

In this lecture we'll give more background on the relationship between hardness of approximation and PCP.

The **Constraint Satisfaction Problem** is a generalization of SAT:
 CSP: q is a natural number q -CSP instance is a collection of functions ϕ_1, \dots, ϕ_m (called constraints).
 $\phi_i: \{0, 1\}^q \rightarrow \{0, 1\}$. Each ϕ_i depends on at most q of the input locations.

$$\forall i \in [m], \exists j_1, \dots, j_q \in [n] \quad f: \{0, 1\}^q \rightarrow \{0, 1\}$$

$$\phi_i(u) = f(u_{j_1}, \dots, u_{j_q}) \text{ for every } u \in \{0, 1\}^n$$

u satisfies the i th constraint ϕ_i if $\phi_i(u) = 1$.

The fraction of constraints satisfied is $\frac{\sum_i \phi_i(u)}{m}$

$\text{val}(\phi)$ is the max of this value over all u .

ϕ is satisfiable if $\text{val}(\phi) = 1$.

q is the arity of ϕ .

Gap CSP $\forall q \in \mathbb{N}, p \leq 1$, define p -GAP q -CSP to be the problem of determining for ϕ , instance of q -CSP, whether

- 1) $\text{val}(\phi) = 1$ YES instance
- 2) $\text{val}(\phi) < p$ NO instance

p -GAP q -CSP is NP-hard if for every $L \in \text{NP}$
 \exists poly-time computable function f

Completeness: $x \in L \Rightarrow \text{val}(f(x)) = 1$.

Soundness: $x \notin L \Rightarrow \text{val}(f(x)) < p$.

Theorem 1: $\exists q \in \mathbb{N}, p \in (0, 1)$ s.t. p -GAP $_q$ CSP is NP-hard.

Theorem 2: $NP = PCP(\log n, 1)$.

Theorem 2 \Rightarrow Theorem 1:

Assume $NP \subseteq PCP(\log n, 1)$. Will show $1/2$ -GAP $_q$ CSP is NP-hard for some p .

SAT has PCP system in which the verifier uses $c \cdot \log n$ random bits + queries q locations.

$V_{x,r}$ is the function that on input $\pi \in \{0, 1\}^q$ is $= 1$ iff the verifier accepts.

$\varphi_x = \{ V_{x,r} \}_{r \in \{0, 1\}^{c \log n}}$
is a poly-sized instance of CSP.

Since V runs in poly-time the transformation from x to φ_x is also poly-time.

if $x \in \text{SAT} \Rightarrow \text{val}(\varphi) = 1$
 $x \notin \text{SAT} \Rightarrow \text{val}(\varphi) \leq 1/2$.

Theorem 1 \Rightarrow Theorem 2:

p -GAP $_q$ CSP is NP-hard for some $q, p < 1$.
 \Rightarrow translates to a PCP system w/ q queries, p soundness and \log randomness. for any $L \in NP$.

Run reduction of L to p -GAP $_q$ CSP to get $\varphi = f(x)$.

Suppose $\varphi = \{ \varphi_i \}_{i \in [m]}$.

The verifier will expect the proof to be an assignment to the

Variables.

Verifier selects random $i \in [m]$ and asks to see the variables involved in Q_i . (Then asks).

if $x \in L \Rightarrow$ verifier accepts w.p. 1

if $x \notin L \Rightarrow$ Verifier accepts w.p. $\leq \rho$.

\hookrightarrow Can be boosted to $1/2$
at the expense of a constant
factor in randomness and queries. //

What about hardness of approximation for other problems?

We already showed a $1/2$ -approx scheme for Vertex cover.

Is it possible to do any better?

We will show that for VC there is a δ s.t. approximating VC to within δ is NP-hard. Also for any $\delta < 1$ approximating Indep Set to within δ is NP-hard.

Note that the complement of a VC is an IS. So in terms of exact solutions, they have the same complexity.

Let VC be the size of the smallest vertex cover.

Let IS be the size of the largest independent set.

$$VC = n - IS.$$

A p -approx for Indep Set produces an independent of size at least $p \cdot IS$. What kind of approx factor does this give for VC? $\frac{n - IS}{n - p \cdot IS}$ this could be very small if IS is close to n .

We know that VC has a $1/2$ -approx and IS can have no such approx alg — so approximability of the two problems ~~is~~ is very different.

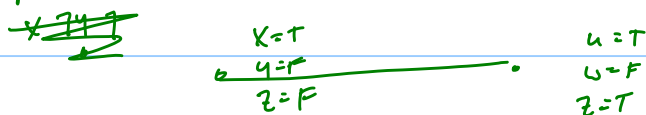
First we will show that each problem has a p st. it can not be p -approximated. Then we will show how to amplify this factor for Ind Set.

Lemma: \exists poly-time reduction from 3CNF \rightarrow graphs
 s.t. $\forall \varphi$, $f(\varphi)$ is an n vertex graph whose largest indep set has size $\frac{1}{7} \text{val}(\varphi)$.
 \hookrightarrow for VC has size $6/7n \text{val}(\varphi)$

This was the normal reduction for Ind Set.

(each clause has a 3 node cluster which is a clique)

Each node represents an assignment that satisfies that clause. Then put edges between partial assignments in different clauses that are in conflict.



Corollary: $\exists p < 1, p' < 1$

s.t. Ind Set can not be p -approximated in poly time

\wedge Vertex-Cover can not be p' -approx in poly time

= unless $P=NP$.

$L \in NP. \exists f, f'$

$x \in L \rightarrow \varphi$ satisfiable $\rightarrow G$ has Ind Set of size $\frac{m}{7}$

$x \notin L \rightarrow \exists pm$ class in φ satisfiable \rightarrow Ind Set has size $< \frac{pm}{7}$

Approximating IS to within ϵ solves $X \in L$.

$$X \in L \rightarrow \rho \text{ set} \rightarrow VC \leq \frac{\epsilon}{\epsilon} m$$

$$X \notin L \rightarrow \leq \frac{\epsilon m}{\epsilon} \text{ class set} \rightarrow VC \geq (1 - \frac{\epsilon}{\epsilon}) m$$

approx to within ϵ ~~is~~ $\frac{\epsilon}{1-\epsilon}$ wh possible unless $P=NP$.

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Boosting for IS:

$$\text{Graph } G \rightarrow G^k$$

↳ vertex = size k subset of vertices in G .

two vertices are not adj iff S_1, S_2 is an Ind Set in G .

$$IS \longleftrightarrow \binom{IS}{k}$$

$$\text{Approx value for } f \text{ in } G = \frac{\binom{\rho IS}{k}}{\binom{1-IS}{k}} \approx \rho^k$$

ρ^k can be made smaller than any const.

Number of vertices is $O(n^k)$ k constant.