Near-optimal Fixed-parameter Tractability of the Bron–Kerbosch Algorithm for Maximal Cliques

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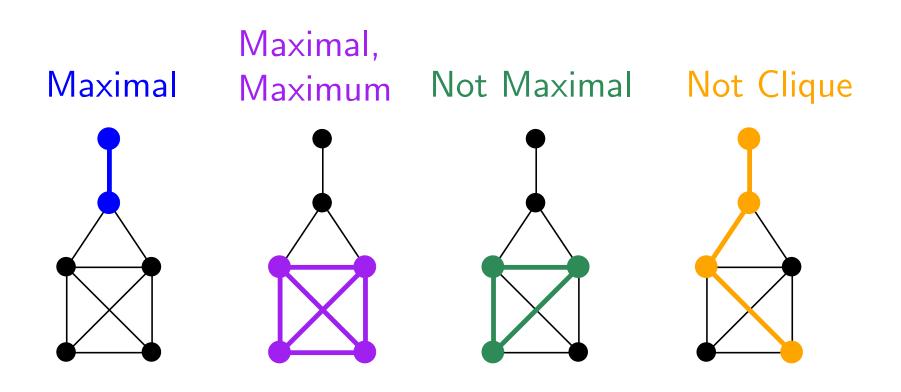
Joint work with David Eppstein and Maarten Löffler

What is a Maximal Clique?

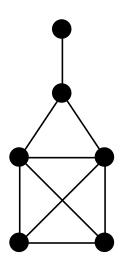
A clique that cannot be made bigger by adding more vertices

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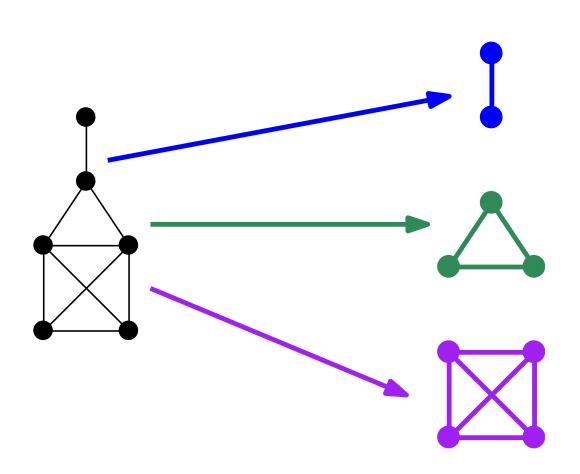
A clique that cannot be made bigger by adding more vertices



Goal: Design an algorithm to list all maximal cliques



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Features in ERGM

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Detect structural motifs from similarities between proteins

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Determine the docking regions between biomolecules

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Detect structural motifs from similarities between proteins

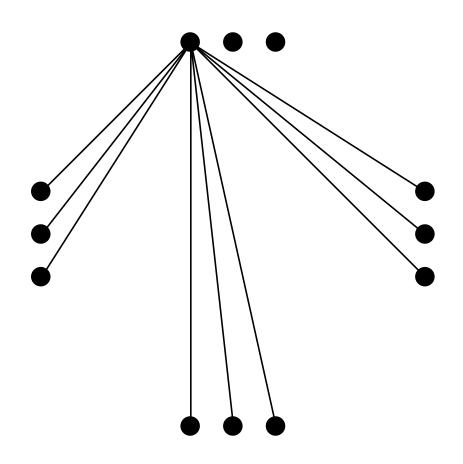
Determine the docking regions between biomolecules

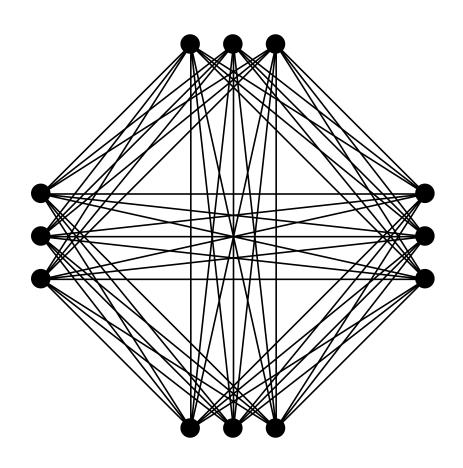
Document clustering for information retrieval

