

A set of vectors $\{\vec{v}_1, \dots, \vec{v}_p\}$ in $\mathbb{R}^n$

is linearly indep if the only solution to

$$x_1 \vec{v}_1 + \dots + x_p \vec{v}_p = \vec{0} \text{ is trivial.}$$

Linearly dep if $\uparrow$ has non-trivial solution.

$\{\vec{v}_1, \dots, \vec{v}_p\} \Rightarrow$ are they linearly indep??

$$A = [\vec{v}_1 \dots \vec{v}_p] \rightsquigarrow \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix} \vec{x} = \vec{0}$$

row ech.

if every col is a pivot col

$\Rightarrow$ linearly indep

$\downarrow$ non-pivot.

$\rightsquigarrow$

$$\begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

linearly dep

$$\{\vec{v}_1\} \quad \vec{v}_1 \neq \vec{0} \quad \text{lin indep.}$$

$$\{\vec{v}_1, \dots, \vec{v}_p, \vec{0}\} \Rightarrow \text{lin dep.}$$

$$0 \cdot \vec{v}_1 + \dots + 0 \cdot \vec{v}_p + 1 \cdot \vec{0} = \vec{0}$$

$$\{\vec{v}_1, \vec{v}_2\}$$

$$\vec{v}_1 \neq \vec{0}$$

$$\vec{v}_2 \neq \vec{0}$$

$$\vec{v}_1 \neq c\vec{v}_2$$

linearly indep.

Theorem: $\{\vec{v}_1, \dots, \vec{v}_p\}$ is linearly dependent
if & only if there is a vector $\vec{v}_i$

that can be expressed as a
linear comb. of the others.

$\Rightarrow$ Assume $\{\vec{v}_1, \dots, \vec{v}_p\}$ lin dep

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_i \vec{v}_i + \dots + c_n \vec{v}_n = \vec{0} \quad c_i \neq 0.$$

divide
by
 $c_i \neq 0$

$$\frac{c_1}{-c_i} \vec{v}_1 + \dots + \frac{c_{i-1}}{-c_i} \vec{v}_{i-1} + \frac{c_{i+1}}{-c_i} \vec{v}_{i+1} + \dots + \frac{c_n}{-c_i} \vec{v}_n = - \cancel{\frac{c_i}{-c_i} \vec{v}_i} = \vec{v}_i$$

$\Leftarrow$ Assume $\vec{v}_i = c_1 \vec{v}_1 + \dots + c_{i-1} \vec{v}_{i-1} + c_{i+1} \vec{v}_{i+1} + \dots + c_n \vec{v}_n$
 Subtract $\vec{v}_i$

$$\vec{0} = c_1 \vec{v}_1 + \dots + c_{i-1} \vec{v}_{i-1} - 1 \cdot \vec{v}_i + c_{i+1} \vec{v}_{i+1} + \dots + c_n \vec{v}_n$$

$\vec{0}$ has two entries.

A $m \times n$ matrix columns $\vec{a}_1 + \dots + \vec{a}_n \in \mathbb{R}^m$

System of lin eq $\Leftrightarrow$ vector equation. $\Leftrightarrow A\vec{x} = \vec{b}$.

$$x_1 \vec{a}_1 + \dots + x_n \vec{a}_n = \vec{b}$$

A as a function. $A\vec{x} = \vec{b}$ $\vec{x} \in \mathbb{R}^n$

A maps vectors $\mathbb{R}^n$ to vectors in $\mathbb{R}^m$ $\vec{b} \in \mathbb{R}^m$

$$\begin{bmatrix} 1 & 3 & 4 & 1 \\ 2 & -1 & 0 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \\ -2 \end{bmatrix} = \begin{bmatrix} 3 \\ -8 \end{bmatrix}$$

$\uparrow$ input $\uparrow$ output.

$$\begin{bmatrix} 1 & 2 \\ -1 & 0 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 4 \\ 2 \end{bmatrix} = \begin{bmatrix} 6 \\ -4 \\ 12 \end{bmatrix}$$

$\uparrow$ input
 $\uparrow$ output.

A transformation (or function or mapping) T from $\mathbb{R}^n$ to $\mathbb{R}^m$ is a rule that assigns a vector from $\mathbb{R}^m$ to every vector in $\mathbb{R}^n$.

$$\vec{x} \in \mathbb{R}^n \quad \underline{\underline{T(\vec{x})}} \in \mathbb{R}^m$$

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$\uparrow$ domain
 $\uparrow$ co-domain target.

The set of all $T(\vec{x})$ is called the range of T .

We're interested in functions defined by matrix mult.

$$A \text{ is } m \times n \text{ matrix} \quad T(\vec{x}) \triangleq A\vec{x}$$

$T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by matrix $[A] = \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ -1 & 3 \end{bmatrix}$

① Given $\vec{u} \in \mathbb{R}^2$ compute $T(\vec{u})$.

$$\vec{u} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad T(\vec{u}) = \begin{bmatrix} 1 & 0 \\ -1 & 1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$$

② Given $\vec{b} \in \mathbb{R}^3$ find an $\vec{x} \in \mathbb{R}^2$ s.t. $T(\vec{x}) = \vec{b}$

$$A\vec{x} = \vec{b} \quad \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 3 \\ 3 & 0 & -3 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

$\begin{matrix} 4 & 4 \\ x_1 & x_2 \end{matrix}$

$$\begin{bmatrix} 1 & 0 \\ -1 & 1 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ -3 \end{bmatrix}$$

$$\begin{aligned} x_2 &= 2 \\ x_1 &= -1 \end{aligned}$$

③ Given $\vec{c}$ is $\vec{c}$ in the range of T ?

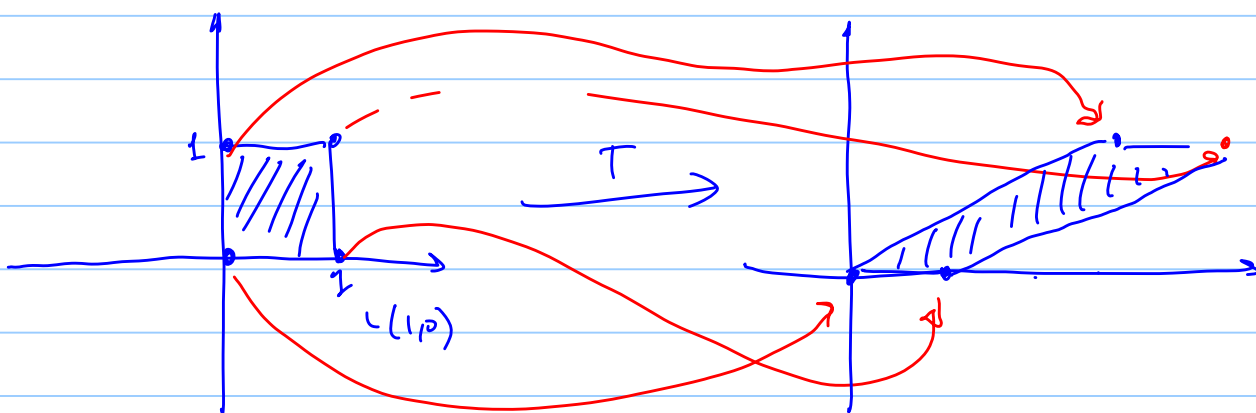
④ Is there more than one $\vec{x}$ that maps on to a particular $\vec{c}$?

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^3 \quad A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$A\vec{x} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ 0 \end{bmatrix}$$

example of
a projection.

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \quad A = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$$



$$A\vec{0} = \vec{0}$$

$$\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$