## 3D convex hulls

Computational Geometry [csci 3250]
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## Convex Hull in 3D

The problem: Given a set P of points in 3D, compute their convex hull


3D

polygon
polyhedron


2D


3D

## Gift wrapping in 3D



- YouTube
- Video of CH in 3D (by Lucas Benevides)
- Fast 3D convex hull algorithms with CGAL


## Gift wrapping in 3D

## Algorithm

- find a face guaranteed to be on the CH
- REPEAT
- find an edge e of a face $f$ that's on the CH , and such that the face on the other side of e has not been found.
- for all remaining points pi, find the angle of (e,pi) with $f$
- find point pi with the minimal angle; add face (e,pi) to CH
- Analysis: $\mathrm{O}(\mathrm{n} \times \mathrm{F})$, where F is the number of faces on CH



## Gift wrapping in 3D

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- find point pi with the minimal angle; add face (e,pi) to CH
- Implementation details
- sketch more detailed pseudocode
- finding first face?
- what data structures do you need? how to keep track of vertices, edges, faces? how to store the connectivity of faces?


## 3d hull: divide \& conquer

The same idea as 2D algorithm

- divide points in two halves P1 and P2
- recursively find $\mathrm{CH}(\mathrm{P} 1)$ and $\mathrm{CH}(\mathrm{P} 2)$
- merge
- If merge in $\mathrm{O}(\mathrm{n})$ time $==>\mathrm{O}(\mathrm{n} \lg \mathrm{n})$ algorithm


## Merge

- How does the merged hull look like?

cylinder without end caps


## Merge

- Idea: Start with the lower tangent, wrap around, find one face at a time.



## Merge

- Let PI be a plane that supports the hull from below


Claim:

- When we rotate Pl around ab , the first vertex hit c must be a vertex adjacent to a or b
- $\quad$ c has the smallest angle among all neighbors of $a, b$


## Merge

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## Merge

1. Find a common tangent ab
2. Start from ab and wrap around, to create the cylinder of triangles that connects the two hulls $A$ and $B$
3. Find and delete the hidden faces that are "inside" the cylinder


(b)


- start from the edges on the boundary of the cylinder
- BFS or DFS faces "towards" the cylinder
- all faces reached are inside


## 3d hull: divide \& conquer

- Theoretically important and elegant
- Of all algorithms that extend to 3D, DC\& is the only one that achieves optimal ( $\mathrm{n} \lg \mathrm{n}$ )
- Difficult to implement
- The slower algorithms (quickhull, incremental) preferred in practice