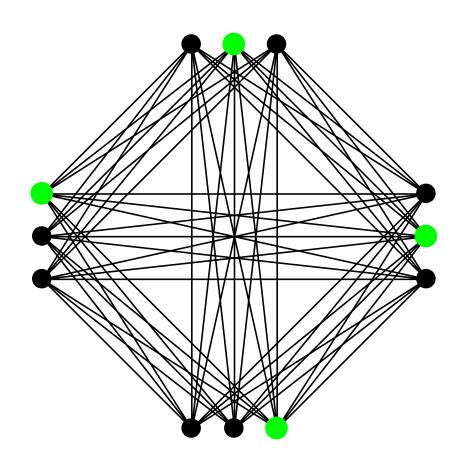


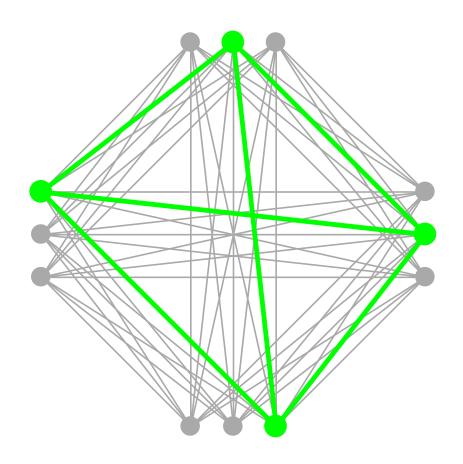


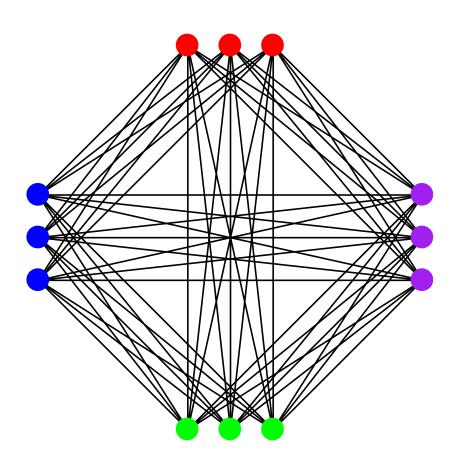
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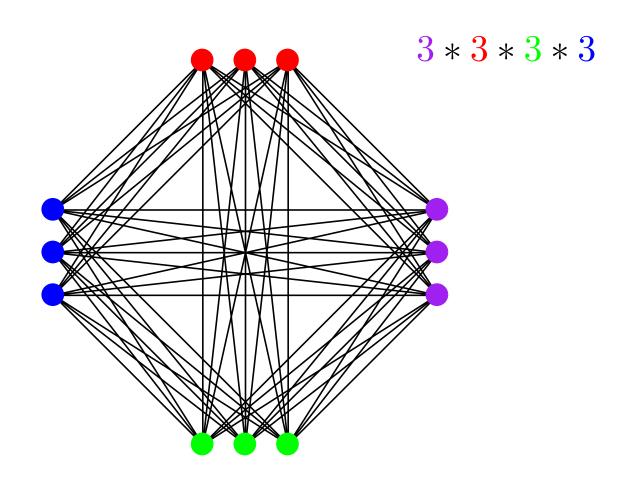


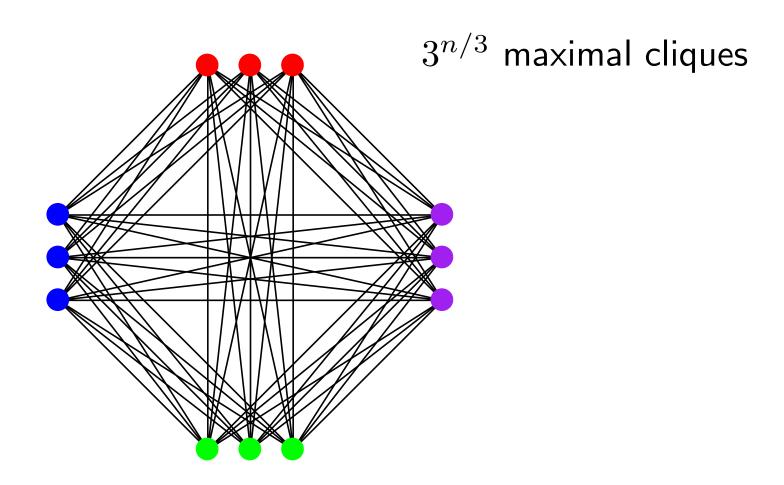


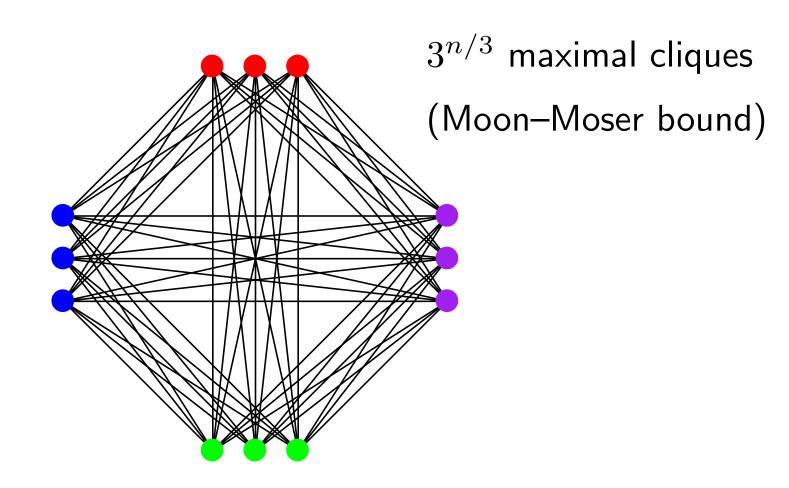












Maximal Clique Listing Algorithms

Author	Year	Running Time
Bron and Kerbosch	1973	???
Tsukiyama et al.	1977	$O(nm\mu)$
Chiba and Nishizeki	1985	$O(\alpha m \mu)$
Makino and Uno	2004	$O(\Delta^4\mu)$

n = number of vertices

m = number of edges

 $\mu =$ number of maximal cliques

 $\alpha = arboricity$

 $\Delta = \text{maximum degree of the graph}$

Tomita et al. (2006)

Tomita et al. (2006)

Worst-case optimal running time $O(3^{n/3})$

Tomita et al. (2006)

Worst-case optimal running time $O(3^{n/3})$

Computational experiments:

AMC	AMC*	CLIQUES
[14]	[14]	
261.27	9.51	10.49
952.25	49.45	10.20
3,601.09	130.76	9.90
14,448.21	431.20	10.95
35,866.69	530.53	12.97
> 24 h	1,066.62	16.85
> 24 h	4,350.94	33.75
> 24 h	15,655.05	65.06
> 24 h	> 24 h	293.97

Easy to understand

Easy to implement

There are many heuristics, which make it faster

Its variations work well in practice.

