## Approximation Algorithms

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## Applications

- One of the most time-consuming parts of astronomy involves collecting the light from the galaxy or star over a given period of time.
- To do this with a telescope, a large aluminum disk the size of the diameter of the telescope is used.
- This disk is placed in the focal plane of the telescope, so that the light from each stellar objects in an observation falls in a specific spot on the disk.
- The astronomers use robotic drilling equipment to drill a hole in each spot of interest and they insert a fiber-optic cable into each such hole and connect it to a spectrograph.



## Application to TSP

- Drilling the holes in the fastest way is an instance of the traveling salesperson problem (TSP).

- According to this formulation of TSP, each of the hole locations is a "city" and the time it takes to move a robot drill from one hole to another corresponds to the distance between the "citie" for these two holes.
- Thus, a minimum-distance tour of the cities that starts and ends at the resting position for the robot drill is one that will drill the holes the fastest.
- Unfortunately, TSP is NP-complete.
- So it would be ideal if we could at least approximate this problem.


## Application to Set Cover

- Another optimization problem is to minimize the number of observations needed in order to collect the spectra of all the stellar objects of interest.
- In this case, we want to cover the map of objects with the minimum number of disks having the same diameter as the telescope.
- This optimization problem is an instance of the set cover problem.
- Each of the distinct sets of objects that can be included in a single observation is given as an input set and the optimization problem is to minimize the number of sets whose union includes all the objects of interest.
- This problem is also NP-complete, but it is a problem for which an approximation to the optimum might be sufficient.


## Set Cover Example



Figure 18.2: An example disk cover for a set of significant stellar objects (smaller objects are not included). Background image is from Omega Centauri, 2009. U.S. government image. Credit: NASA, ESA, and the Hubble SM4 ERO team.

## Approximation Ratios

## * Optimization Problems

- We have some problem instance $x$ that has many feasible "solutions".
- We are trying to minimize (or maximize) some cost function $c(S)$ for a "solution" $S$ to $x$. For example,
- Finding a minimum spanning tree of a graph
- Finding a smallest vertex cover of a graph
- Finding a smallest traveling salesperson tour in a graph
- An approximation produces a solution T
- T is a k-approximation to the optimal solution OPT if $c(T) / c(O P T) \leq k$ (assuming a min. prob.; a maximization approximation would be the reverse)


## Special Case of the Traveling Salesperson Problem

* OPT-TSP: Given a complete, weighted graph, find a cycle of minimum cost that visits each vertex.
- OPT-TSP is NP-hard
- Special case: edge weights satisfy the triangle inequality (which is common in many applications):
- $w(a, b)+w(b, c) \geq w(a, c)$



## A 2-Approximation for TSP

 Special Case
## Algorithm TSPApprox(G)

Input weighted complete graph $\boldsymbol{G}$, satisfying the triangle inequality
Output a TSP tour $\boldsymbol{T}$ for $\boldsymbol{G}$
$M \leftarrow$ a minimum spanning tree for $\boldsymbol{G}$
$\boldsymbol{P} \leftarrow$ an Euler tour traversal of $\boldsymbol{M}$, starting at some vertex $\boldsymbol{s}$
$T \leftarrow$ empty list
for each vertex $\boldsymbol{v}$ in $\boldsymbol{P}$ (in traversal order) if this is $\boldsymbol{v}$ 's first appearance in $\boldsymbol{P}$ then T.insertLast(v)
T.insertLast(s)
return $T$


Euler tour $P$ of MST $M$

Output tour $T$


## A 2-Approximation for TSP Special Case - Proof



- The optimal tour is a spanning tour; hence $|\mathrm{M}| \leq|\mathrm{OPT}|$.
* The Euler tour P visits each edge of M twice; hence $|\mathrm{P}|=2|\mathrm{M}|$
- Each time we shortcut a vertex in the Euler Tour we will not increase the total length, by the triangle inequality $(w(a, b)+w(b, c) \geq$ $w(a, c))$; hence, $|T| \leq|P|$.
- Therefore, $|\mathrm{T}| \leq|\mathrm{P}|=2|\mathrm{M}| \leq 2|\mathrm{OPT}|$


Output tour $T$ (at most the cost of $P$ )


Euler tour $P$ of MST $M$ (twice the cost of $M$ )


Optimal tour $O P T$ (at least the cost of MST M)

## Vertex Cover

- A vertex cover of graph $\mathrm{G}=(\mathrm{V}, \mathrm{E})$ is a subset W of V , such that, for every $(a, b)$ in $E$, $a$ is in $W$ or $b$ is in $W$.
- OPT-VERTEX-COVER: Given an graph G, find a vertex cover of $G$ with smallest size.
- OPT-VERTEX-COVER is NP-hard.



