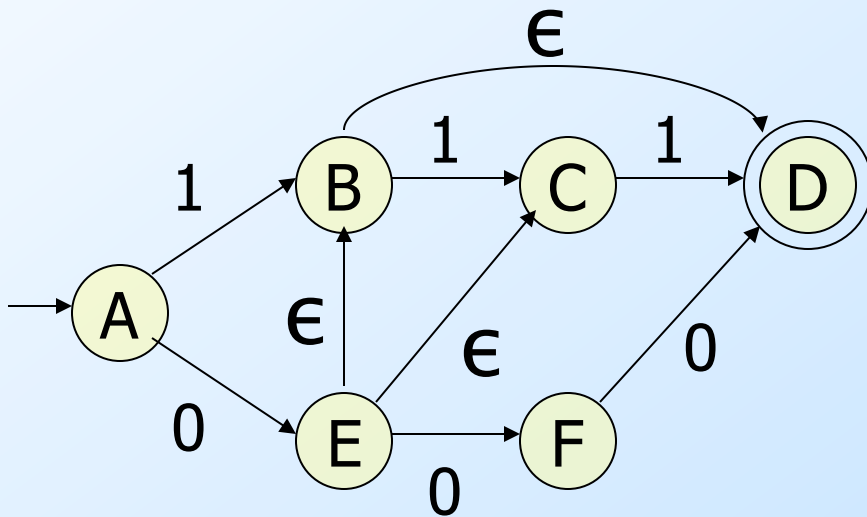
- Assume IH for strings shorter than  $w$ .
- Let  $w = xa$ ; IH holds for  $x$ .
- Let  $\delta_N(q_0, x) = \delta_D(\{q_0\}, x) = S$ .
- Let  $T =$  the union over all states  $p$  in  $S$  of  $\delta_N(p, a)$ .
- Then  $\delta_N(q_0, w) = \delta_D(\{q_0\}, w) = T$ .
  - For NFA: the extension of  $\delta_N$ .
  - For DFA: definition of  $\delta_D$  plus extension of  $\delta_D$ .
    - That is,  $\delta_D(S, a) = T$ ; then extend  $\delta_D$  to  $w = xa$ .



# NFA's With $\epsilon$ -Transitions

- We can allow state-to-state transitions on  $\epsilon$  input.
- These transitions are done spontaneously, without looking at the input string.
- A convenience at times, but still only regular languages are accepted.

# Example: $\epsilon$ -NFA

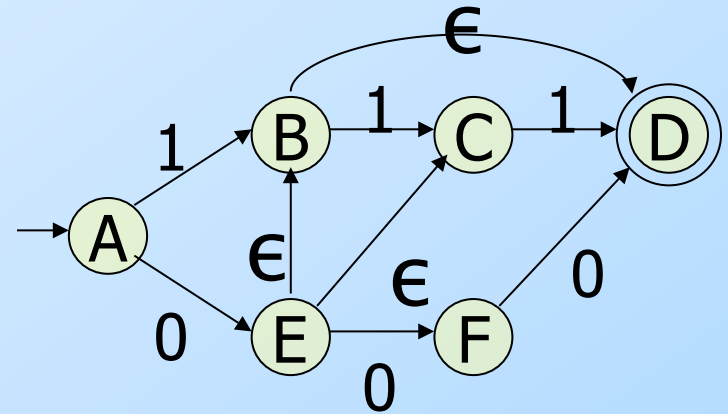


	0	1	$\epsilon$
$\rightarrow$ A	{E}	{B}	$\emptyset$
B	$\emptyset$	{C}	{D}
C	$\emptyset$	{D}	$\emptyset$
* D	$\emptyset$	$\emptyset$	$\emptyset$
E	{F}	$\emptyset$	{B, C}
F	{D}	$\emptyset$	$\emptyset$

# Closure of States

- $CL(q)$  = set of states you can reach from state  $q$  following only arcs labeled  $\epsilon$ .