Confirmed through computational experiments Johnston (1976), Koch (2001), Baum (2003)

One variation is worst-case optimal $(O(3^{n/3}))$ time) Tomita et al. (2006)

Easy to understand

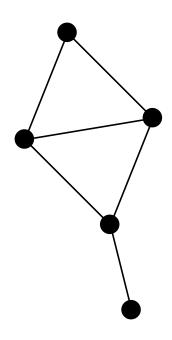
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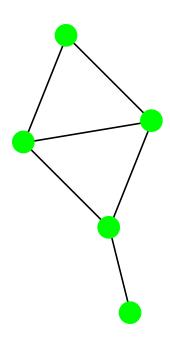
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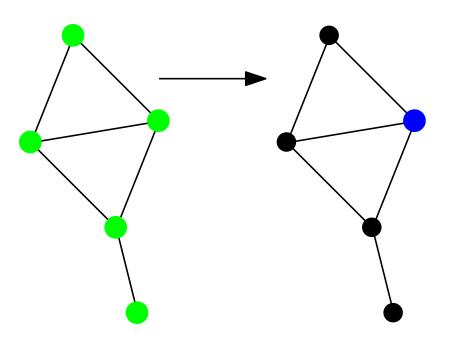
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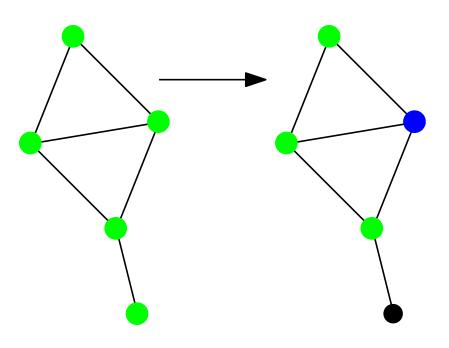
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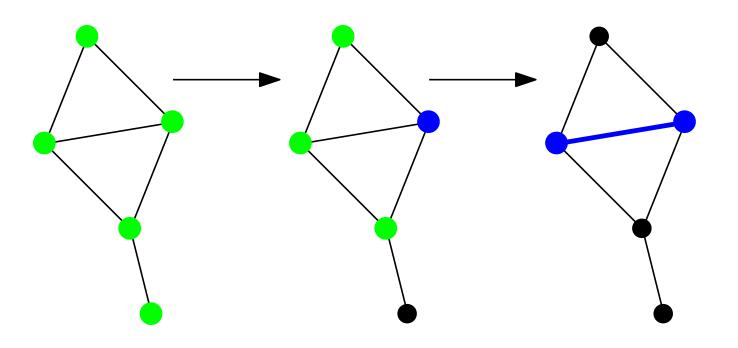
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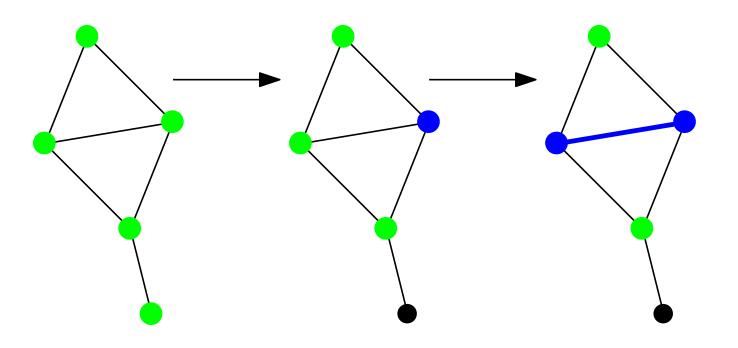