## A 2-Approximation for Vertex Cover

- Every chosen edge e has both ends in C
- But e must be covered by an optimal cover; hence, one end of e must be in OPT
- Thus, there is at most twice as many vertices in C as in OPT.
- That is, C is a 2-approx. of OPT
- Running time: $\mathrm{O}(\mathrm{n}+\mathrm{m})$


## Set Cover (Greedy Algorithm)

- OPT-SET-COVER: Given a collection of $m$ sets, find the smallest number of them whose union is the same as the whole collection of $m$ sets?
- OPT-SET-COVER is NP-hard
- Greedy approach produces an O(log n)-approximation algorithm.

Algorithm SetCoverApprox $(S)$ :
Input: A collection $S$ of sets $S_{1}, S_{2}, \ldots, S_{m}$ whose union is $U$
Output: A small set cover $C$ for $S$
$C \leftarrow \emptyset \quad / /$ The set cover built so far
$E \leftarrow \emptyset \quad / /$ The elements from $U$ currently covered by $C$ while $E \neq U$ do
select a set $S_{i}$ that has the maximum number of uncovered elements add $S_{i}$ to $C$
$E \leftarrow E \cup S_{i}$
Return $C$.

## Greedy Set Cover Analysis

- Consider the moment in our algorithm when a set $S_{j}$ is added to $C$, and let $k$ be the number of previously uncovered elements in $\mathrm{S}_{\mathrm{j}}$.
- We pay a total charge of 1 to add this set to C, so we charge each previously uncovered element $i$ of $S_{j}$ a charge of $c(i)=1 / k$.
- Thus, the total size of our cover is equal to the total charges made.
- To prove an approximation bound, we will consider the charges made to the elements in each subset $\mathrm{S}_{\mathrm{j}}$ that belongs to an optimal cover, $C^{\prime}$. So, suppose that $S_{j}$ belongs to $C^{\prime}$.
Let us write $S_{j}=\left\{x_{1}, x_{2}, \ldots, x_{n j}\right\}$ so that $S_{j}$ 's elements are listed in the order in which they are covered by our algorithm.


## Greedy Set Cover Analysis, cont.

Now, consider the iteration in which $x_{1}$ is first covered. At that moment, $S_{j}$ has not yet been selected; hence, whichever set is selected must have at least $n_{j}$ uncovered elements. Thus, $x_{1}$ is charged at most $1 / n_{j}$. So let us consider, then, the moment our algorithm charges an element $x_{l}$ of $S_{j}$. In the worst case, we will have not yet chosen $S_{j}$ (indeed, our algorithm may never choose this $S_{j}$ ). Whichever set is chosen in this iteration has, in the worst case, at least $n_{j}-l+1$ uncovered elements; hence, $x_{l}$ is charged at most $1 /\left(n_{j}-l+1\right)$. Therefore, the total amount charged to all the elements of $S_{j}$ is at most|

$$
\sum_{l=1}^{n_{j}} \frac{1}{n_{l}-l+1}=\sum_{l=1}^{n_{j}} \frac{1}{l}
$$

which is the familiar harmonic number, $H_{n_{i}}$. It is well known (for example, see the Appendix) that $H_{n_{j}}$ is $O\left(\log n_{j}\right)$. Let $c\left(S_{j}\right)$ denote the total charges given to all the elements of a set $S_{j}$ that belongs to the optimal cover $C^{\prime}$. Our charging scheme implies that $c\left(S_{j}\right)$ is $O\left(\log n_{j}\right)$. Thus, summing over the sets of $C^{\prime}$, we obtain

$$
\begin{aligned}
\sum_{S_{j} \in C^{\prime}} c\left(S_{j}\right) & \leq \sum_{S_{j} \in C^{\prime}} b \log n_{j} \\
& \leq b\left|C^{\prime}\right| \log n
\end{aligned}
$$

for some constant $b \geq 1$. But, since $C^{\prime}$ is a set cover,

$$
\sum_{i \in U} c(i) \leq \sum_{S_{j} \in C^{\prime}} c\left(S_{j}\right)
$$

Therefore,

$$
|C| \leq b\left|C^{\prime}\right| \log n
$$

## Polynomial-Time Approximation

## Schemes

A problem L has a polynomial-time approximation scheme (PTAS) if it has a polynomial-time ( $1+\varepsilon$ )-approximation algorithm, for any fixed $\varepsilon>0$ (this value can appear in the running time).
0/1 Knapsack has a PTAS, with a running time that is $\mathrm{O}\left(\mathrm{n}^{3} / \varepsilon\right)$.