- **Example:**  $CL(A) = \{A\}$ ;  
 $CL(E) = \{B, C, D, E\}$ .



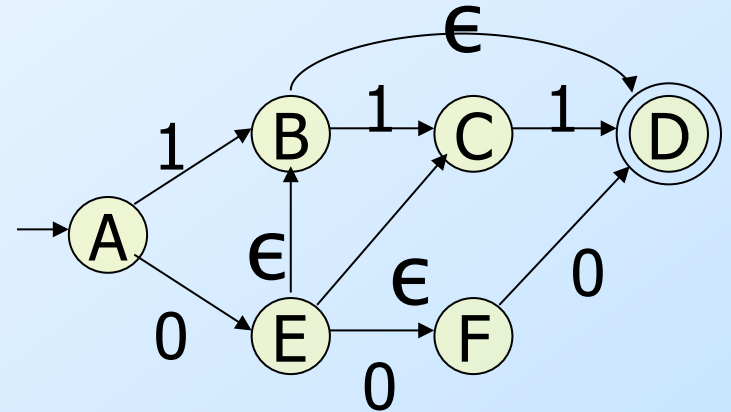
- Closure of a set of states = union of the closure of each state.

# Extended Delta

- **Basis:**  $\delta(q, \epsilon) = CL(q)$ .
  - **Induction:**  $\delta(q, xa)$  is computed as follows:
    1. Start with  $\delta(q, x) = S$ .
    2. Take the union of  $CL(\delta(p, a))$  for all  $p$  in  $S$ .
  - **Intuition:**  $\delta(q, w)$  is the set of states you can reach from  $q$  following a path labeled  $w$ .
- And notice that  $\delta(q, a)$  is *not* that set of states, for symbol  $a$ .

# Example:

## Extended Delta



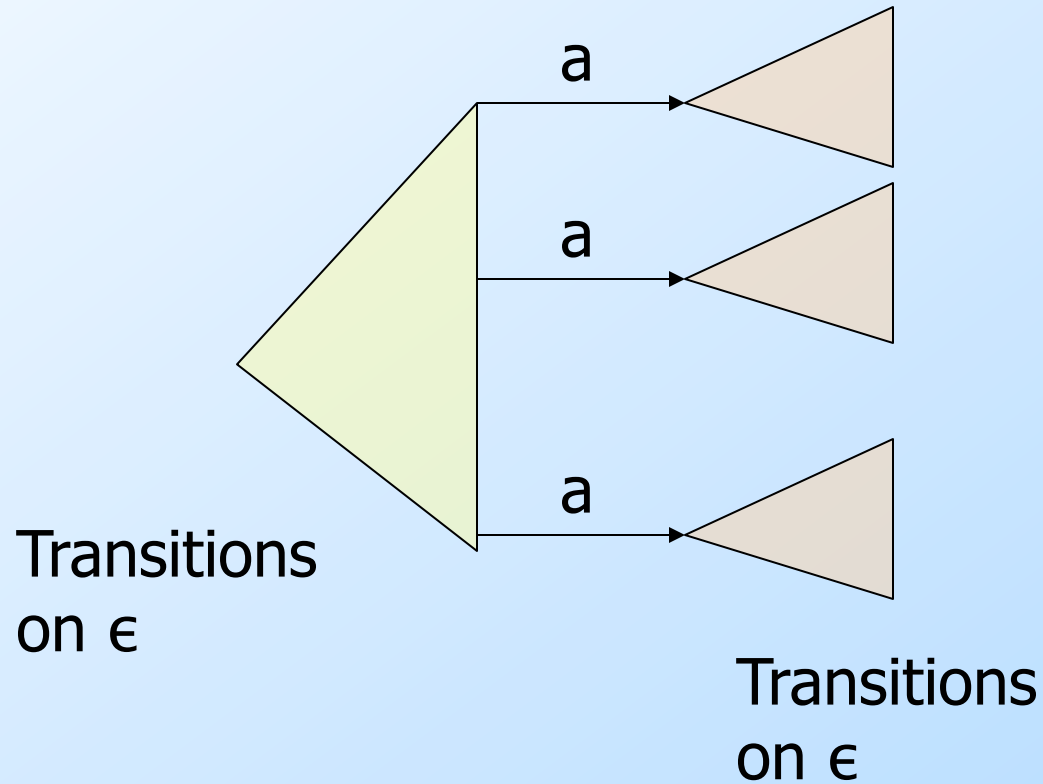
- $\delta(A, \epsilon) = CL(A) = \{A\}$ .
- $\delta(A, 0) = CL(\{E\}) = \{B, C, D, E\}$ .
- $\delta(A, 01) = CL(\{C, D\}) = \{C, D\}$ .
- *Language* of an  $\epsilon$ -NFA is the set of strings  $w$  such that  $\delta(q_0, w)$  contains a final state.