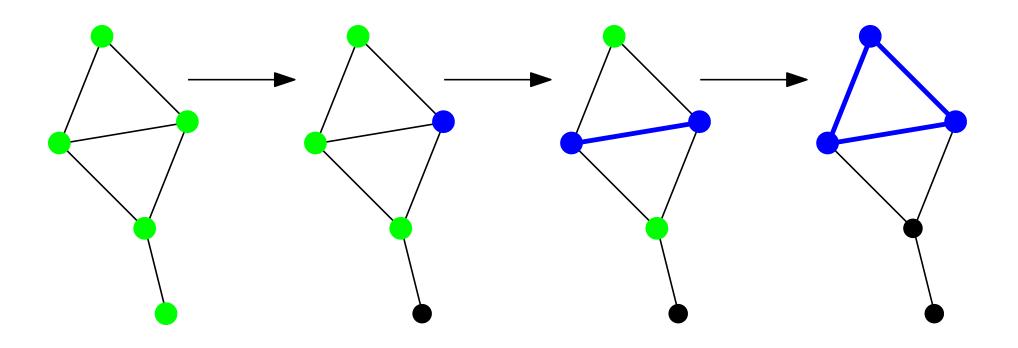


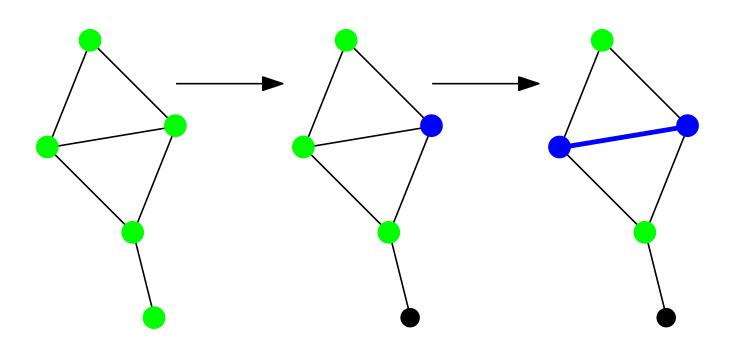


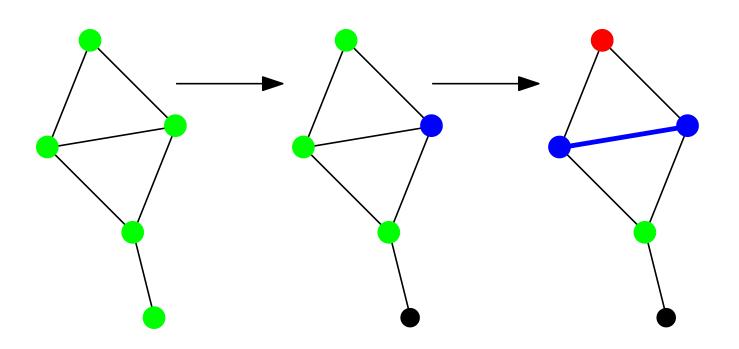


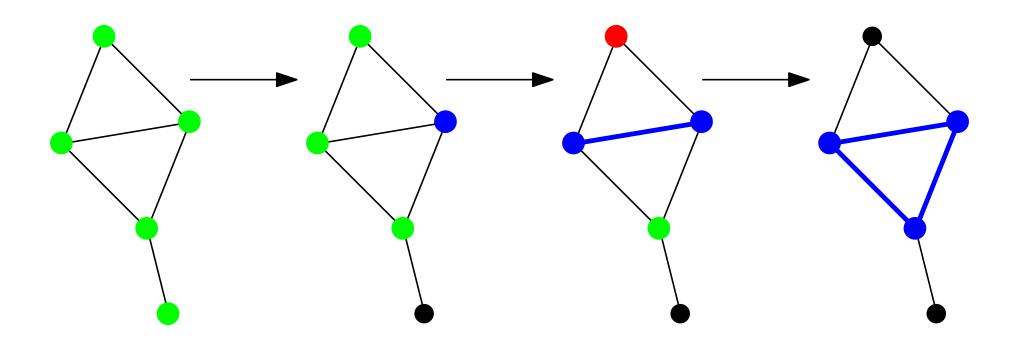


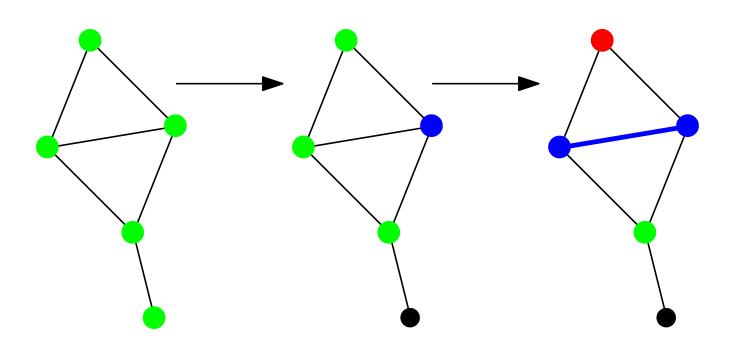


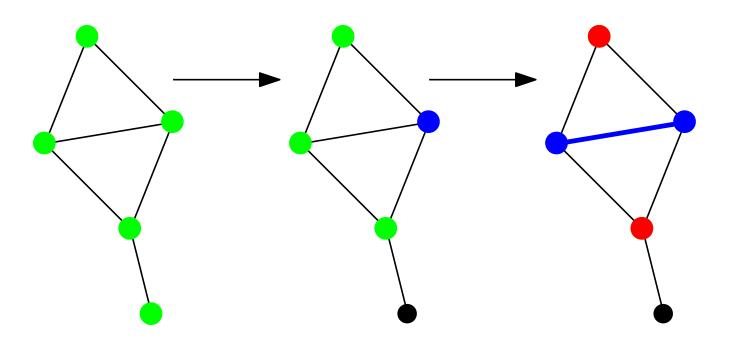


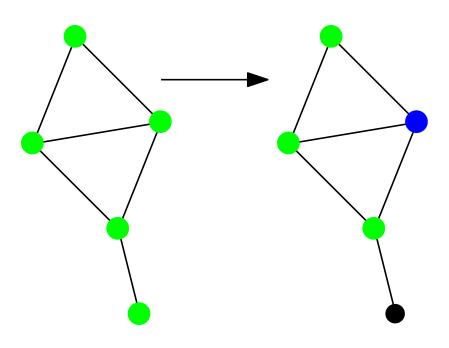


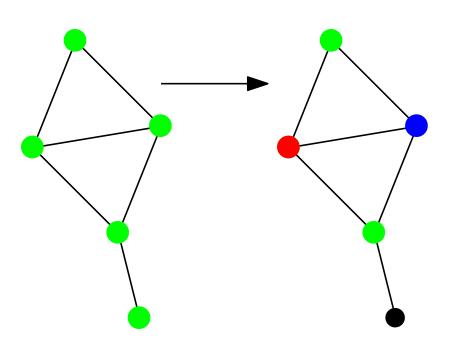


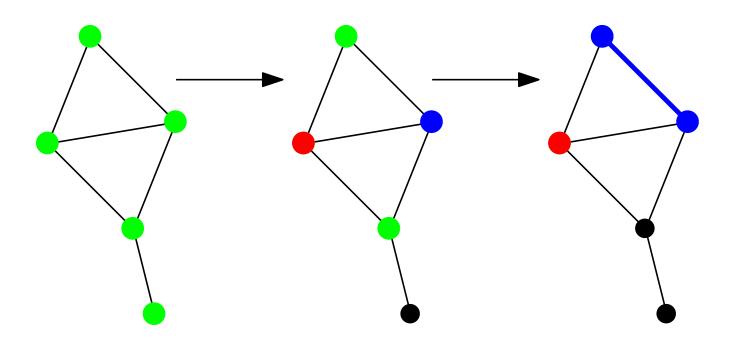


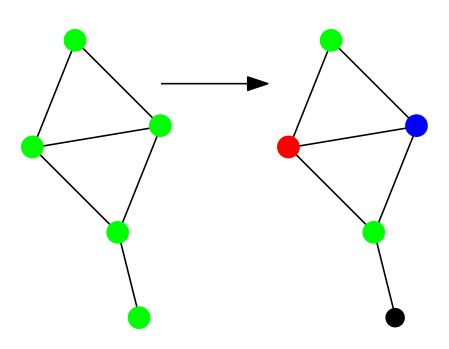


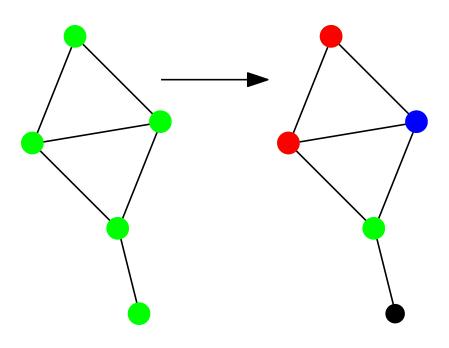


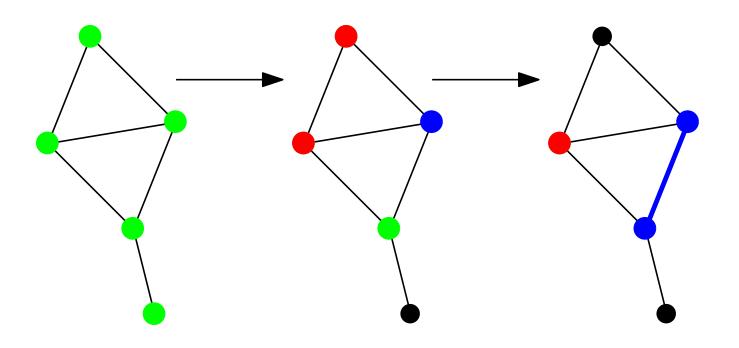


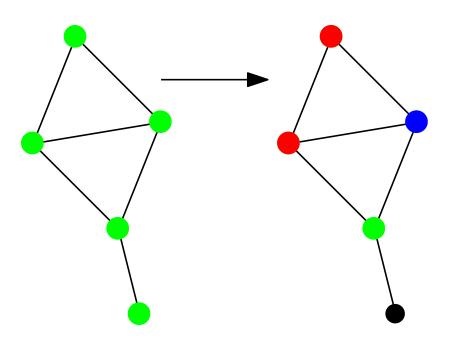


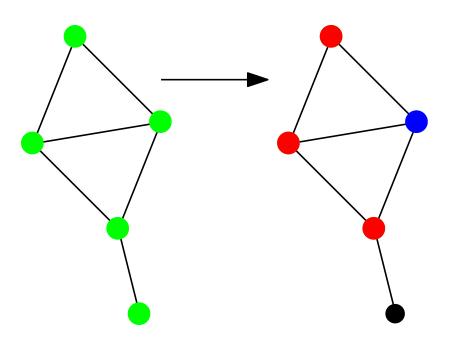


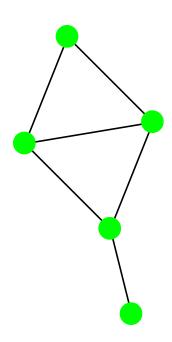


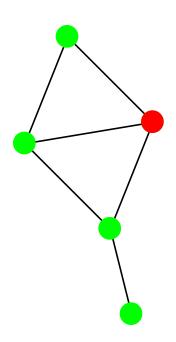












```
proc BronKerbosch(P, R, X)

1: if P \cup X = \emptyset then

2: report R as a maximal clique

3: end if

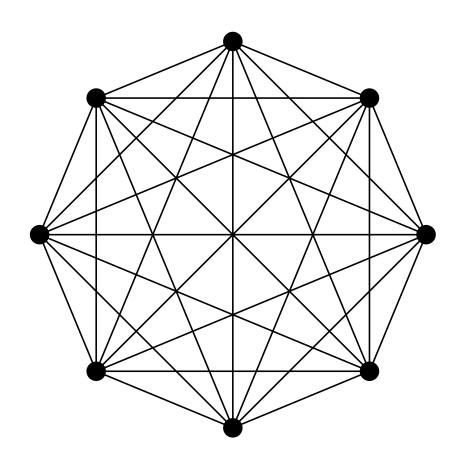
4: for each vertex v \in P do

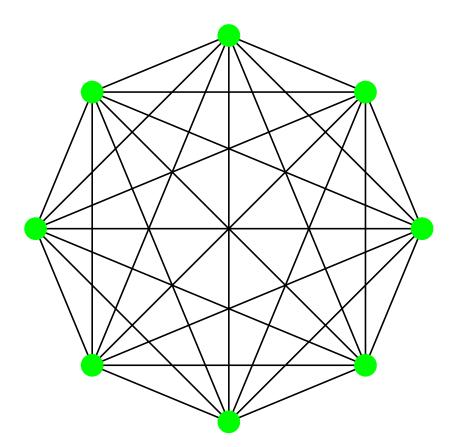
5: BronKerbosch(P \cap \Gamma(v), R \cup \{v\}, X \cap \Gamma(v))

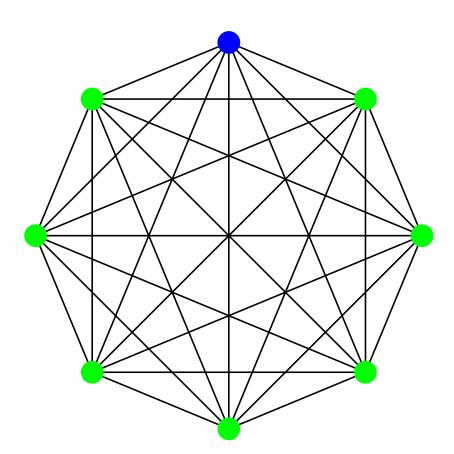
6: P \leftarrow P \setminus \{v\}

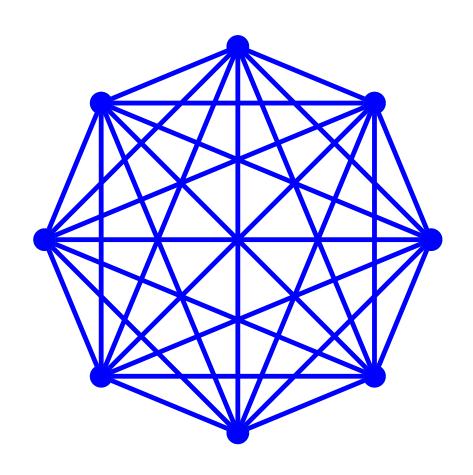
7: X \leftarrow X \cup \{v\}

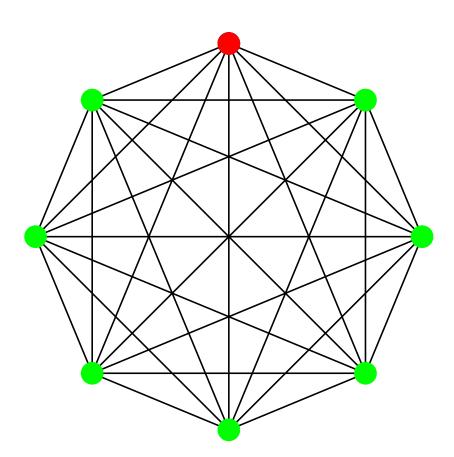
8: end for
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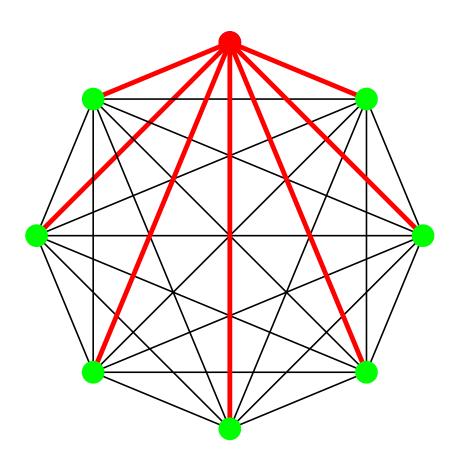


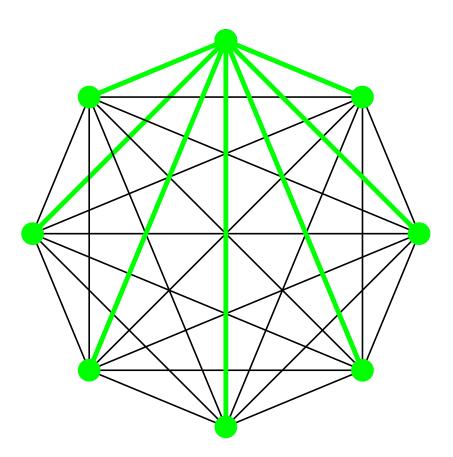












The Bron–Kerbosch Algorithm with Pivoting **proc** BronKerboschPivot(P, R, X)

- 1: if $P \cup X = \emptyset$ then
- 2: report R as a maximal clique
- 3: end if
- 4: choose a pivot $u \in P \cup X$
- 5: for each vertex $v \in P \setminus \Gamma(u)$ do
- 6: BronKerboschPivot $(P \cap \Gamma(v), R \cup \{v\}, X \cap \Gamma(v))$
- 7: $P \leftarrow P \setminus \{v\}$
- 8: $X \leftarrow X \cup \{v\}$
- 9: end for

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- 1: if $P \cup X = \emptyset$ then
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- 5: for each vertex $v \in P \setminus \Gamma(u)$ do
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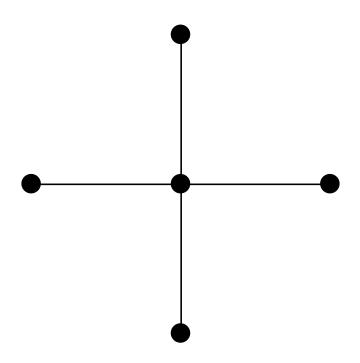
The Bron-Kerbosch Algorithm with Pivoting

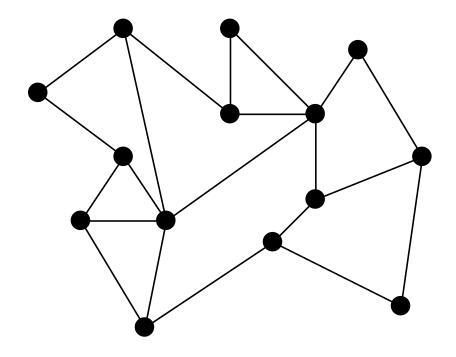
$$T(n) \le \max_{k} \{kT(n-k)\} + O(n^2)$$

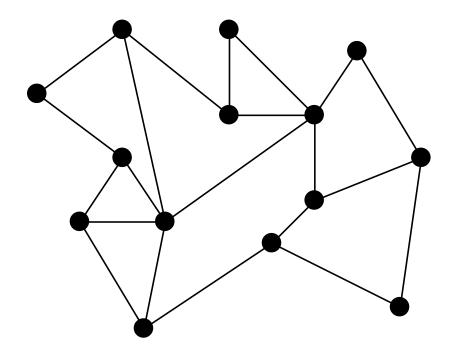
The Bron-Kerbosch Algorithm with Pivoting