# Equivalence of NFA, $\epsilon$ -NFA

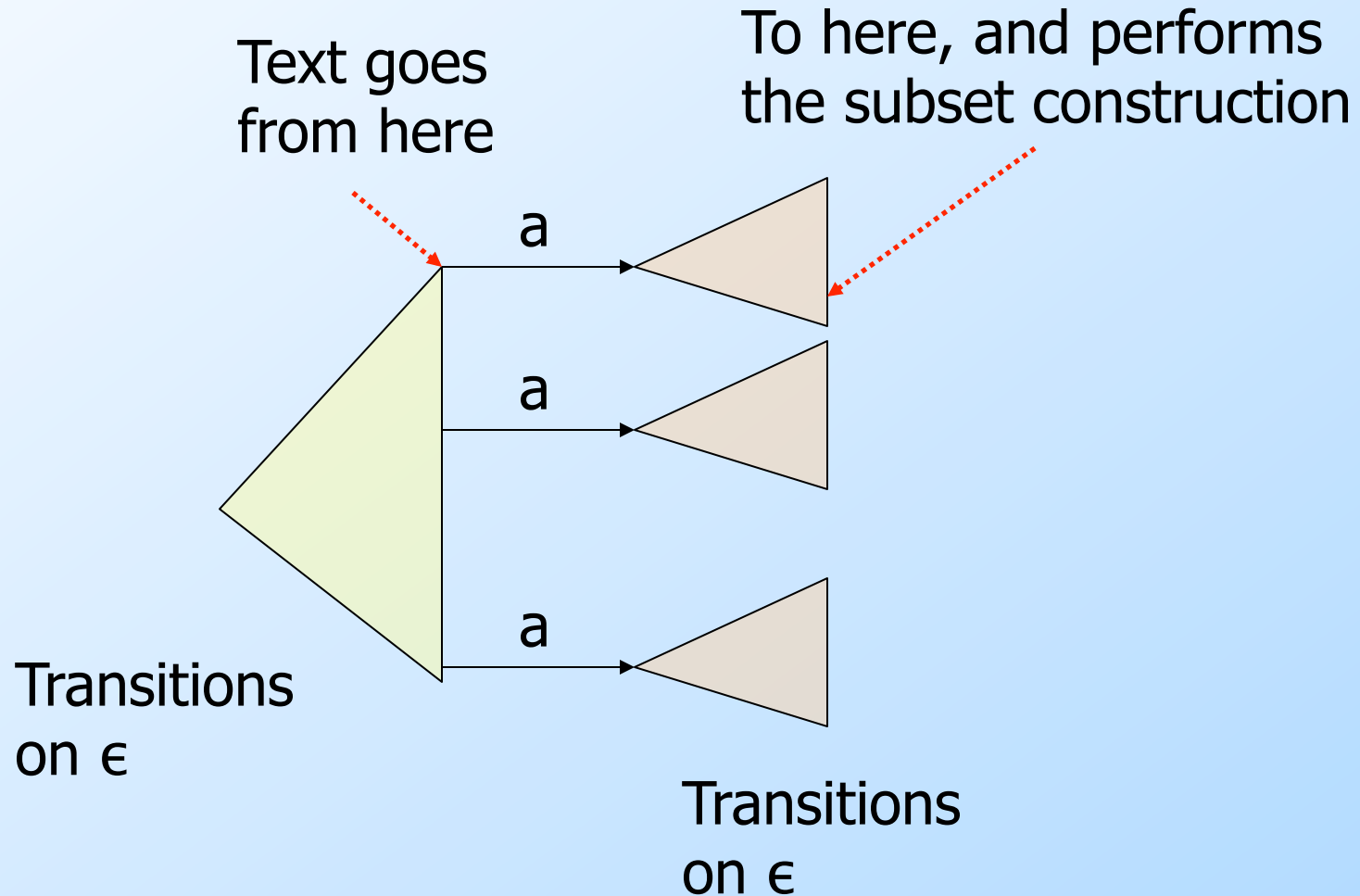
- Every NFA **is** an  $\epsilon$ -NFA.
  - It just has no transitions on  $\epsilon$ .
- Converse requires us to take an  $\epsilon$ -NFA and construct an NFA that accepts the same language.
- We do so by combining  $\epsilon$ -transitions with the next transition on a real input.