$$T(n) \le \max_{k} \{kT(n-k)\} + O(n^2)$$

$$T(n) = O(3^{n/3})$$







All cliques in planar graphs may be listed in time O(n) Chiba and Nishizeki (1985), Chrobak and Eppstein (1991)

Want to characterize the running time with a parameter.

Let p be our parameter of choice.

An algorithm is fixed-parameter tractable with parameter p if it has running time

$$f(p)n^{O(1)}$$

The key is to avoid things like n^p .

Parameterize on Sparsity

Parameterize on Sparsity

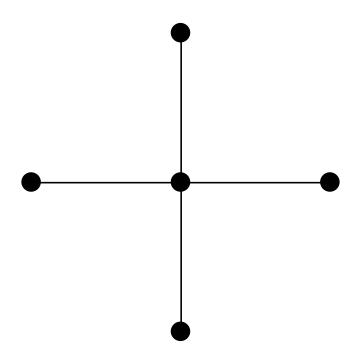
degeneracy:

Parameterize on Sparsity

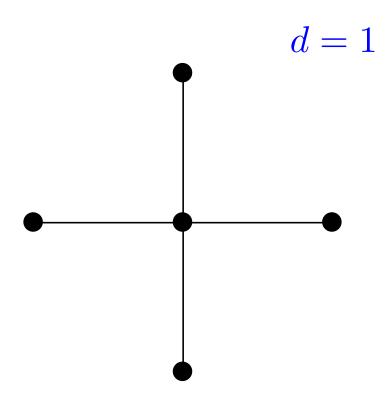
degeneracy:

The minimum integer d such that every subgraph of G has a vertex of degree d or less.

Degeneracy



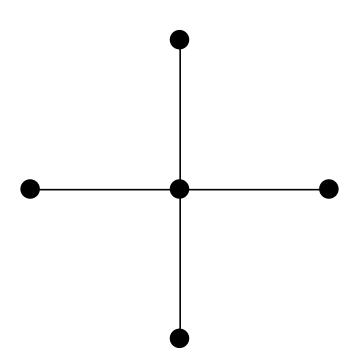
Degeneracy

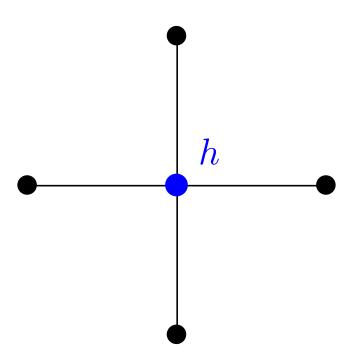


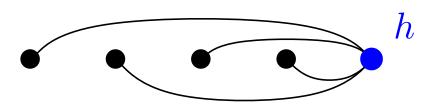
Degeneracy

degeneracy:

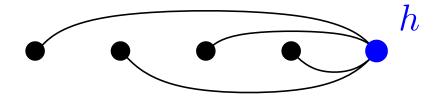
The minimum integer d such that there is an ordering of the vertices where each vertex has at most d neighbors later in the ordering.

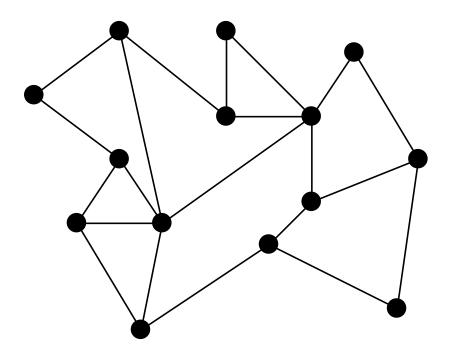




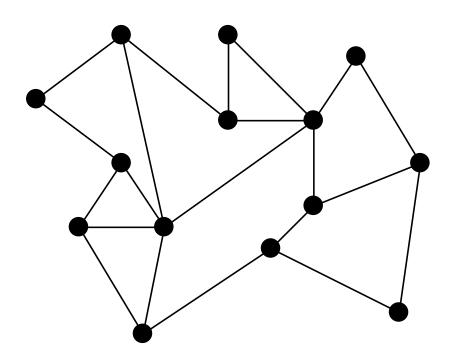




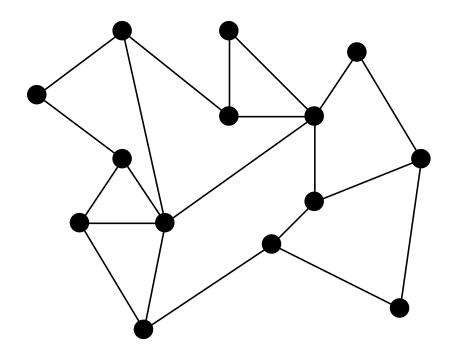


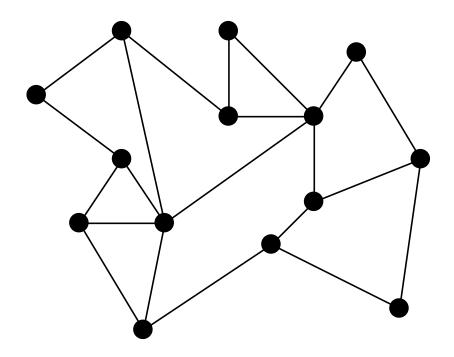


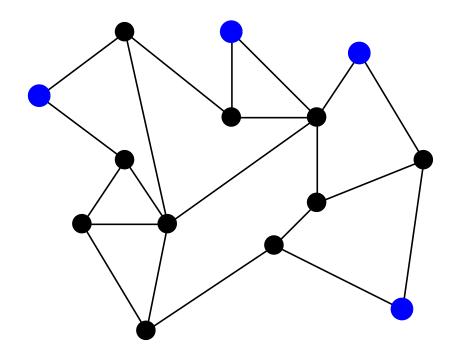
Planar graphs have degeneracy at most 5

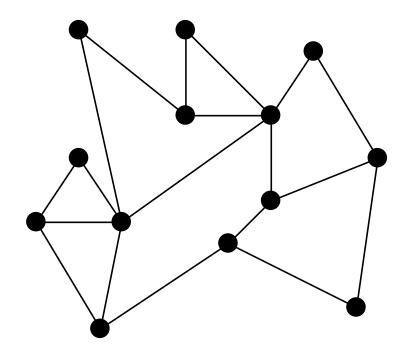


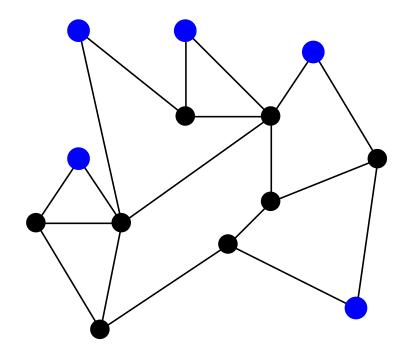
Degeneracy is easy to compute

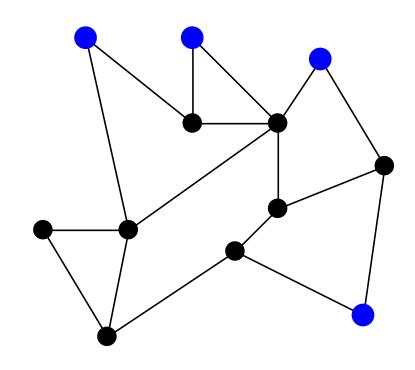




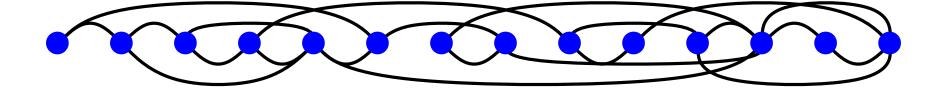








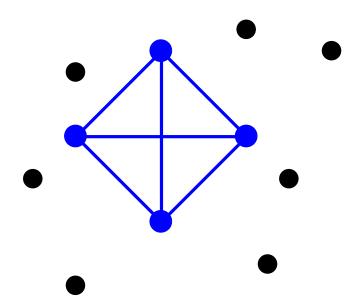




 $\emph{d}\text{-degenerate graphs}...$

cannot contain cliques with more than d+1 vertices

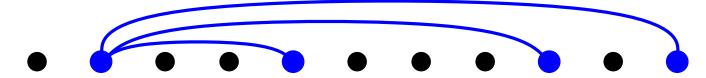
cannot contain cliques with more than d+1 vertices



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> d later neighbors.

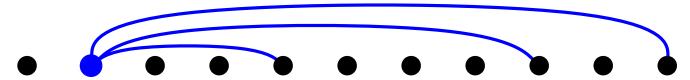


 $\emph{d}\text{-degenerate graphs}...$

have fewer than dn edges.

have fewer than dn edges.

 $\leq d$ later neighbors.



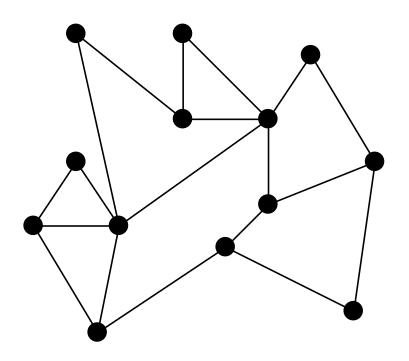
A few more facts about degeneracy...

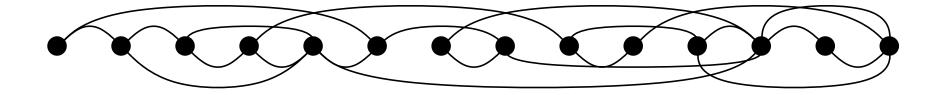
Degeneracy is within a constant factor of other popular sparsity measures.

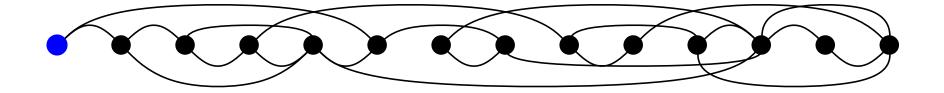