**Warning:** This treatment is a bit different from that in the text.

# Picture of $\epsilon$ -Transition Removal

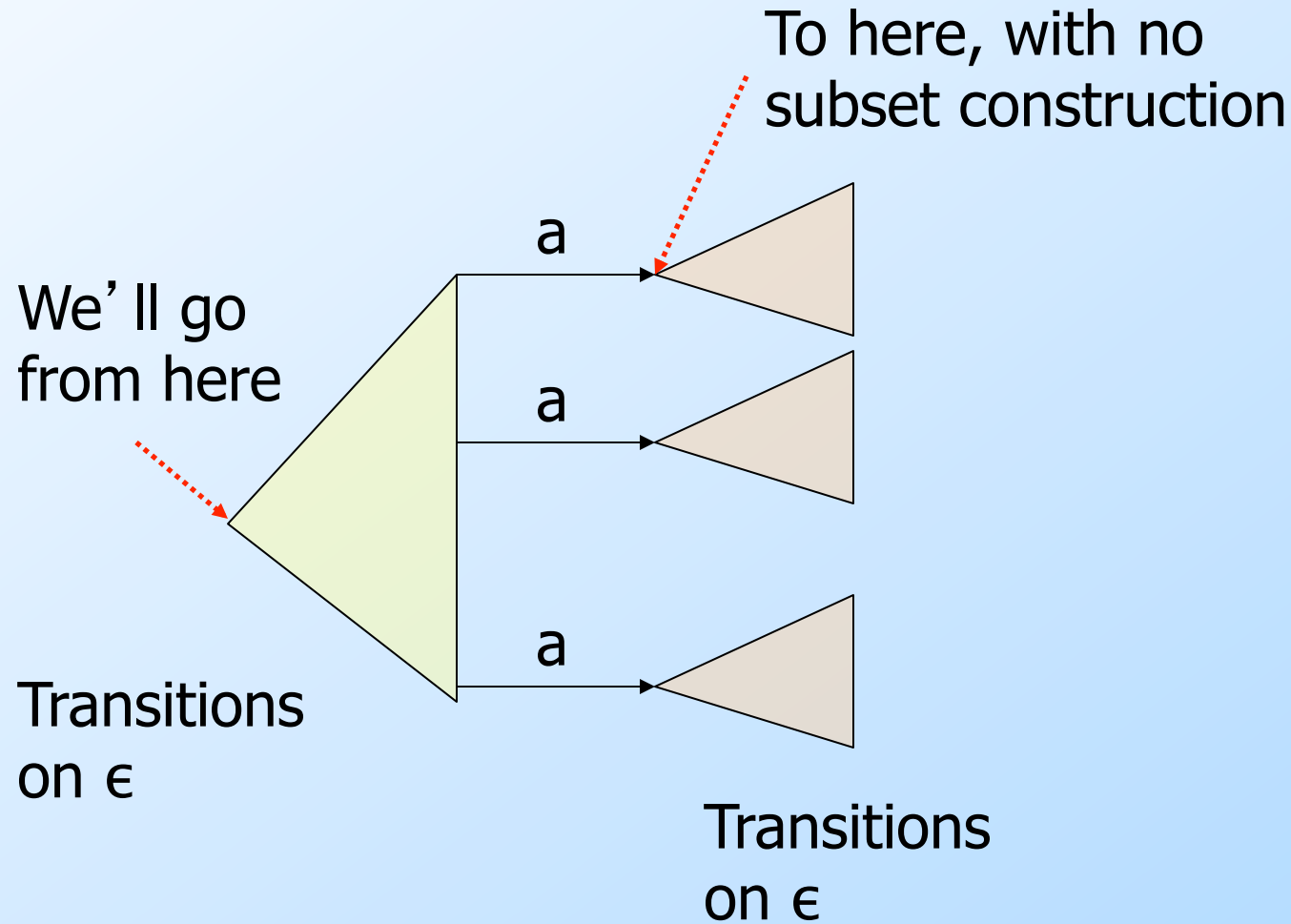


# Picture of $\epsilon$ -Transition Removal





# Picture of $\epsilon$ -Transition Removal



# Equivalence – (2)

- Start with an  $\epsilon$ -NFA with states  $Q$ , inputs  $\Sigma$ , start state  $q_0$ , final states  $F$ , and transition function  $\delta_E$ .
- Construct an “ordinary” NFA with states  $Q$ , inputs  $\Sigma$ , start state  $q_0$ , final states  $F'$ , and transition function  $\delta_N$ .

# Equivalence – (3)

- Compute  $\delta_N(q, a)$  as follows:
  1. Let  $S = CL(q)$ .
  2.  $\delta_N(q, a)$  is the union over all  $p$  in  $S$  of  $\delta_E(p, a)$ .
- $F'$  = the set of states  $q$  such that  $CL(q)$  contains a state of  $F$ .
- **Intuition:**  $\delta_N$  incorporates  $\epsilon$ -transitions before using  $a$  but not after.

# Equivalence – (4)

- Prove by induction on  $|w|$  that