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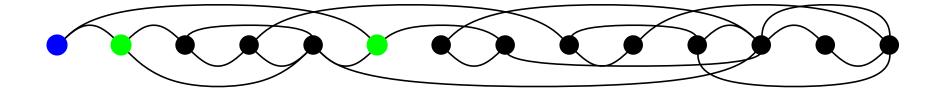
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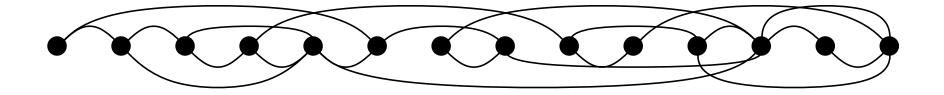
Graphs generated by the preferential attachment mechanism of Barabási and Albert have low degeneracy.

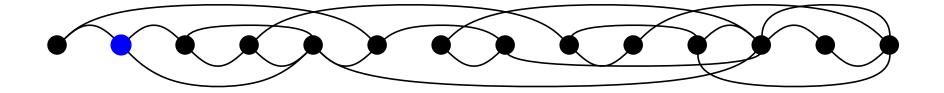


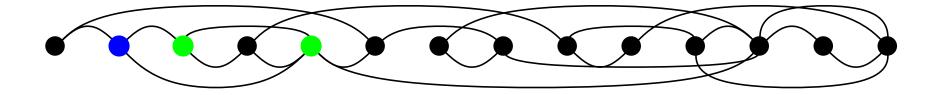


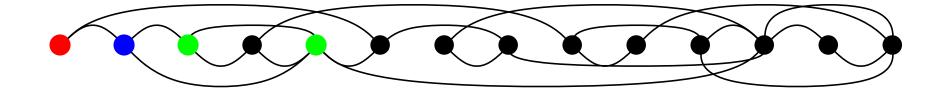






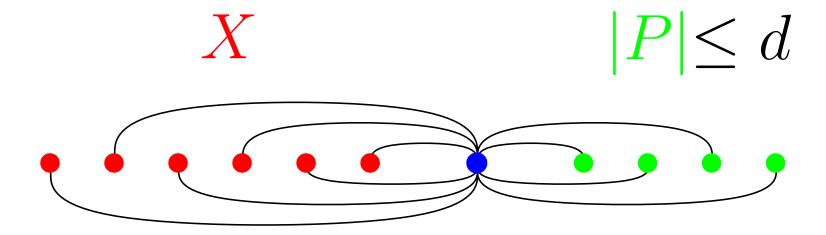






proc BronKerboschDegeneracy(V, E)

- 1: **for** each vertex v_i in a degeneracy ordering v_0 , v_1 , v_2 , ... of (V, E) **do**
- 2: $P \leftarrow \Gamma(v_i) \cap \{v_{i+1}, \dots, v_{n-1}\}$
- 3: $X \leftarrow \Gamma(v_i) \cap \{v_0, \dots, v_{i-1}\}$
- 4: BronKerboschPivot(P, $\{v_i\}$, X)
- 5: end for



Our running time: $O(dn3^{d/3})$

The Bron-Kerbosch Algorithm

```
proc BronKerbosch(P, R, X)

1: if P \cup X = \emptyset then

2: report R as a maximal clique

3: end if

4: for each vertex v \in P (in degeneracy order) do

5: BronKerboschPivot(P \cap \Gamma(v), R \cup \{v\}, X \cap \Gamma(v))

6: P \leftarrow P \setminus \{v\}

7: X \leftarrow X \cup \{v\}

8: end for
```