$$CL(\delta_N(q_0, w)) = \delta_E(q_0, w).$$

- Thus, the  $\epsilon$ -NFA accepts  $w$  if and only if the “ordinary” NFA does.

Interesting  
 closures:  $CL(B)$   
 $= \{B, D\}$ ;  $CL(E)$   
 $= \{B, C, D, E\}$

# Example: $\epsilon$ -NFA-to-NFA

	0	1	$\epsilon$
$\rightarrow$ A	{E}	{B}	$\emptyset$
B	$\emptyset$	{C}	{D}
C	$\emptyset$	{D}	$\emptyset$
* D	$\emptyset$	$\emptyset$	$\emptyset$
E	{F}	$\emptyset$	{B, C}
F	{D}	$\emptyset$	$\emptyset$

$\epsilon$ -NFA

Since closures of B and E include final state D.

	0	1
$\rightarrow$ A	{E}	{B}
B	$\emptyset$	{C}
C	$\emptyset$	{D}
* D	$\emptyset$	$\emptyset$
E	{F}	{C, D}
F	{D}	$\emptyset$

Since closure of E includes B and C; which have transitions on 1 to C and D.

# Summary

- DFA' s, NFA' s, and  $\epsilon$ -NFA' s all accept exactly the same set of languages: the regular languages.
- The NFA types are easier to design and may have exponentially fewer states than a DFA.
- But only a DFA can be implemented in linear time!